

# Practical challenges faced when using modern approaches to numerical PDEs to simulate petroleum reservoirs

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# Our groups work

- Which subject do we come from
  - Hyperbolic conservation laws
  - (Geometrical Integration, computational geometry, Physics)
- History of the research in reservoirs,
  - From: Complicated methods for simple problems like (incompressible 2phase flow)
    - Discretization: (Eliptic; mimetic, mpfa, Hyperbolic: fronttracking, reordering, operator splitting)
    - Multiscale (Mixed finite element,m Finite Volume .)
    - Streamlines (Fronttracking)
  - To: Simple Methods for complicated problems
    - fast prototyping, model reduction, optimization, EOR
- Software:
  - Matlab Reservoir Simulation Toolbox (MRST)
    - Collection of our research
    - Research tool
    - Fast prototyping
  - Open Porous Media (OPM) C++
    - Platform for implementing methods on Industry standard models

## People (Current):

**Knut Andreas Lie**

Stein Krogstad

Atgeirr Rasmussen

Xavier Raynaud

Olav Møyner

Bård Skaflestad

# Matlab Reservoir Simulation Toolbox - MRST

- An *open source* comprehensive set of routines for reading, visualising and running numerical simulations on reservoir models.
- Developed at SINTEF Applied Mathematics.
- MRST core: grid + basic functionality
- Add-on modules: discretizations (TPFA, MPFA, mimetic), black oil, thermal, upscaling, coarsening, multiscale, flow diagnostics, CO2 laboratory,....

## Statistics: (release 2013b)

- Number of downloads: ~3000
- Number of countries: ~120
- Number of institutions: ~1080

<http://www.sintef.no/MRST/>

MRST - MATLAB Reservoir Simulation Toolbox

MRST Modules Tutorials Gallery Download Publications Developers Contact

The **MATLAB Reservoir Simulation Toolbox (MRST)** is developed by **SINTEF Applied Mathematics** and is a result of our research on the development of new (multiscale) computational methodologies.

The toolbox consists of two main parts: a **core** offering basic functionality and single and two-phase solvers, and a set of **add-on modules** offering more advanced models, viewers and solvers. MRST is mainly intended as a toolbox for rapid prototyping and demonstration of new simulation methods and modeling concepts on unstructured grids. Despite this, many of the tools are quite efficient and can be applied to surprisingly large and complex models. For more computationally challenging cases, we are developing C-accelerated backends or standalone C++ solutions as part of the **Open Porous Media (OPM)** initiative.

Version 2013a was released on April 19th 2013, and can be **downloaded** under the terms of the **GNU General Public License (GPL)**. See **our video** highlighting some new features.

If you are using MRST in any publication, please cite our overview paper:

- K.-A. Lie, S. Krogstad, I. S. Lagaarden, J. R. Natvig, H. M. Nilsen, and B. Skaflestad. **Open source MATLAB implementation of consistent discretisations on complex grids**. *Comput. Geosci.*, Vol. 16, No. 2, pp. 297-322, 2012. DOI: 10.1007/s10596-011-9244-4

**Numerical CO<sub>2</sub> Laboratory**

is a MRST module that contains a variety of routines and examples that all focus on studies of phenomena related to geological CO<sub>2</sub> storage. The module includes an interactive viewer that simplifies the process of identifying structural traps and their connection. The user can mark any injection point (or structural trap) to compute the migration path and all traps encountered along this path to the top of the formation, or the user can determine all traps that are downslope of an accumulation point. Likewise, individual traps can be selected and inspected in more detail.

The figure to the left shows a vertical equilibrium simulation of the Sleipner injection, assuming a sharp interface between CO<sub>2</sub> and brine. The simulation includes a detailed CO<sub>2</sub> volume inventory.

[Read more](#)

**Fully implicit solvers based on automatic differentiation**

For rapid development of solvers capable of handling complex physics and adjoint optimization, MRST includes a set of routines for constructing general solvers based on automatic differentiation. When using automatic differentiation, jacobians are calculated automatically based on common rules, making inclusion of new model effects much easier.

The current release includes fully-implicit black-oil and polymer simulators with gas dissolution, multiple well limits, and a CPR-type preconditioner. The simulators give good match compared with a commercial simulator on industry-standard benchmarks such as SPE1 and SPE9 (the plot to the left), good matches have also been obtained on simulation models of real fields.

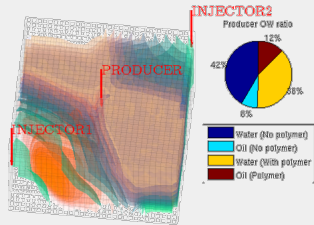
[Read more](#)

Main idea: flexibility and rapid prototyping  
Light weight/  
special purpose

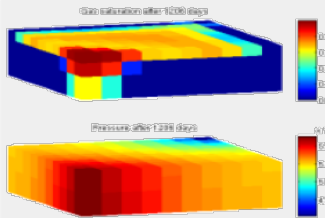
Black box/  
general purpose

complexity/ computational complexity

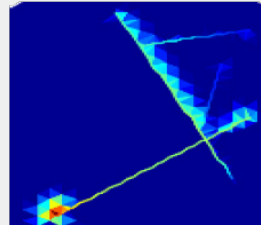
# MRST add-on modules



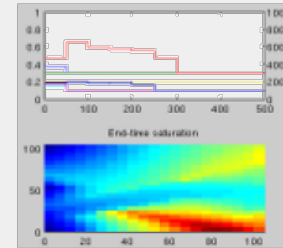
Fully implicit solvers  
(AD and gradients)



