

SLE and α -S

driven by Lévy - pro.

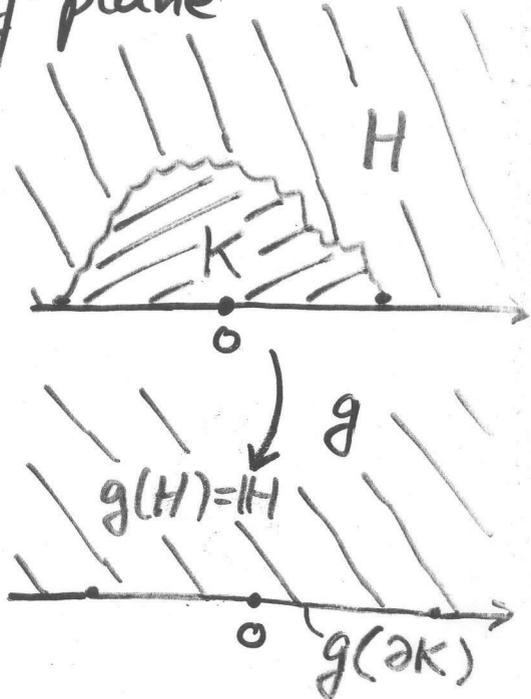
joint work

... .. EDCDC ...

I. Growing clusters in \mathbb{H}

$\bar{\mathbb{H}} := \{z \in \mathbb{C} : \text{Im}(z) \geq 0\}$ complex upper half-plane

We call cluster any compact $K \subseteq \bar{\mathbb{H}}$ such that $H := \mathbb{H} \setminus K$ is simply connected.



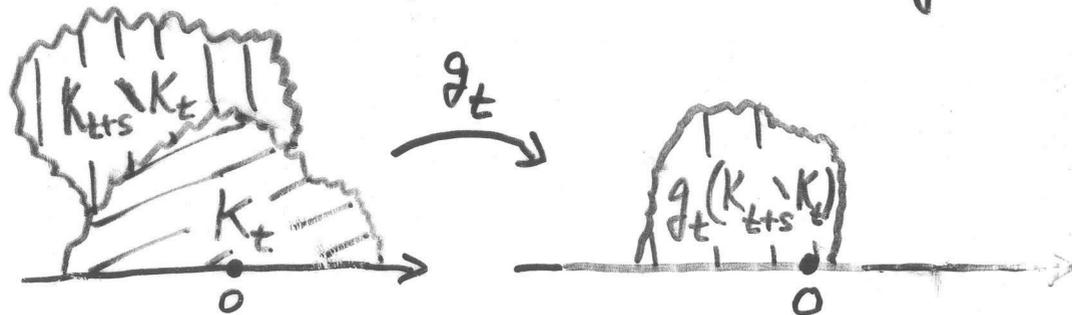
Riemann Mapping Theorem $\Rightarrow \exists!$ $g: \mathbb{H} \rightarrow \mathbb{H}$
conformal

such that $g(z) = z + \frac{b}{z} + O\left(\frac{1}{|z|^2}\right)$ as $z \rightarrow \infty$,

for some $b \geq 0$ called half-plane capacity $\text{hcap}(K)$, a "measure" of the size of K

Consider an increasing cluster

$(K_t)_{t \geq 0}$ such that $\text{hcap}(K_t) = 2t$



2. Local growth and Loewner Evolutions

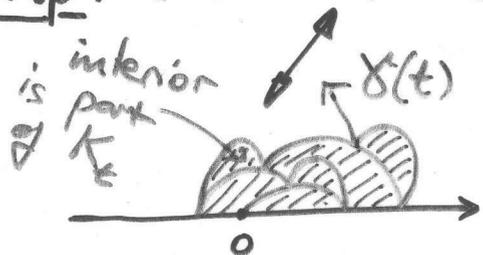
Special cases of increasing clusters: restrict growth to one point. How?

