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Characterising the shape of and material properties of hidden conducting targets in metal detection

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Applications of finding hidden objects

In many practical applications the goal is locate and identify hidden conducting objects from field measurements:



Security Screening



Archeological Searches



UXO and mine clearance



Medical Imaging



Non-destructive testing



Food Safety

This requires solving an **inverse problem**, which is generally more challenging compared to the corresponding **direct problem**. The applications and techniques involve different regimes of electromagnetism.

Why are inverse problems challenging?

- Typically ill-posed (lacks one or more conditions for well-posedness) e.g.
 - possible lack of existence;
 - possible lack of uniqueness;
 - possible lack of stability.
- In practice only limited noisy measurement data is available

Practical engineering solutions to Inverse problems are often posed as minimisation problems e.g.

$$\min_{\mathbf{p}} \|\mathbf{d} - \mathbf{F}(\mathbf{p})\|^2 + \|\mathbf{R}(\mathbf{p})\|^2$$

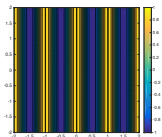
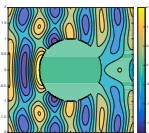
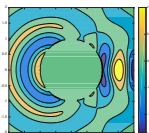
In the above

- \mathbf{d} represents some *measured* data;
- $\mathbf{F}(\mathbf{p})$ represents the *direct* or *forward* problem, parameterised by model parameters \mathbf{p} ;
- $\mathbf{R}(\mathbf{p})$ is some regularisation which may be added to help overcome the ill-posedness.

But there are computational challenges of dimensionality, local minima and choosing \mathbf{R} .

Basic idea of object characterisation using polarizability tensors

When an object is introduced in to a background field u_0 it will perturb it resulting in u_α , e.g. in plane wave scattering of an object

 u_0  u_α  $u_\alpha - u_0$

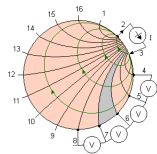
We are interested in finding expressions of the form

$$(u_\alpha - u_0)(\mathbf{x}) = f(\mathcal{T}, u_0(\mathbf{z}), G(\mathbf{x}, \mathbf{z})) + R$$

to use as the **direct problem**.

- \mathbf{z} is the position of the centre of the object.
- \mathcal{T} is a position independent polarizability tensor describing the shape and material of the object
- R is some small quantifiable remainder.
- $G(\mathbf{x}, \mathbf{z})$ is an appropriate (free space) Green's function.
- Also has connections with the construction of cloaking of objects.

Electrical impedance tomography



Given measurements of boundary voltages $u|_{\partial\Omega}$ and external currents $I(\mathbf{x}) := \hat{\mathbf{n}} \cdot \sigma_{\alpha} \nabla u|_{\partial\Omega}$ we want to **find the conductivity distribution** $\sigma_{\alpha}(\mathbf{x})$.

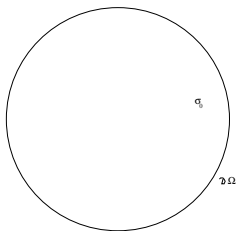
The Maxwell system simplifies since $\omega\mu|\sigma_{\alpha}|\alpha \ll 1$. Introducing $\mathbf{E} = \nabla u_{\alpha}$ where u_{α} solves

$$\begin{aligned} \nabla \cdot \sigma_{\alpha} \nabla u_{\alpha} &= 0 && \text{in } \Omega \subset \mathbb{R}^3 \\ \hat{\mathbf{n}} \cdot \sigma_{\alpha} \nabla u_{\alpha} &= I && \text{on } \partial\Omega \\ \int_{\partial\Omega} I d\mathbf{x} &= 0 \end{aligned}$$

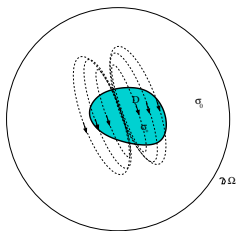
The case of $\alpha = 0$, ie u_0 , corresponds to the case of a known constant background σ_0 .