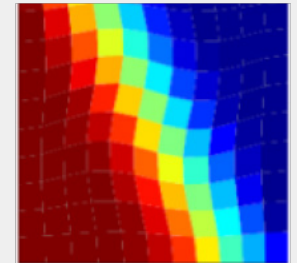
IMPES black-oil  
solvers



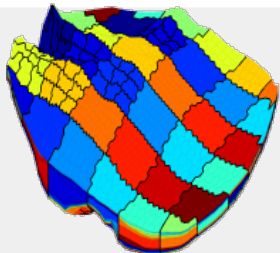
Discrete fracture  
models



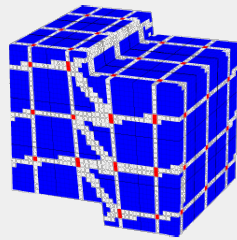
Adjoint methods



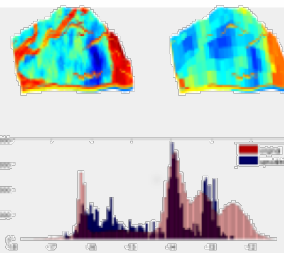
MPFA methods



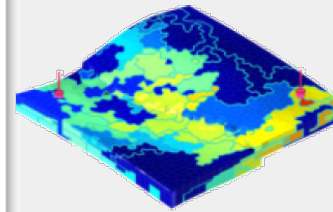
Multiscale mixed  
finite elements



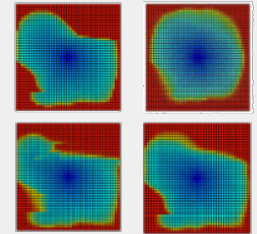
Multiscale finite  
volumes



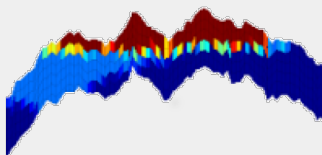
Single and two-  
phase upscaling



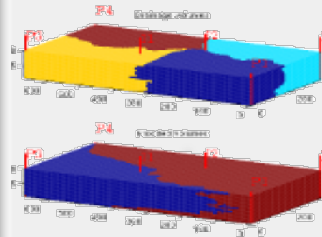
Grid coarsening



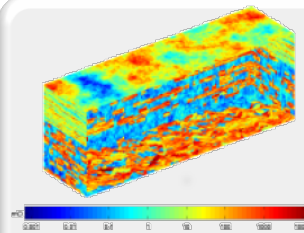
Ensemble Kalman  
filter



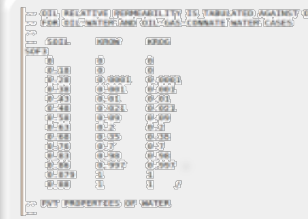
CO2 laboratory



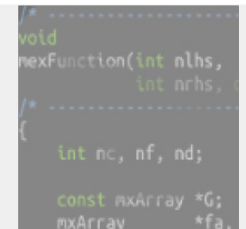
Flow diagnostics



Data sets  
(e.g. SPE 10)



Industry standard  
input formats



C-accelerated  
routines

# Question:

Why is almost all simulations of reservoirs today using a fully implicit Two Point Method with Mobility upwinding.

## Outline

- Reservoir simulation: model , challenges
- Fully implicit two point method's
  - Problems, (Advantages)
- Why not (?)
  - Higher order
  - Explicit saturation
  - Operator splitting based
  - MPFA, MIMETIC ...
- Conclusion/Challenges

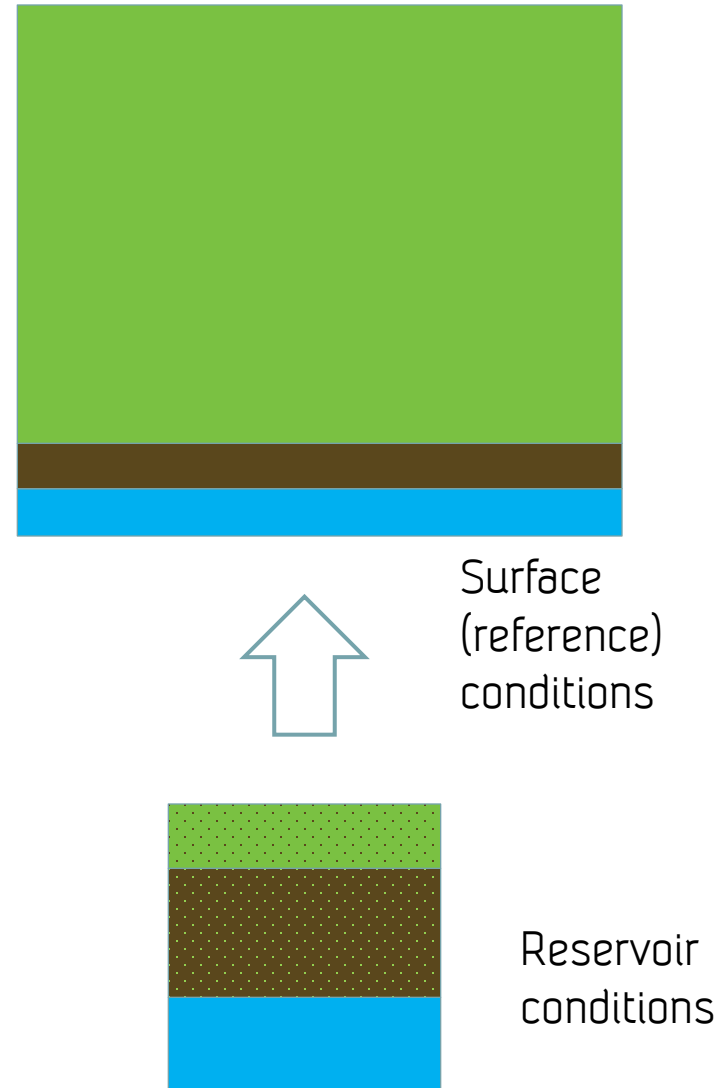
# Model: Black-oil model

- 3 component – 3phase model

		components		
		W	O	G
phases	W	X		
	O		X	X
	G		X	X

## Unknowns

- Phase pressures  $p_\alpha$
- Phase saturations  $s_\alpha$
- Gas comp. in oil phase  $r_s$
- Oil comp. in gas phase  $r_v$