(1) Local growth: $\bigcap_{\varepsilon > 0} \overline{\{g_t(z) : z \in K_{t+\varepsilon} \setminus K_t\}} = \{\text{single point}\} =: \{U(t)\}$

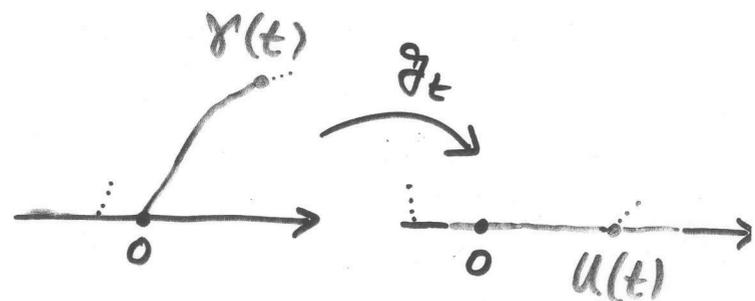
(2) K_t generated by cadlag curve: $\bigcap_{\varepsilon > 0} \overline{K_{t+\varepsilon} \setminus K_t} = \{\text{single point}\} =: \{Y(t)\}$

(3) K_t is a cadlag curve: $K_t = \{Y(s), 0 \leq s \leq t\}$, in particular $\bigcap_{\varepsilon > 0} (\mathbb{H} \cap K_t \setminus K_{t-\varepsilon}) = \{Y(t-)\}$

Prop: (3) \Rightarrow (2) \Rightarrow (1), but (1) $\not\Rightarrow$ (2) $\not\Rightarrow$ (3)



"driving process"



Prop: If (1) holds for cadlag $(U(t))_{t \geq 0}$, then $g_t : \mathbb{H} \setminus K_t \rightarrow \mathbb{H}$ satisfies

Loewner's equation $\partial_t g_t(z) = \frac{2}{g_t(z) - U(t)}$, $g_0(z) = z$, well-defined on $[0, \zeta(z))$, $z \in \overline{\mathbb{H}}$

right derivative

Conversely: $K_t = \{z \in \overline{\mathbb{H}} : \zeta(z) \leq t\}$

3. Independent growth increments

$$U(0) = 0$$

Let $(g_t)_{t \geq 0}$ be a Loewner evolution driven by a cadlag function $(U(t))_{t \geq 0}$

Recall $g_t(z) = z + \frac{2t}{z} + O\left(\frac{1}{|z|^2}\right)$ as $z \rightarrow \infty$

and $g_t(x(t)) = U(t)$
under condition (2)

We could also choose different conformal mappings

$$h_t(z) = z - U(t) + \frac{2t}{z} + O\left(\frac{1}{|z|^2}\right) = g_t(z) - U(t)$$

and $h_t(x(t)) = 0$
under condition (2)

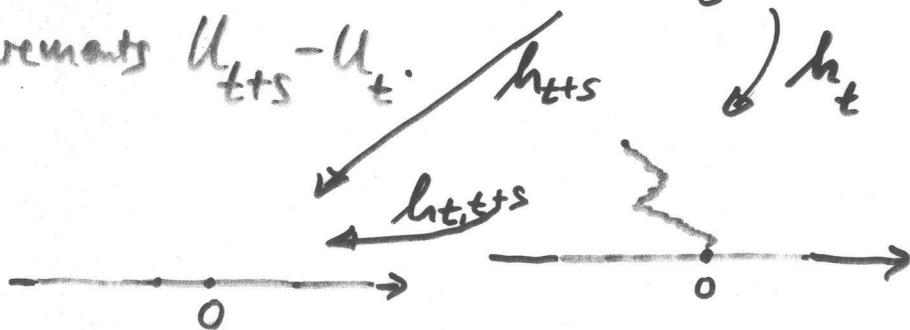
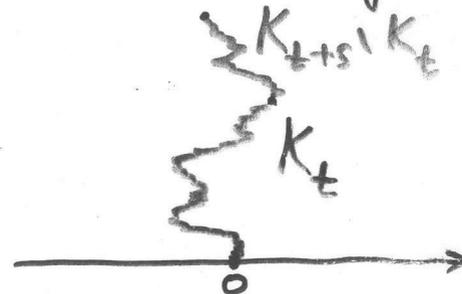
Then Loewner's equation implies: $dh_t(z) = \frac{2}{h_t(z)} dt - dU(t)$ "Bessel flow"