Electrical impedance tomography

The effect of introducing a small object D with conductivity σ_* in a background field u_0 is like introducing a dipole at its centre z



Background problem



Perturbed problem

For a small single inclusion $D := \alpha B + z$ with contrast $c := \frac{\sigma_*}{\sigma_0}$ Ammari and Kang (2007) show that for a related unbounded problem

$$(u_\alpha - u_0)(x) = \nabla_x (G(x, z)) \cdot (\mathcal{T}(c) \nabla_z u_0(z)) + O(\alpha^4)$$

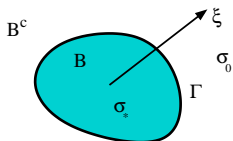
as $\alpha \rightarrow 0$ where $G(x, z) := 1/(4\pi|x - z|)$. Results are also available for the bounded EIT case (Cedio-Fengya, Moskow, Vogelius (1998), Ammari and Kang (2007))

Computing the Pólya–Szegő tensor

The coefficients of the tensor are

$$\mathcal{T}(c)_{ij} = \alpha^3 \left((c-1)|B|\delta_{ij} + (c-1)^2 \int_{\Gamma} \hat{\mathbf{n}} \cdot \nabla \phi_i |^{-\xi_j} d\xi \right),$$

where ϕ_i , $i = 1, 2, 3$, satisfies the transmission problem



$$\begin{aligned} [\phi_i]_{\Gamma} &= 0, & \nabla^2 \phi_i &= 0 & \text{in } B \cup B^c, \\ [\hat{\mathbf{n}} \cdot \sigma \nabla \phi_i]_{\Gamma} &= \sigma_0 \hat{\mathbf{n}} \cdot \nabla \xi_i & \phi_i &\rightarrow 0 & \text{on } \Gamma, \\ & & & & \text{as } |\xi| \rightarrow \infty. \end{aligned}$$

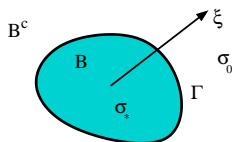
- \mathcal{T} is a real symmetric tensor **defined by 6 coefficients**;
- \mathcal{T} can be diagonalised and an equivalent best fitting ellipsoid found that has the same \mathcal{T} as the object D ;
- \mathcal{T} contains both **shape and material contrast information**;
- Determining the coefficients of \mathcal{T} and the location z from $u|_{\partial\Omega}$ and I offers possibilities for **low-cost identification of inclusions**;

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Electromagnetic scattering

For known analytic incident fields $E^{in} = E_0$, $H^{in} = H_0$ and measured scattered fields $E^{sc} := E_\alpha - E^{in}$, $H^{sc} := H_\alpha - H^{in}$ we want to infer information about the shape of the shape of scatterer D and the contrasts ϵ_*/ϵ_0 and μ/μ_0 .

For wave number $\kappa := \omega\sqrt{\epsilon_0\mu_0}$ the fields satisfy the (scaled) Maxwell system

$$\begin{aligned} \nabla \times E_\alpha &= i\kappa\mu_\alpha^r H_\alpha, & \nabla \times H_\alpha &= -i\epsilon_\alpha^r \kappa E_\alpha & \text{in } \mathbb{R}^3, \\ \nabla \cdot \epsilon_\alpha^r E_\alpha &= 0 & \nabla \cdot \mu_\alpha^r H_\alpha &= 0 & \text{in } \mathbb{R}^3, \end{aligned}$$

For smooth, simply connected objects $D := \alpha B + z$ (PDL, WRBL 2015a)

$$\begin{aligned} (E_\alpha - E^{in})(x)_i &= \alpha^3 \kappa^2 \mathcal{G}^\kappa(x, z)_{ij} \left(\mathcal{T} \left(\frac{\epsilon_*}{\epsilon_0} \right) \right)_{jk} E^{in}(z)_k + \\ &+ \alpha^3 i\kappa (\nabla_x \times \mathcal{G}^\kappa(x, z))_{ij} \left(\mathcal{T} \left(\frac{\mu_*}{\mu_0} \right) \right)_{jk} H^{in}(z)_k + O(\Gamma^4), \end{aligned}$$

as $\Gamma := \max(\kappa\alpha, \alpha/r) \rightarrow 0$, with $r := |x - z|$

$$\mathcal{G}^\kappa(x, z)_{ij} := G^\kappa((x, z)\delta_{ij} + \frac{1}{\kappa^2}(D_x^2 G^\kappa(x, z))_{ij} \quad G^\kappa = \frac{e^{i\kappa|x-z|}}{4\pi|x-z|}$$

with a similar result for $H_\alpha - H^{in}$.