# Black-oil model

$$\frac{d}{dt}(\phi b_w s_w) + \nabla \cdot (b_w v_w) - b_w q_w = 0$$

$$\frac{d}{dt}(\phi(b_g r_v s_g + b_o s_o)) + \nabla \cdot (b_g r_v v_g + b_o v_o) - (b_g r_v q_g + b_o q_o) = 0$$

$$\frac{d}{dt}(\phi(b_g s_g + b_o r_s s_o)) + \nabla \cdot (b_g v_g + b_o r_s v_o) - (b_g q_g + b_o r_s q_o) = 0$$

$$v_j = -\frac{k_{rj}}{\mu_j} K(\nabla p_j - \rho_j g \nabla z)$$

Primary variables:

- Oil pressure
- Water saturation , gas saturation(/dissolved gas/dissolved oil)

Two point flux mobility upwinding:

$$dp_{i,j} = (p_j - p_i - \rho_{i,j} g(z_j - z_i))$$

$$v_{i,j} = \begin{cases} -\frac{k_{r,j}}{\mu_j} T_{i,j} dp_{i,j} & \text{for } dp_{i,j} \geq 0 \\ -\frac{k_{r,i}}{\mu_i} T_{i,j} dp_{i,j} & \text{for } dp_{i,j} < 0 \end{cases}$$

# Black-oil model: wells

For each connection:

$$q_j = T m_{wj} (p_w - p + Hw)$$

- Well head computed explicitly based on phase distribution along well
- For producing connection:

$$m_{wj} = m_j = \frac{k_{rj}}{\mu_j}$$

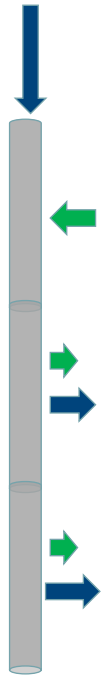
- For injecting connection:

$$m_{wj} = \alpha_j (m_w + m_o + m_g)$$

- $\alpha_j$  is the volume fraction of phase  $j$  in the injected mixture at connection conditions

## Handling of *cross-flow (implicit)*:

- 1) Compute inflow from producing connections (at reference conditions)
- 2) Compute average wellbore mixture (at reference conditions)
- 3) Compute average volumetric mixture at injection connection conditions
- 4) Compute injection connection mobilities





# Black-oil model: Jacobian

Setting up the Jacobian:

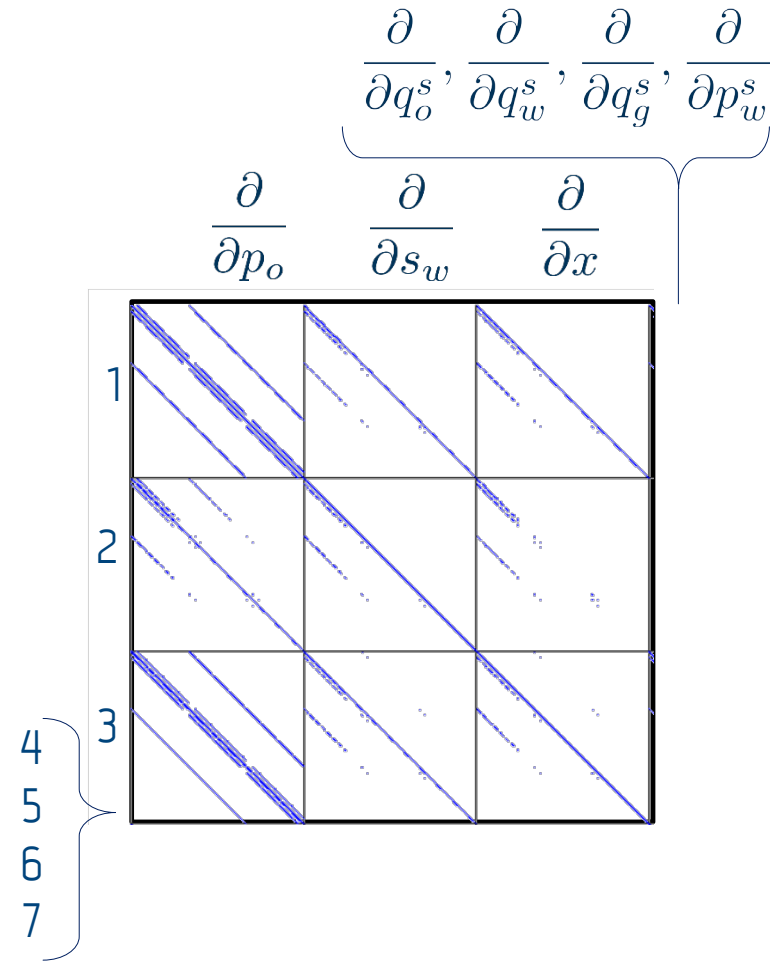
- Primary variables:

$$p_o, s_w, x, q_o^s, q_w^s, q_g^s, p_w$$

$$\underbrace{\hspace{10em}}_{s_g, r_s, r_v}$$

- Equations:

- 1-3: reservoir equations
- 4-6:  $q_w^s - \sum b_w^c q_w^c = 0, q_o^s = \dots$
- 7: well control (phase rates, bhp, ...)



