Riemannian Geometry IV

Solutions, set 11.

Exercise 26. Let $N = \dim G$ and $n = \dim H$.

(a) We first show that $T_e H \subset \ker D\pi(e)$. Let $v \in T_e H$. Then there exists a curve $c : (-\epsilon, \epsilon) \to H$ such that c(0) = e and c'(0) = v. The image curve $\pi \circ c : (-\epsilon, \epsilon) \to G/H$ is constant because of c(t)H = eH for all $t \in (-\epsilon, \epsilon)$. This implies that

$$D\pi(e)(v) = \frac{d}{dt}|_{t=0}\pi \circ c(t) = 0 \in T_{eH}G/H.$$

 $D\pi(e): T_eG \to T_{eH}G/H$ is surjective, and we have by the dimension formula:

 $\dim \ker D\pi(e) + \dim T_{eH}G/H = \dim T_eG,$

i.e., dimker $D\pi(e) = N - (N - n) = n$. Since dim $T_e H = n$, we conclude that $T_e H = \ker D\pi(e)$.

(b) Note first that dim $V = \dim T_e G - \dim \ker D\Pi(e) = N - n$ and dim $T_{eH}G/H = N - n$, so we are done if we prove that Φ is surjective (then it is also injective, for dimensional reasons). We know that $D\pi(e) : T_e G \to$ $T_{eH}G/H$ is surjective. For a given $v \in T_{eH}G/H$ let $v_1 \in T_eG$ such that $D\pi(e)(v_1) = v$. Let $v_1 = u_1 + w_1 \in T_eH \perp V$. Since $T_eH = \ker D\pi(e)$, we have $D\pi(v_1) = D\pi(w_1) = \Phi(w_1)$. This shows surjectivity of Φ .

(c) We first show that T_eH is Ad(H) invariant. Let $v \in T_eH = \ker D\pi(e)$. Then there is a curve $c : (-\epsilon, \epsilon) \to H$ such that c(0) = e and c'(0) = v, and we have

$$D\pi(e)(Ad(h)v) = \frac{d}{dt}|_{t=0}\pi(\underbrace{hc(t)h^{-1}}_{\in H})) = 0 \in T_{eH}G/H,$$

i.e., $Ad(h)v \in \ker D\pi(e) = T_eH$. Recall that $\langle \cdot, \cdot rangle_e \text{ is } Ad(H) \text{-invariant.}$ Let $v \in V$. We need to show that $Ad(h)v \perp T_eH$. Let $h \in H$ and $w \in T_eH$. Then

$$\langle Ad(h)v,w\rangle_e = \langle Ad(h^{-1})Ad(h)v, Ad(h^{-1})w\rangle_e = \langle \underbrace{v}_{\in V}, \underbrace{Ad(h^{-1})w}_{\in T_eH}\rangle_e = 0.$$

Here we used $Ad(h_1)Ad(h_2) = Ad(h_1h_2)$, which we finally show:

$$Ad(h_1)Ad(h_2)v = Ad(h_1)\frac{d}{dt}|_{t=0}h_2Exp(tv)h_2^{-1}$$

= $\frac{d}{dt}|_{t=0}h_1\left(h_2Exp(tv)h_2^{-1}\right)h_1^{-1}$
= $\frac{d}{dt}|_{t=0}(h_1h_2)Exp(tv)(h_1h_2)^{-1} = Ad(h_1h_2)v.$

Exercise 27. (a) The curve

$$c(t) = Exp(t\begin{pmatrix} 0 & \alpha \\ -\alpha & 0 \end{pmatrix}) = \begin{pmatrix} \cos \alpha t & \sin \alpha t \\ -\sin \alpha t & \cos \alpha t \end{pmatrix} \in H$$

satisfies c(0) = e and $c'(0) = \begin{pmatrix} 0 & \alpha \\ -\alpha & 0 \end{pmatrix}$. Thus we have $\{ \begin{pmatrix} 0 & \alpha \\ -\alpha & 0 \end{pmatrix} \mid \alpha \in \mathbb{R} \} \subset T_e H.$

Equality follows from the fact that both vector spaces are one-dimensional.