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For large r and fixed α this agrees with the far field term obtained by Kleinman (*et al.* (1982))

$$\frac{\alpha^3 \kappa}{r} \left(\hat{\mathbf{r}} \times \hat{\mathbf{r}} \times \left(\mathcal{T} \left(\frac{\epsilon_*}{\epsilon_0} \right) \mathbf{E}^{in}(\mathbf{z}) \right) + \hat{\mathbf{r}} \times \left(\mathcal{T} \left(\frac{\mu_*}{\mu_0} \right) \mathbf{H}^{in}(\mathbf{z}) \right) \right) + O(\kappa^2)$$

as $\kappa \rightarrow 0$. On the other hand, fixing κ , r then is of the same form of Ammari, Volkov (2005) for small objects.

$$\begin{aligned} (\mathbf{E}_\alpha - \mathbf{E}^{in})(\mathbf{x})_i &= \alpha^3 \kappa^2 \mathcal{G}^\kappa(\mathbf{x}, \mathbf{z})_{ij} \left(\mathcal{T} \left(\frac{\epsilon_*}{\epsilon_0} \right) \right)_{jk} \mathbf{E}^{in}(\mathbf{z})_k + \\ &+ \alpha^3 i \kappa (\nabla_x \times \mathcal{G}^\kappa(\mathbf{x}, \mathbf{z}))_{ij} \left(\mathcal{T} \left(\frac{\mu_*}{\mu_0} \right) \right)_{jk} \mathbf{H}^{in}(\mathbf{z})_k + O(\alpha^4), \end{aligned}$$

as $\alpha \rightarrow 0$



GPR one possible application but not metal detection.

We have an analogous result for objects with $(\epsilon_* + i\sigma_*/\omega)/\epsilon_0$ but this is for fixed κ and thus does not apply to low frequencies.

Describing the response from metal detectors



Eddy current approximation.

$\sqrt{\epsilon_* \mu_*} \alpha \omega \ll 1, \epsilon_* \omega / \sigma_* \ll 1$ (rigorous justification involves the topology of the object).

Current source \mathbf{J}_0 at \mathbf{w} idealised as a dipole with moment \mathbf{m} generates $\mathbf{H}_0(\mathbf{x}) = D_x^2 G(\mathbf{x}, \mathbf{w}) \mathbf{m}$.

From measurements of $(\mathbf{H}_\alpha - \mathbf{H}_0)(\mathbf{x})$ we want to find information about an object's shape and $\mu_*/\mu_0, \sigma_*$.

The interaction fields satisfy

$$\begin{aligned} \nabla \times \mathbf{E}_\alpha &= i\omega \mu_\alpha \mathbf{H}_\alpha, & \nabla \times \mathbf{H}_\alpha &= \sigma_\alpha \mathbf{E}_\alpha + \mathbf{J}_0 & \text{in } \mathbb{R}^3, \\ \nabla \cdot \mathbf{E}_\alpha &= 0 & \nabla \cdot \mu_\alpha \mathbf{H}_\alpha &= 0 & \text{in } \mathbb{R}^3. \end{aligned}$$

Polarizability tensors for the eddy current problem

For the case where $\nu = 2\alpha^2/s^2 = O(1)$, ($s = \sqrt{2/(\omega\mu_*\sigma_*)}$) and $\mu_r = \mu_*/\mu_0$ Ammari, Chen, Chen, Garnier and Volkov (2013) have shown that

$$(\mathbf{H}_\alpha - \mathbf{H}_0)(\mathbf{x})_j = \mathbf{D}^2 G(\mathbf{x}, \mathbf{z})_{\ell m} \mathcal{M}_{\ell m j i} \mathbf{H}_0(\mathbf{z})_i + O(\alpha^4)$$

as $\alpha \rightarrow 0$ for fixed \mathbf{x} away from \mathbf{z}

In the above \mathcal{M} is a **new rank 4 tensor**, which depends on the shape of the object, μ_r and σ_* .

Note the response is not characterised by a suitably parameterised \mathcal{T} .

But, electrical engineers predict that the response from a conducting object form a single measure-excitor coil pair as

$$\text{Voltage signal} \approx m_j^{ms} (\mathbf{H}_\alpha - \mathbf{H}_0)(\mathbf{x})_j \approx \mathbf{H}_0^{ms}(\mathbf{z})_j \widetilde{\widetilde{\mathcal{M}}}_{ji} \mathbf{H}_0(\mathbf{z})_i \quad (= \mathbf{D}^2 G(\mathbf{x}, \mathbf{z})_{jk} m_k^{ms} \widetilde{\widetilde{\mathcal{M}}}_{ji} \mathbf{H}_0(\mathbf{z})_i)$$

They fit coefficients to rank 2 tensor $\widetilde{\widetilde{\mathcal{M}}}$ but they don't have an explicit formula .

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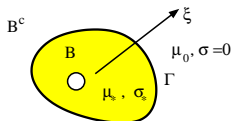
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They fit coefficients to rank 2 tensor $\widetilde{\widetilde{\mathcal{M}}}$ but they don't have an explicit formula .