$$\frac{V}{\Delta t} (\phi^{n+1} b_w^{n+1} s_w^{n+1} - \phi^n b_w^n s_w^n) + \nabla \cdot (b_w^{n+1} v_w^{n+1}) - b_w^{n+1} q_w^{n+1} = 0$$

```
dpW = s.grad(p-pcOW) - g*(rhoWf.*s.grad(z));upc = (double(dpW)>=0);
bWvW = s.faceUpstr(upc, bW.*mobW).*s.T.*dpW;
eqs{2} = (pv/dt).*( pvMult.*bW.*sW - pvMult0.*f.bW(p0).*sW0 ) + s.div(bWvW);
```

# Black-oil model: linear system

## Solution procedure for linear equation

$$\frac{\partial F(x^i)}{\partial x^i} \delta x^{i+1} = -F(x^i)$$

1. Eliminate  $\delta q_o^s, \delta q_w^s, \delta q_g^s$

2. Eliminate  $\delta p_w$

$$\begin{bmatrix} A_{op_o} & A_{os_w} & A_{om} \\ A_{wp_o} & A_{ws_w} & A_{wm} \\ A_{gp_o} & A_{gs_w} & A_{gm} \end{bmatrix} \begin{bmatrix} \delta p_o \\ \delta s_w \\ \delta m \end{bmatrix} = \begin{bmatrix} r_o \\ r_w \\ r_g \end{bmatrix}$$

3. After approximate decoupling of pressure, we solve the resulting linear system using GMRES with CPR preconditioner,

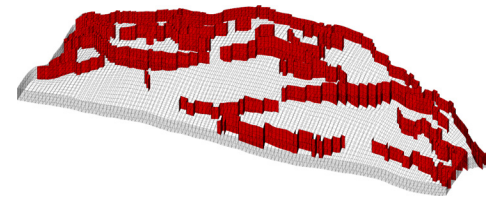
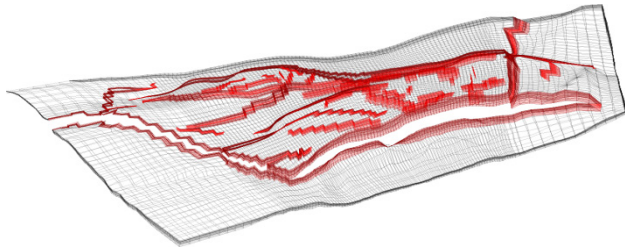
4. Recover remaining variables

- Similar (transposed) approach implemented for adjoint equations
- *Appleyard chop* performed when updating saturations

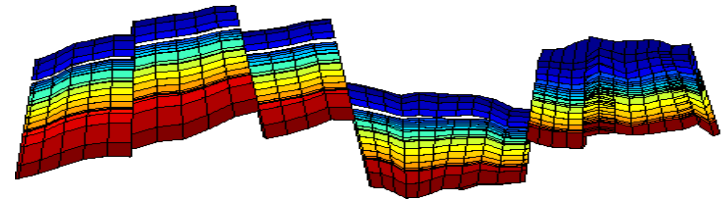
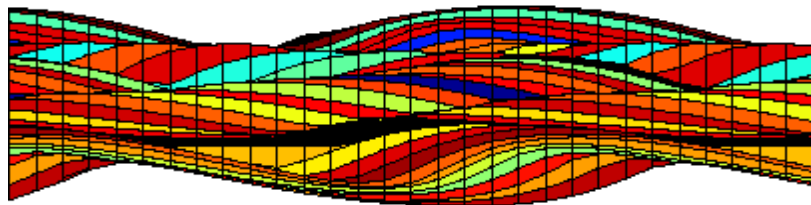
- The CPR preconditioner consist of
  1. ILU on whole system
  2. Algebraic multigrid on pressure sub-system,

# Grid: model and data

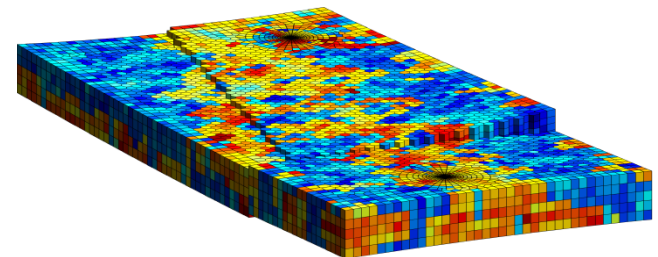
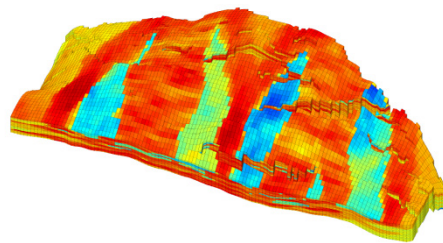
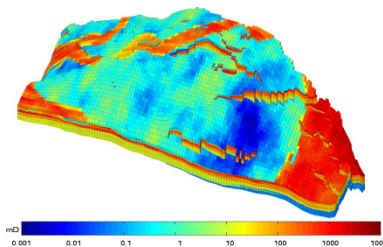
- The structure of the reservoir ( geological , surfaces, faults, etc)