Prop: $(h_t)_{t \geq 0}$ has stationary independent "increments"

$$h_{t,t+s} := h_{t+s} \circ h_t^{-1} \text{ if and only if } (U(t))_{t \geq 0}$$

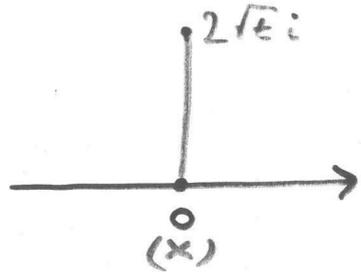
has stationary independent increments $U_{t+s} - U_t$.

Remark: $a^{\frac{1}{2}} K_{t/a} \stackrel{d}{=} K_t$ if and only if $\alpha = 2$ and $(U(t))_{t \geq 0}$ is a multiple $(\sqrt{\kappa} B_t)_{t \geq 0}$ of Brownian motion



4. Jumps of $(U(t))_{t \geq 0}$ and tree structure of K_t

Examples: 1) $U(t) \equiv 0$, $g_t(z) = \sqrt{z^2 + 4t}$, $K_t = [0, 2\sqrt{t}i]$

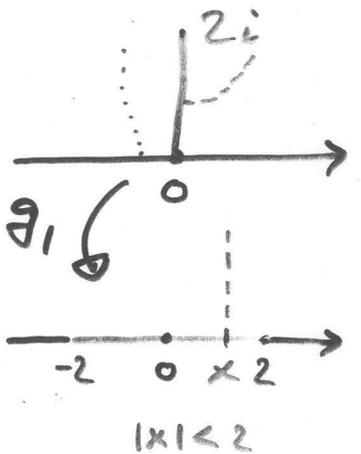
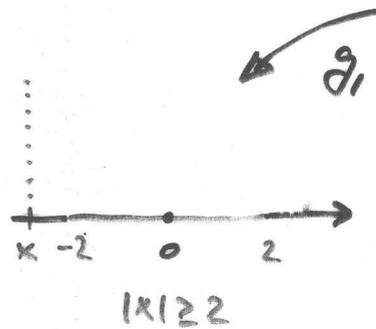


2) $U(t) \equiv x$, $K_t = [x, x + 2\sqrt{t}i]$, translation of 1) by x .

3) $U(t) = \begin{cases} 0 & 0 \leq t < 1 \\ x & t \geq 1 \end{cases}$, $g_1(z) = \sqrt{z^2 + 4}$, $U(1) = x$

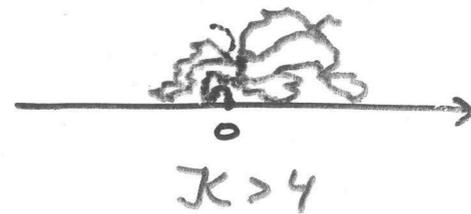
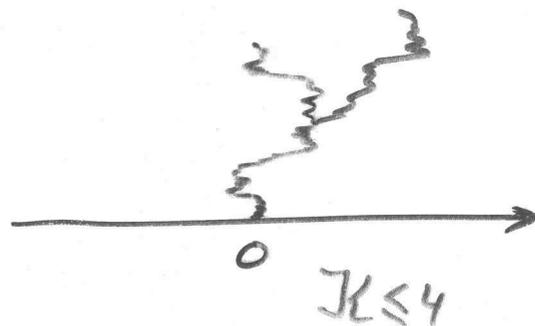
Recall $\partial_t g_t(z) = \frac{2}{g_t(z) - \underbrace{U(t)}_0}$, $0 \leq t < 1$

and $\partial_t g_{1,t}(z) = \frac{2}{g_{1,t}(z) - \underbrace{(U(1+t) - U(1))}_{=x}}$, $t \geq 0$