Computing \mathcal{M} 

$$\mathcal{M}_{\ell mji} := \mathcal{P}_{\ell mji} + \delta_{\ell j} \delta_{mk} \mathcal{N}_{ki}$$

$$\mathcal{P}_{\ell mji} := \beta \hat{e}_j \cdot \left(\hat{e}_\ell \times \int_B \xi_m (\boldsymbol{\theta}_i + \hat{e}_i \times \boldsymbol{\xi}) d\xi \right),$$

$$\mathcal{N}_{ki} := \alpha^3 \left(1 - \frac{\mu_0}{\mu_*} \right) \int_B \left(\hat{e}_k \cdot \hat{e}_i + \frac{1}{2} \hat{e}_k \cdot \nabla \times \boldsymbol{\theta}_i \right) d\xi.$$

$\beta = -\frac{i\nu\alpha^3}{2}$ and $\boldsymbol{\theta}_i, i = 1, 2, 3$, is the solution to

$$\nabla \times \mu^{-1} \nabla \times \boldsymbol{\theta}_i - i\omega\sigma\alpha^2 \boldsymbol{\theta}_i = i\omega\sigma\alpha^2 \hat{e}_i \times \boldsymbol{\xi} \quad \text{in } B \cup B^c,$$

$$\nabla \cdot \boldsymbol{\theta}_i = 0 \quad \text{in } B^c,$$

$$[\boldsymbol{\theta}_i \times \hat{\mathbf{n}}]_\Gamma = \mathbf{0}, \quad \left[\mu^{-1} \nabla \times \boldsymbol{\theta}_i \times \hat{\mathbf{n}} \right]_\Gamma = -2 \left[\mu^{-1} \right]_\Gamma \hat{e}_i \times \hat{\mathbf{n}} \quad \text{on } \Gamma,$$

$$\boldsymbol{\theta}_i(\boldsymbol{\xi}) = O(|\boldsymbol{\xi}|^{-1}) \quad \text{as } |\boldsymbol{\xi}| \rightarrow \infty,$$

Reduction to a Rank 2 Tensor

For orthonormal coordinates we have shown (PDL & WRBL 2015) that

$$(\mathbf{H}_\alpha - \mathbf{H}_0)(\mathbf{x})_j = \mathbf{D}_\mathbf{x}^2 G(\mathbf{x}, \mathbf{z})_{jm} \widetilde{\widetilde{\mathcal{M}}}_{mi} \mathbf{H}_0(\mathbf{z})_i + O(\alpha^4),$$

where $\widetilde{\widetilde{\mathcal{M}}}_{mi} = -\check{C}_{mi} + \mathcal{N}_{mi}$ are the coefficients of a complex symmetric rank 2 tensor.

Proof:

The skew symmetry of \mathcal{P} , $\mathcal{P}_{\ell mji} = -\mathcal{P}_{j m \ell i}$ allows us to write

$$C_{nsi} = \frac{1}{2} \varepsilon_{sjl} \mathcal{P}_{\ell nji} \quad \mathcal{P}_{\ell mji} = \varepsilon_{j \ell s} C_{msi}$$

where C is a rank 3 tensor density.

The rank 3 tensor density has coefficients which satisfy $C_{msi} = -C_{smi}$ and so

$$\check{C}_{mi} := \frac{\beta}{2} \hat{e}_m \cdot \int_B \boldsymbol{\xi} \times (\boldsymbol{\theta}_i + \hat{e}_i \times \boldsymbol{\xi}) d\xi = \frac{1}{4} \varepsilon_{mns} \varepsilon_{sjl} \mathcal{P}_{\ell nji} = \frac{1}{2} \varepsilon_{mns} C_{nsi}, \quad C_{msi} = \varepsilon_{msk} \check{C}_{kl}$$

Combining this with the fact that $D^2 G(\mathbf{x}, \mathbf{z})_{\ell m} = D^2 G(\mathbf{x}, \mathbf{z})_{m \ell}$ and $D^2 G(\mathbf{x}, \mathbf{z})_{\ell \ell} = 0$ completes the proof.

- Predicts the voltage in terms of a complex symmetric rank 2 tensor $\widetilde{\widetilde{\mathcal{M}}}$ with 6 complex coefficients. Agrees with engineering prediction and provides an explicit formula for the Magnetic Polarizability tensor that allow us to explore object characteristics

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






Further reductions in the number of independent coefficients

If an object has mirror or rotation symmetries the coefficients of the tensor must remain invariant under this transformation.