(b) For the symmetry, observe that $tr(U) = tr(U^{\top})$. Thus

$$\langle A, B \rangle_e = 2 \operatorname{tr}(AB^{\top}) = 2 \operatorname{tr}(BA^{\top}) = \langle B, A \rangle_e.$$

Let $X \in H$. Then (see Example 30):

$$Ad(X)A = XAX^{-1}, \quad Ad(X)B = XBX^{-1}.$$

Using $X^{-1} = X^{\top}$ (since $X \in SO(2)$), this implies

$$\langle Ad(X)A, Ad(X)B\rangle_e = 2\mathrm{tr}\left((XAX^{-1})(XBX^{-1})^{\top}\right) = 2\mathrm{tr}\left(XAB^{\top}X^{-1}\right) = 2\mathrm{tr}\left(X^{-1}XAB^{\top}\right) = 2\mathrm{tr}(AB^{\top}) = \langle A, B\rangle_e,$$

where we used tr(UV) = tr(VU) in the second to last line above. (c) We have

$$\begin{pmatrix} \alpha & \beta \\ \beta & -\alpha \end{pmatrix}, \begin{pmatrix} 0 & \gamma \\ -\gamma & 0 \end{pmatrix} = 2 \operatorname{tr} \left(\begin{pmatrix} \alpha & \beta \\ \beta & -\alpha \end{pmatrix} \begin{pmatrix} 0 & -\gamma \\ \gamma & 0 \end{pmatrix} \right)$$
$$= 2 \operatorname{tr} \begin{pmatrix} \beta \gamma & -\alpha \alpha \\ -\alpha \gamma & -\beta \gamma \end{pmatrix} = 0.$$

(d) We have

$$\langle A, A \rangle_2 = 2 \operatorname{tr} \left(\begin{pmatrix} \frac{1}{2} & 0\\ 0 & -\frac{1}{2} \end{pmatrix} \begin{pmatrix} \frac{1}{2} & 0\\ 0 & -\frac{1}{2} \end{pmatrix} \right) = 2 \operatorname{tr} \begin{pmatrix} \frac{1}{4} & 0\\ 0 & \frac{1}{4} \end{pmatrix} = 1,$$

$$\langle A, B \rangle_2 = 2 \operatorname{tr} \left(\begin{pmatrix} \frac{1}{2} & 0\\ 0 & -\frac{1}{2} \end{pmatrix} \begin{pmatrix} 0 & \frac{1}{2}\\ \frac{1}{2} & 0 \end{pmatrix} \right) = 2 \operatorname{tr} \begin{pmatrix} 0 & \frac{1}{4}\\ -\frac{1}{4} & 0 \end{pmatrix} = 0,$$

$$\langle B, B \rangle_2 = 2 \operatorname{tr} \left(\begin{pmatrix} 0 & \frac{1}{2}\\ \frac{1}{2} & 0 \end{pmatrix} \begin{pmatrix} 0 & \frac{1}{2}\\ \frac{1}{2} & 0 \end{pmatrix} \right) = 2 \operatorname{tr} \begin{pmatrix} \frac{1}{4} & 0\\ 0 & \frac{1}{4} \end{pmatrix} = 1.$$

(e) Let

$$c_1(t) = Exp(tA) = Exp\left(\begin{array}{cc} \frac{t}{2} & 0\\ 0 & -\frac{t}{2} \end{array}\right) = \begin{pmatrix} e^{t/2} & 0\\ 0e^{-t/2} \end{pmatrix} \in SL(2,\mathbb{R}),$$

$$c_2(t) = Exp(tB) = Exp\left(\begin{array}{cc} 0 & \frac{t}{2}\\ \frac{t}{2} & 0 \end{array}\right) = \begin{pmatrix} \cosh(t/2) & \sinh(t/2)\\ \sinh(t/2) & \cosh(t/2) \end{pmatrix} \in SL(2,\mathbb{R}).$$

Then $c_1(0) = c_2(0) = e$ and $c'_1(0) = A$ and $c'_2(0) = B$. We calculate the tangent vectors of the image curves

$$\gamma_1(t) = f_{c_1(t)}(i) = \frac{e^{t/2}i + 0}{e^{-t/2}} = e^t i \in \mathbb{H}^2,$$

$$\gamma_2(t) = f_{c_2(t)}(i) = \frac{\cosh(t/2)i + \sinh(t/2)}{\sinh(t/2)i + \cosh(t/2)} \in \mathbb{H}^2,$$

at t = 0. Then $\gamma_1(0) = \gamma_2(0) = i$ and

$$\gamma_1'(t) = e^t i \in T_{\gamma_1(t)} \mathbb{H}^2,$$

i.e., $\gamma_1'(0) = i \in T_i \mathbb{H}^2$, and

$$\gamma_{2}'(t) = \frac{1}{2(\sinh(t/2)i + \cosh(t/2))^{2}} \cdot \\ \left((\sinh(t/2)i + \cosh(t/2))^{2} - (\cosh(t/2)i + \sinh(t/2))^{2} \right) \\ = \frac{1}{(\sinh(t/2)i + \cosh(t/2))^{2}} \in T_{\gamma_{2}(t)} \mathbb{H}^{2},$$

i.e., $\gamma'_2(0) = 1 \in T_i \mathbb{H}^2$. Note that $1, i \in T_i \mathbb{H}^2$ form an orthonormal base with respect to the hyperbolic Riemannian metric on \mathbb{H}^2 .