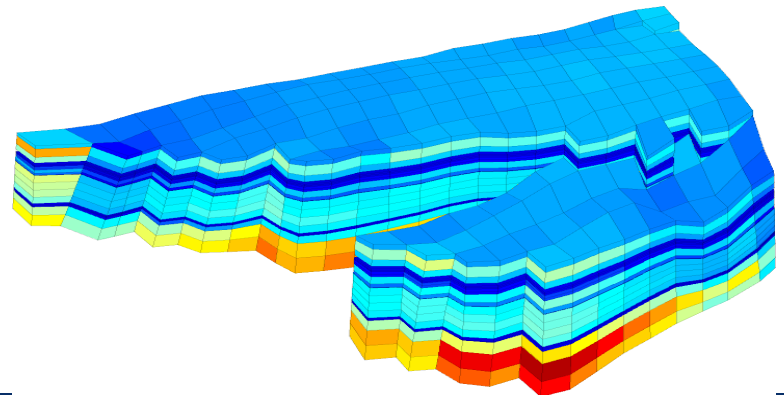
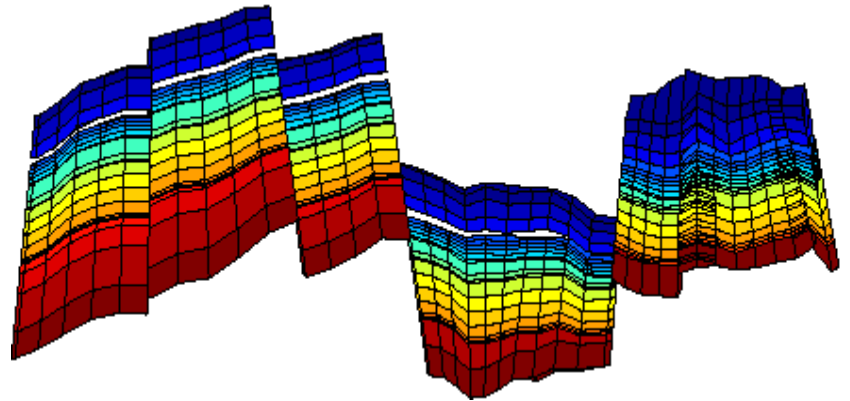
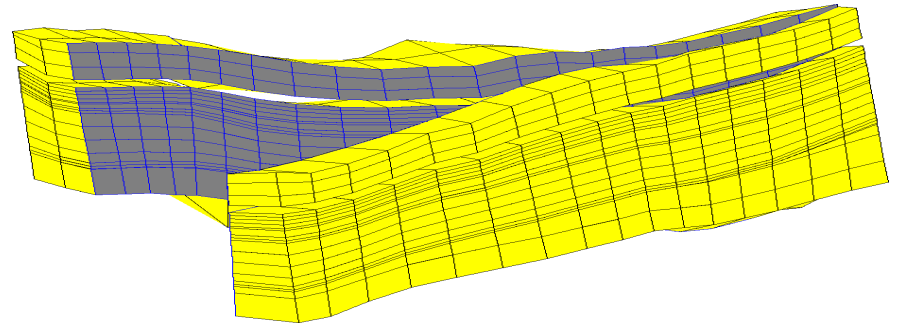
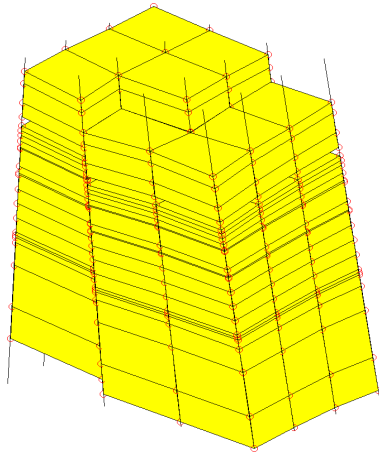
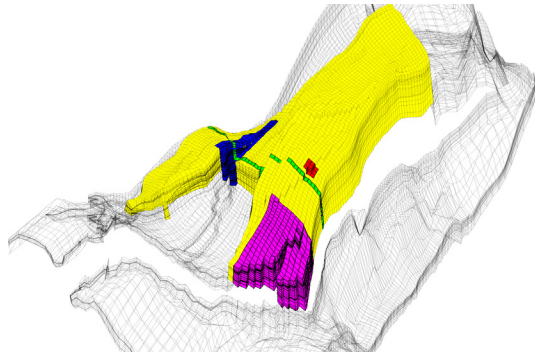
- The stratigraphy of the reservoir (sedimentary structure)



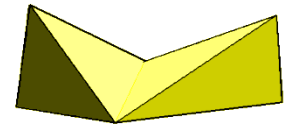
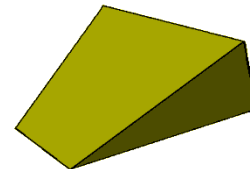
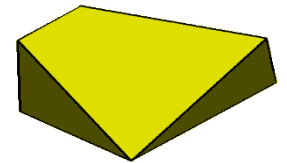
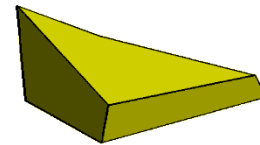
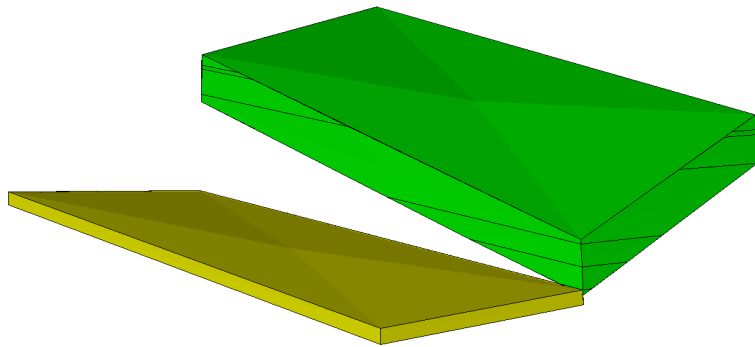
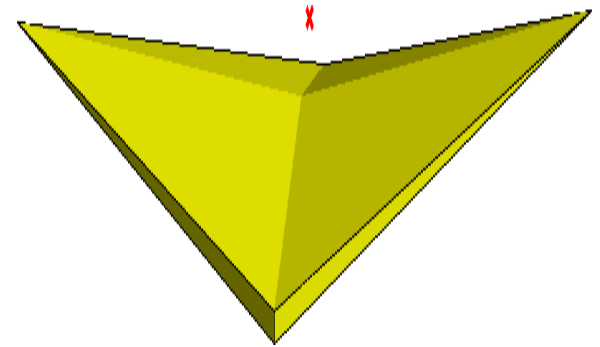
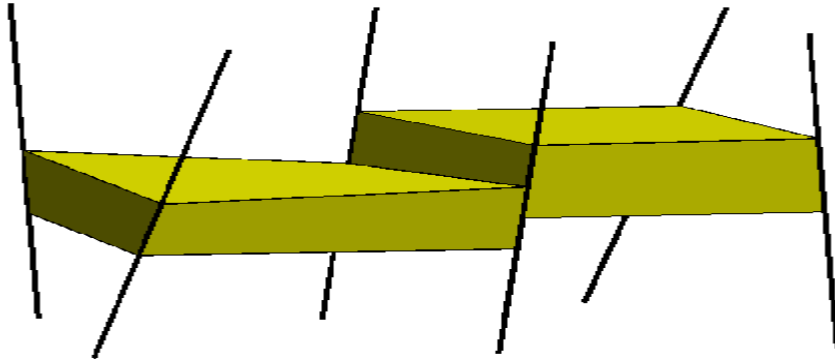
- Petrophysical parameters (permeability, porosity, net-to-gross, ....)