- Under the action of an orthogonal matrix \mathcal{R}

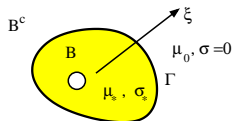
$$\widetilde{\mathcal{M}}'_{ij} = \mathcal{R}_{il} \mathcal{R}_{jm} \widetilde{\mathcal{M}}_{lm}.$$

We can deduce the number of independent coefficients:

Object							
$\widetilde{\mathcal{M}}$	1	1	3	2	2	2	3

Computational treatment of transmission problem

Follow PDL, Zaglmayr (2010), truncate at a finite distance from the object, introduce the domain $\Omega = B \cup \tilde{B}^c$ and solve for $\vartheta_i = \bar{\theta}_i$, $i = 1, 2, 3$:



$$\begin{aligned} \nabla \times \mu_r^{-1} \nabla \times \vartheta_i + i\mu_0\omega\sigma_*\alpha^2\vartheta_i &= -i\mu_0\omega\sigma_*\alpha^2\hat{e}_i \times \xi && \text{in } B, \\ \nabla \times \nabla \times \vartheta_i + \tau\vartheta_i &= \mathbf{0} && \text{in } \tilde{B}^c, \\ [\theta_i \times \hat{n}]_{\Gamma} &= \mathbf{0} && \text{on } \Gamma, \\ [\tilde{\mu}_r^{-1} \nabla \times \vartheta_i \times \hat{n}]_{\Gamma} &= -2 [\tilde{\mu}_r^{-1}]_{\Gamma} \hat{e}_i \times \hat{n} && \text{on } \Gamma, \\ \nabla \times \vartheta_i \times \hat{n} &= \mathbf{0} && \text{on } \partial\Omega, \end{aligned}$$

where $\|\vartheta_i - \bar{\theta}_i\|_{H(\text{curl})} \leq C\tau$, C independent of the small perturbation parameter τ .

Weak form: find $\vartheta_i^T \in \mathbf{H}(\text{curl}, \Omega)$ such that

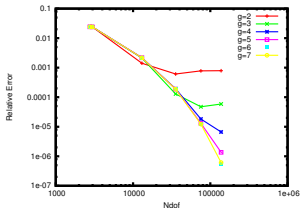
$$\begin{aligned} (\tilde{\mu}_r^{-1} \nabla \times \vartheta_i^T, \nabla \times \mathbf{v})_{\Omega} + (\tilde{\kappa} \vartheta_i^T, \mathbf{v})_{\Omega} &= \\ - (i\mu_0\omega\sigma\alpha^2 \hat{e}_i \times \xi, \mathbf{v})_B - 2 \int_{\Gamma} [\tilde{\mu}_r^{-1}] \hat{e}_i \times \hat{n} \cdot \bar{\nu} d\xi, \end{aligned}$$

for all $\mathbf{v} \in \mathbf{H}(\text{curl}, \Omega)$ where $(\cdot, \cdot)_{\Omega}$ is the L_2 inner product and

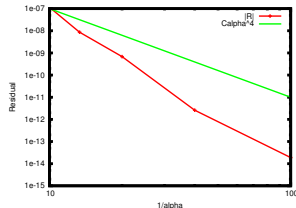
$$\tilde{\kappa} = \begin{cases} i\mu_0\omega\sigma\alpha^2 & \text{in } B \\ \tau & \text{in } \tilde{B}^c \end{cases} \quad \tilde{\mu}_r = \begin{cases} \mu_r & \text{in } B \\ 1 & \text{in } \tilde{B}^c \end{cases}.$$

Verification with known analytical results for $\overline{\mathcal{M}}$

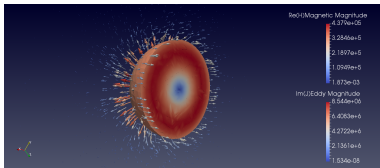
Spherical object $\sigma_* = 5.96e7S/m$, $\mu_* = 1.5\mu_0$, $\omega = 133.5rad/s$, $\alpha = 0.01m$