4) $U(t) = \begin{cases} \sqrt{K} B_t & 0 \leq t < 1 \\ x + \sqrt{K} B_t & t \geq 1 \end{cases}$

where $(B_t)_{t \geq 0}$ Brownian motion and x "small"



5. Phase transitions $K=4$, $\alpha=1$

Consider a Lévy process

$$U(t) = \sqrt{K} B_t + \theta^{1/\alpha} S_t$$

$$S(z) = \inf\{t \geq 0 : z \in K_t\}$$

Brownian motion \perp symmetric α -stable
 $\text{Var}(B_t) = t$ $\mathbb{E} e^{i\lambda S_t} = e^{-t|\lambda|^\alpha}$

Theorem: (i) $0 \leq K \leq 4$ and $U \neq 0 \Rightarrow \mathbb{P}(S(z) = \infty) = 1$ for all $z \in \bar{H} \setminus \{0\}$;
 (ii) $K > 4$ and $1 \leq \alpha < 2 \Rightarrow \mathbb{P}(S(z) < \infty) = 1$ for all $z \in \bar{H} \setminus \{0\}$;
 (iii) $K > 4$ and $0 < \alpha < 1 \Rightarrow 0 < \mathbb{P}(S(z) < \infty) < 1$ for all $z \in \bar{H} \setminus \{0\}$.

Rushkin et al predicted a weaker statement and described their simulations as

(i) trees (ii)-(iii) bushes, (ii) isolated (iii) forests of bushes
 $K=4$ phase transition for $\theta=0$ known (Schramm) $\alpha=1$ phase transition

Corollary: (i) $\text{Leb}(\bigcup_{t \geq 0} K_t) = 0$ (ii) $\text{Leb}(\bar{H} \setminus \bigcup_{t \geq 0} K_t) = 0$ (iii) $\text{Leb}(K_t) > 0$

Conjecture: (i) K_t is a tree: $\forall x, y \in K_t \exists!$ $\{e(s), 0 \leq s \leq 1\}$ ^{simple} path $e(0)=x, e(1)=y$ in $K_t \cup \mathbb{R}$
 (ii)-(iii) K_t is generated by a left-continuous function.

6. α -SLE driven by α -stable processes

Recall $a^{\frac{1}{\alpha}} K_{t/a} \stackrel{d}{=} K_t$ even for α -stable $(U(t))_{t \geq 0}$; SLE
 Brownian scaling is intrinsic to Loewner's equation $\partial_t g_t(z) = \frac{z}{g_t(z) - U(t)}$

Consider instead α -stable

$$\partial_t g_t(z) = \frac{2 |g_t(z) - \theta^{\frac{1}{\alpha}} S_t|^{2-\alpha}}{g_t(z) - \theta^{\frac{1}{\alpha}} S_t}, \quad g_0(z) = z, \quad t \in [0, f(z))$$

$$K_t = \{z \in \bar{\mathbb{H}} : f(z) \leq t\}$$

Theorem: $\exists \theta_0(\alpha) > 0$ s.t.

- (i) $0 \leq \theta < \theta_0(\alpha) \Rightarrow \mathbb{P}(f(z) = \infty) = 1$ for all $z \in \bar{\mathbb{H}} \setminus \{0\}$; $m(\bigcup_{t \geq 0} K_t) = 0$;
 (ii) $\theta > \theta_0(\alpha) \Rightarrow \mathbb{P}(f(z) < \infty) = 1$ for all $z \in \bar{\mathbb{H}} \setminus \{0\}$; $m(\mathbb{H} \setminus \bigcup_{t \geq 0} K_t) = 0$

Remarks: 1) $a^{\frac{1}{\alpha}} K_{t/a} \stackrel{d}{=} K_t$ is scale-invariant

2) g_t is NOT conformal