# Grid: North Sea Model

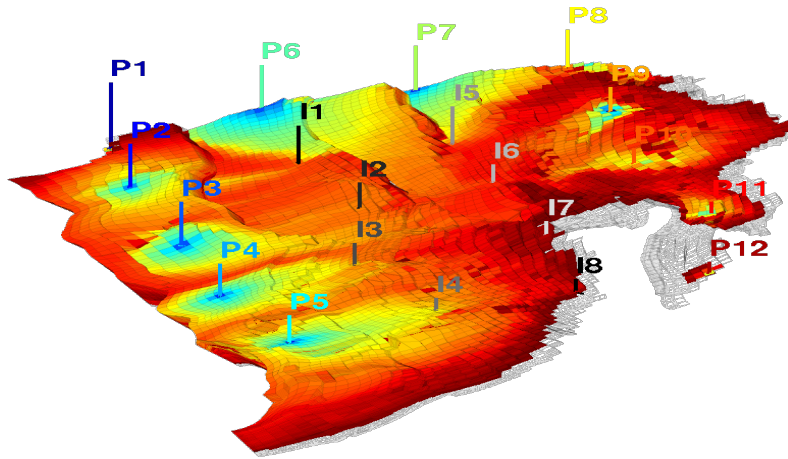


# Grid: strange cells



# Few observations, few data

- Wells are the observables



The incompressible single phase case have only  $n-1$  degrees of freedom for all possible boundary conditions

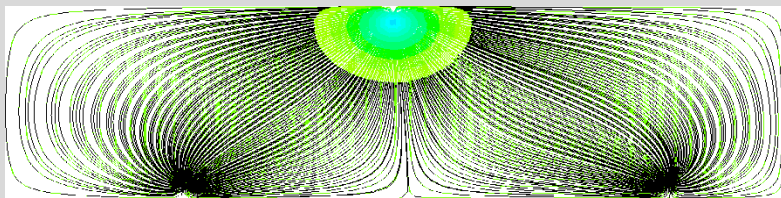
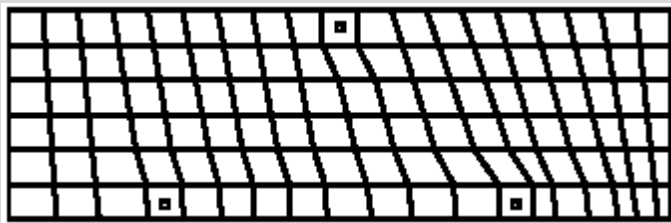
- Observables:
  - Well rates (oil, water, gas)
  - Bottom hole pressure
- Parameter knowledge
  - Horizons – seismic
  - Permeability, porosity, relative permeability from cores
  - Geological interpretation/knowledge, interpolation, geostatistic
  - historymatching

# Grid orientation effects/ tensor permeability

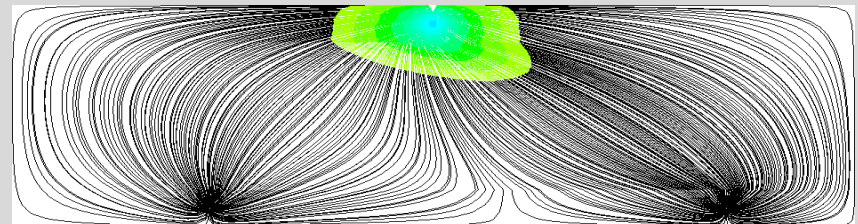
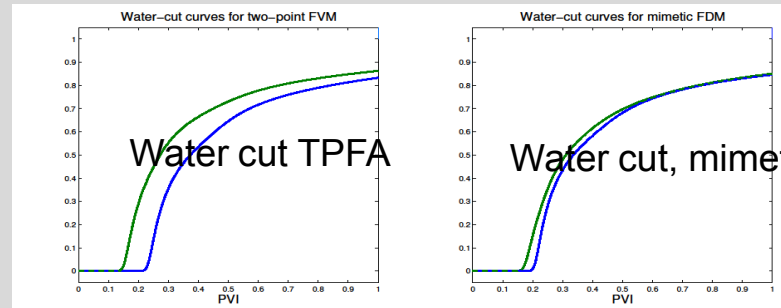
Standard method + skew grid = grid-orientation effects

MPFA/mimetic : Consistent discretization methods capable of handling general polyhedral grids