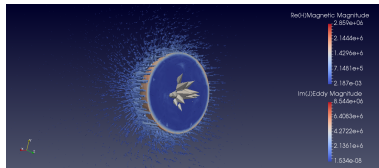
hp FEM convergence



Decay of remainder

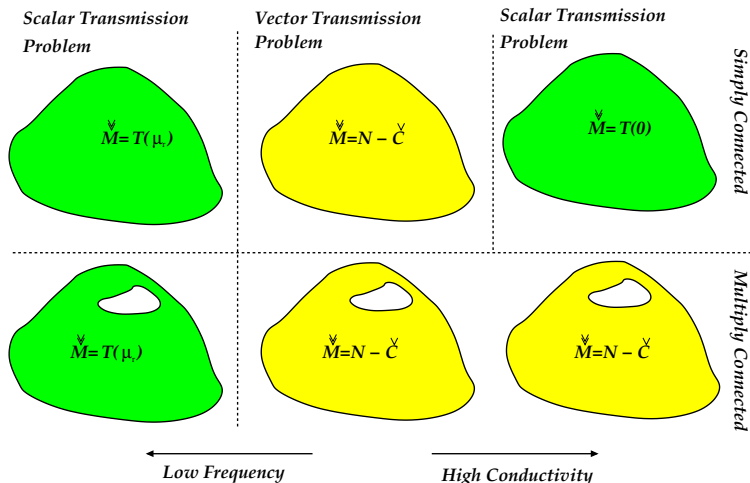


$\text{Re}(\nabla \times \theta_1)$, $|\text{Im}(\omega\sigma\theta_1)|$



and now with $\omega = 133.5 \times 10^3 rad/s$

Limiting cases of \vec{M}



Similar results can be obtained for small σ_* and large ω , but they need to be interpreted in terms of the limit of the eddy current model. (PDL, WRBL (2016)).

Low Frequency and High Conductivity Response

Independent of Betti number $\beta_1(B)$ for an object with conductivity σ_* and relative permeability $\mu_r = \mu_*/\mu_0$, (PDL, WRBL 2016)

$$\widetilde{\widetilde{\mathcal{M}}}_{ij} = \mathcal{T}_{ij}(\mu_r) + O(\omega) \quad \text{as } \omega \rightarrow 0$$

For an object with $\beta_1(B) = 0$, μ_r and fixed ω then

$$\widetilde{\widetilde{\mathcal{M}}}_{ij} = \mathcal{T}_{ij}(0) + O(1/\sqrt{\sigma_*}) \quad \text{as } \sigma_* \rightarrow \infty$$

where

$$\mathcal{T}_{ij}(0) = \alpha^3 \left(|B| \delta_{ij} - \int_{\Gamma} \hat{\mathbf{n}}^- \cdot \hat{\mathbf{e}}_i \phi_j d\xi \right) \quad \text{Magnetic tensor for a PEC}$$

$$\begin{aligned} \nabla^2 \phi_j &= 0 && \text{in } B^c \\ \hat{\mathbf{n}} \cdot \nabla \phi_j &= \hat{\mathbf{n}} \cdot \nabla \xi_j && \text{on } \Gamma \\ \phi_j &\rightarrow 0 && \text{as } |\xi| \rightarrow \infty \end{aligned}$$

- The Betti number does not play a role in objects at low frequencies, but does play a role in high conductivities.

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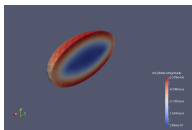
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- The **Betti number does not play a role in objects at low frequencies, but does play a role in high conductivities.**

Frequency response of a conducting (magnetic) spheroid

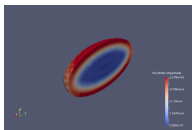


$$\sigma_* = 1.5 \times 10^7 \text{ S/m}$$

$$\mu_* = \mu_0$$

$$\beta_0(B) = 1,$$

$$\beta_1(B) = \beta_2(B) = 0$$

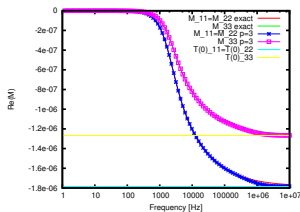


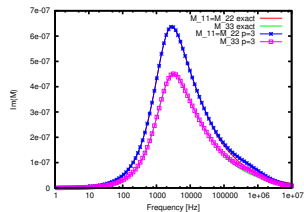
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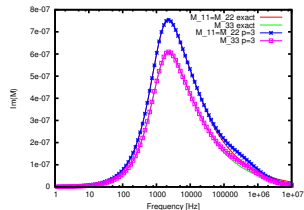
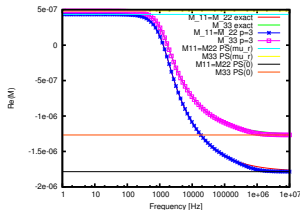
$$\mu_* = 1.5\mu_0$$

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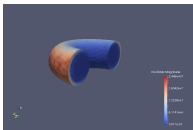


$$\text{Re}(\overline{\overline{\mathcal{M}}})$$


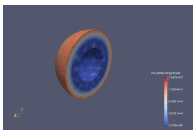
$$\text{Im}(\overline{\overline{\mathcal{M}}})$$


Comparing analytical solution for conducting permeable spheroid, $p = 3$ elements on a mesh of 14 579 tetrahedra and limiting Pólya–Szegő tensor coefficients

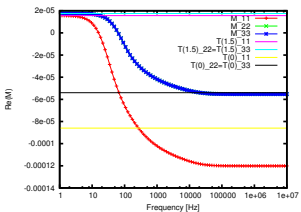
Frequency response of multiply connected objects

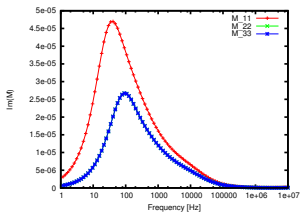


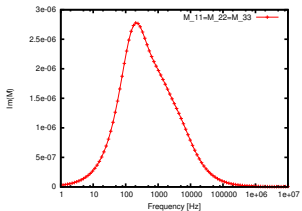
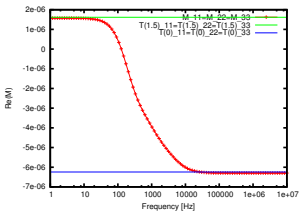
$$\begin{aligned}\sigma_* &= 5.96 \times 10^7 \text{ S/m} \\ \mu_* &= 1.5\mu_0 \\ \beta_0(\mathbf{B}) &= \beta_1(\mathbf{B}) = 1, \\ \beta_2(\mathbf{B}) &= 0\end{aligned}$$



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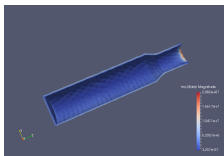
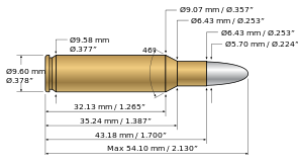


$$\text{Re}(\overline{\overline{\mathcal{M}}})$$


$$\text{Im}(\overline{\overline{\mathcal{M}}})$$


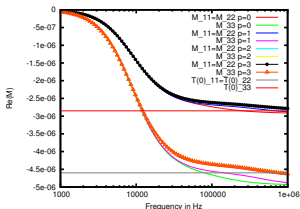
$p = 2$ elements on meshes of 29 882, 6 873 tetrahedra respectively, comparison with limiting Pólya–Szegő tensor coefficients

Realistic Remington .222 shell casing test case

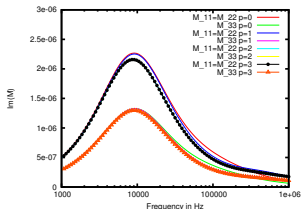


z axis parallel to barrel

- Only shell casing considered with $\mu_* = \mu_0$ and $\sigma_* = 1.5 \times 10^7 \text{ S/m}$.
- Rotational and reflection symmetries imply $\overline{\overline{\mathcal{M}}}$ is diagonal with coefficients $\overline{\overline{\mathcal{M}}}_{11} = \overline{\overline{\mathcal{M}}}_{22}$ and $\overline{\overline{\mathcal{M}}}_{33}$.



$\overline{\overline{\mathcal{M}}}$
 $\text{Re}(\overline{\overline{\mathcal{M}}})$



$\overline{\overline{\mathcal{M}}}$
 $\text{Im}(\overline{\overline{\mathcal{M}}})$

First steps with Bayesian inversion

Recall at the start we stated the inverse problem as the minimisation problem.

$$\min_{\mathbf{p}} \|\mathbf{d} - \mathbf{F}(\mathbf{p})\|^2 + \|\mathbf{R}(\mathbf{p})\|^2$$

Polarization tensors offer a low-cost way of describing the forward problem $\mathbf{F}(\mathbf{p})$, where $\mathbf{p} := \{\overline{\overline{\mathcal{M}}}_{11}, \overline{\overline{\mathcal{M}}}_{22}, \overline{\overline{\mathcal{M}}}_{33}, \overline{\overline{\mathcal{M}}}_{12}, \overline{\overline{\mathcal{M}}}_{13}, \overline{\overline{\mathcal{M}}}_{23}\}$, say.

The Bayesian approach can be thought of as being natural when statistical information about the noise is available:

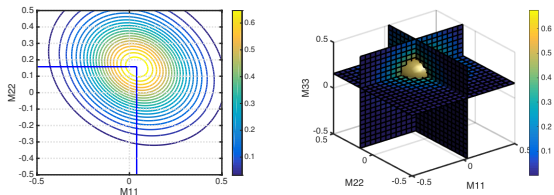
- Likelihood density $\pi(\mathbf{d}|\mathbf{p}) \sim \exp\{-\frac{1}{2}(\mathbf{F}(\mathbf{p}) - \mathbf{d})_i C_{ij}^{-1} (\mathbf{F}(\mathbf{p}) - \mathbf{d})_j\}$ if $\mathbf{e} \sim \mathcal{N}(0, C)$.
- Prior probability distribution $\pi(\mathbf{p}) \sim \exp\{-\frac{1}{2}\mathbf{p}_i D_{ij}^{-1} \mathbf{p}_j\}$ for a regularising prior with $\mathbf{p} \sim \mathcal{N}(0, D)$
- Bayes formula then gives the posterior as a probability distribution