Example:  
Homogenous and isotropic medium with a  
symmetric well pattern



Streamlines Mimetic

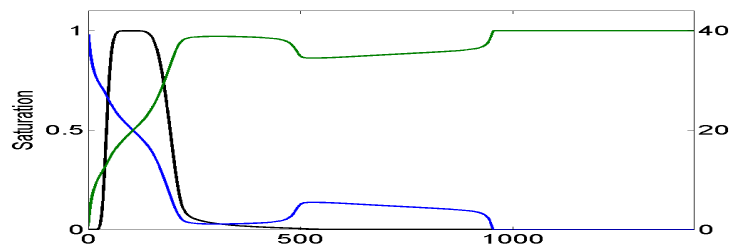


Streamlines TPFA

Upscaled models do have tensor permeability and relative permeability

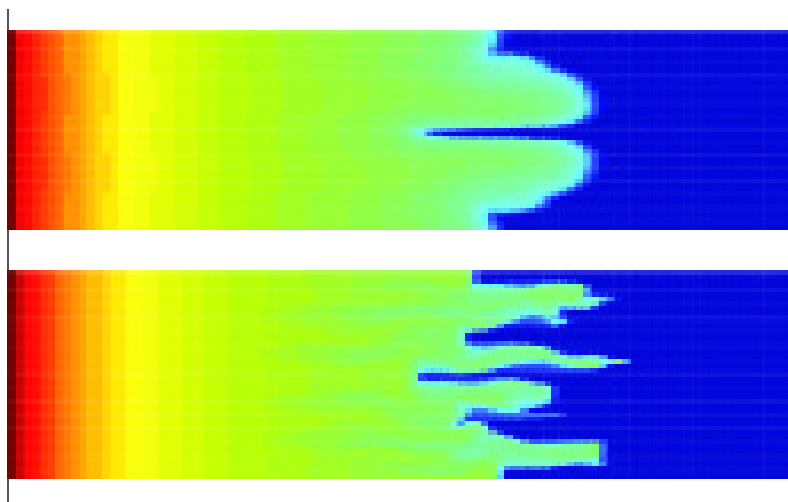
# Numerical diffusion

- Front capturing



Upwind need fine grid and small time steps to resolve a polymer slug

- Viscous fingering instabilities

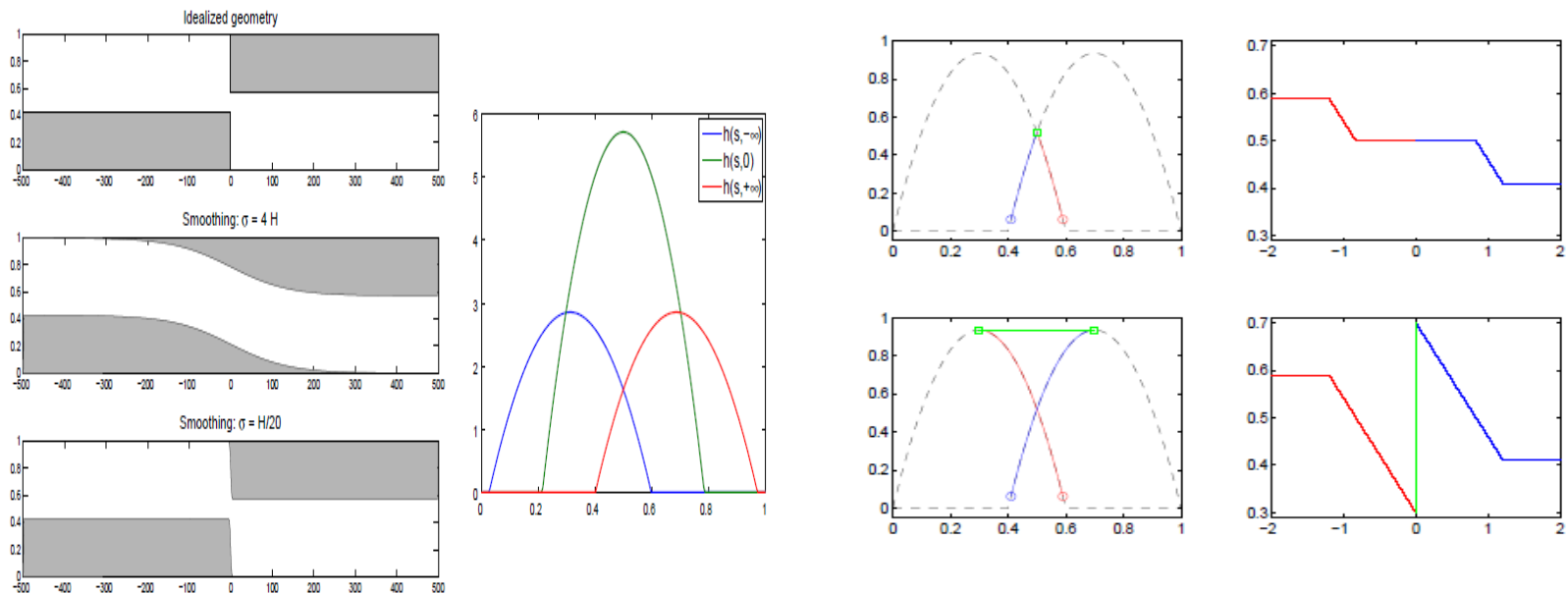


Viscous fingering comparing a fully implicit single-point upwind and 'TVD-type' schemes



# Discontinuous Riemann problem

$$\frac{\partial s}{\partial t} + \frac{\partial}{\partial x} h(s, x) = q(x), \quad h(s, x) = f_g(s, x)g(x),$$