$$\begin{aligned} \pi(\mathbf{p}|\mathbf{d}) &\sim \pi(\mathbf{d}|\mathbf{p})\pi(\mathbf{p}) \\ &\sim \exp\left\{-\frac{1}{2}(\mathbf{F}(\mathbf{p}) - \mathbf{d})_i C_{ij}^{-1} (\mathbf{F}(\mathbf{p}) - \mathbf{d})_j - \frac{1}{2}\mathbf{p}_i D_{ij}^{-1} \mathbf{p}_j\right\} \end{aligned}$$

(written for simplicity for the real case)

Exploring the probability distribution

Notice that for different trial solutions \mathbf{u} , $\pi(\mathbf{p}|\mathbf{d})$ gives us the probability of \mathbf{p} given \mathbf{d}

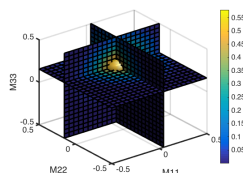
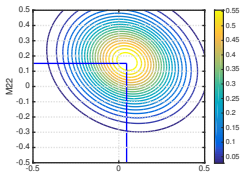
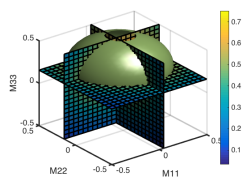
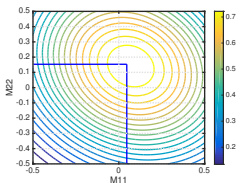
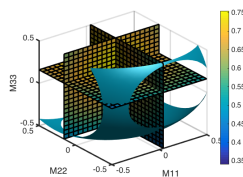
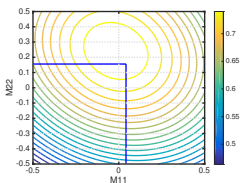


We can interrogate the distribution using conditional mean (CM), maximum a-posterior (MAP) estimates, which for Gaussian distributions become

$$\begin{aligned} \mathbf{u}_{CM} = \mathbf{p}_{MAP} &= \min \mathcal{F}(\mathbf{p}) = \min \frac{1}{2} \left(\|\mathbf{F}(\mathbf{p}) - \mathbf{d}\|_V^2 + \lambda \|\mathbf{p}\|_W^2 \right) \\ &= \min \frac{1}{2} \left((\mathbf{F}(\mathbf{p}) - \mathbf{d})_i C_{ij}^{-1} (\mathbf{F}(\mathbf{p}) - \mathbf{d})_j + \lambda^{-2} \mathbf{p}_i D_{ij}^{-1} \mathbf{p}_i \right) \end{aligned}$$

with $V = S^{-1}$, $W = G^{-1}$, $C = SS^T$, $D = GG^T$ (Cholesky factorisation of a p.d. matrix).

Noise levels $\sigma = 0.5, 0.25, 0.1$, $C = \sigma^2 \mathbb{I}$, D approx. with 125 samples.



Conclusions

- PS tensor provides the leading order response in EIT and EM scattering, but the situation is different for eddy currents;
- Recent results of Ammari, *et al.* predicts the response in terms of a rank 4 tensor;
- But our recent work shows this does in fact reduce to an expansion involving a symmetric rank 2 tensor $\widetilde{\widetilde{\mathcal{M}}}$;
- $\widetilde{\widetilde{\mathcal{M}}}$ is part of a family of polarizability tensors for describing the response from conducting and permeable objects;
- Skin effects are important and $\widetilde{\widetilde{\mathcal{M}}}$ can be computed by using hp - edge finite elements;
- Asymptotic behaviour of low frequency/high conductivity for $\widetilde{\widetilde{\mathcal{M}}}$ investigated where topology plays a role;
- On going work includes developing a Bayesian inverse framework for $\widetilde{\widetilde{\mathcal{M}}}$.

References

Thank you

References

- P. D. Ledger, W.R.B. Lionheart, The perturbation of electromagnetic fields at distances that are large compared with the object's size, *IMA Journal of Applied Mathematics*, **80**: 865-892 (2015a).
- P. D. Ledger, W.R.B. Lionheart, Characterising the shape and material properties of hidden targets from magnetic induction data, *IMA Journal of Applied Mathematics*, **80**: 1776-1798 (2015b).
- P.D. Ledger and W.R.B. Lionheart, Understanding the magnetic polarizability tensor, *IEEE Transactions on Magnetics*, **52**, Article # 6201216 (2016).