Upwind method do not always give the physical solution

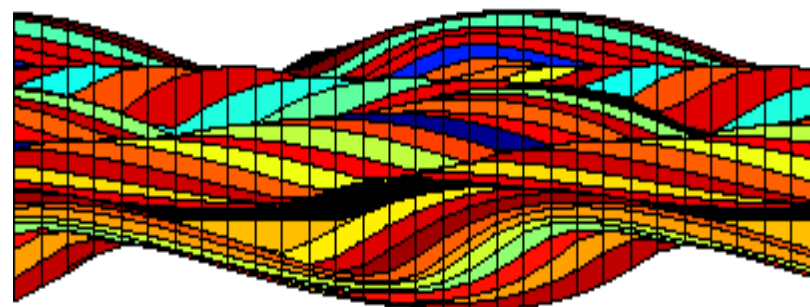
# Proposed methods:

- Explicit
- Splitting:
  - Full system
    - Pressure and transport
  - Transport:
    - Advection, (convection) diffusion
- High order:
- MPFA, MIMETIC, Mixed finite element, DG
- Parallelization:

# Explicit methods

- Heterogeneity (grids):

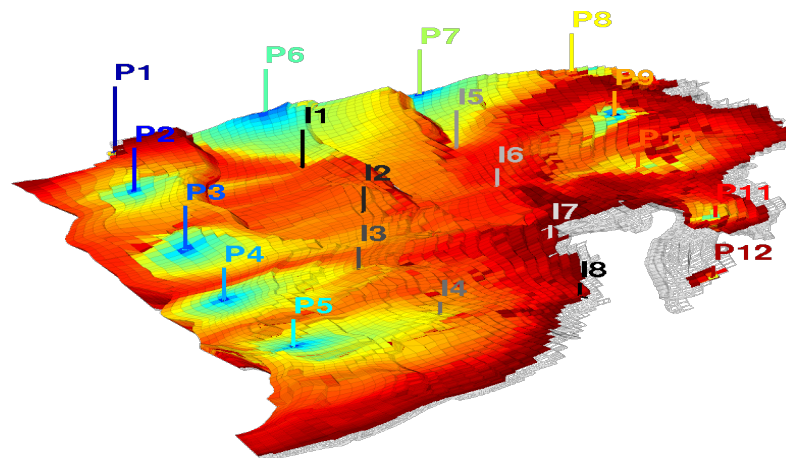
- small cells
- high porosity



- Wells

- Velocity

$$v \sim \frac{1}{r}$$



High CFL numbers from  
localized features

# Splitting:

## Pressure ("elliptic") – transport ("hyperbolic")

- Incompressible two phase flow:

$$\nabla \cdot \vec{v} = q \quad (1)$$

$$\vec{v} + \lambda K [\nabla p - \lambda_w \rho_w + \lambda_n \rho_n] \vec{g} = 0$$

$$\phi \frac{\partial s_w}{\partial t} + \nabla \cdot [f_w (\vec{v} + \lambda_n (\rho_w - \rho_n) K \vec{g})] = q_w. \quad (2)$$

- Equation 1) independent of saturation (and pressure)

- Equation 2) has solution if  $\nabla \cdot \vec{v} = q$

## Splitting:

Pressure ("elliptic") – transport splitting ("hyperbolic")

$$\phi(c_w S_w + (1 - S_w)c_o) \frac{\partial p}{\partial t} + (f_w c_w + (1 - f_w)c_o) \nabla p \cdot \vec{v} + \nabla \cdot \vec{v} = q \quad (1)$$

$$\vec{v} + \lambda K [\nabla p - \lambda_w \rho_w + \lambda_n \rho_n] \vec{g} = 0$$

$$\phi \frac{\partial \rho_w s_w}{\partial t} + \nabla \cdot [\rho_w f_w (\vec{v} + \lambda_n (\rho_w - \rho_n) K \vec{g})] = q_w. \quad (2)$$

- Equation 1) not independent of saturation
- There may be no solution to 2) if 1) is not fulfilled
  - Saturation outside range (0,1)

# Strong coupling: Vertical equilibrium model

Integration in vertical direction  $\rightarrow$  pressure equation:

$$\nabla_{\parallel} \cdot \vec{v} = q_{\text{tot}}, \quad \vec{v} = -\lambda_t \left[ \nabla_{\parallel} p_t - \left( f_v \rho_{\text{CO}_2} + [1 - f_v] \rho_w \right) \vec{g}_{\parallel} + \frac{\lambda_w}{\lambda_t} \nabla_{\parallel} g_c \right]$$

and transport equation:

$$\phi H(x) \frac{\partial s}{\partial t} + \nabla_{\parallel} \cdot \left( f_v(s, x) \vec{v} + f_g(s, x) \left[ \vec{g}_{\parallel} + \nabla_{\parallel} g_c(s, x) \right] \right) = q(x)$$

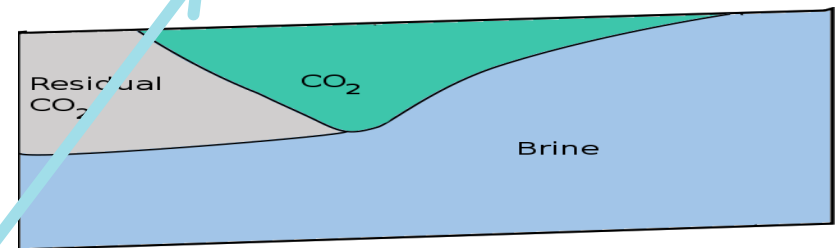
$$\lambda_c(s, x) = \frac{1}{\mu_c} \int_0^{sH} k_c(1) K_x(z, x) dz$$

$$\lambda_w(s, x) = \frac{1}{\mu_w} \int_{sH}^H k_w(1) K_x(z, x) dz$$

$$f_v(s, x) = \frac{\lambda_c(s, x)}{\lambda_c(s, x) + \lambda_w(s, x)}$$

$$f_g(s, x) = \lambda_w(s, x) f(s, x)$$

$$g_c(s, x) = H(x) (\rho_c - \rho_w) g_{\perp} s$$



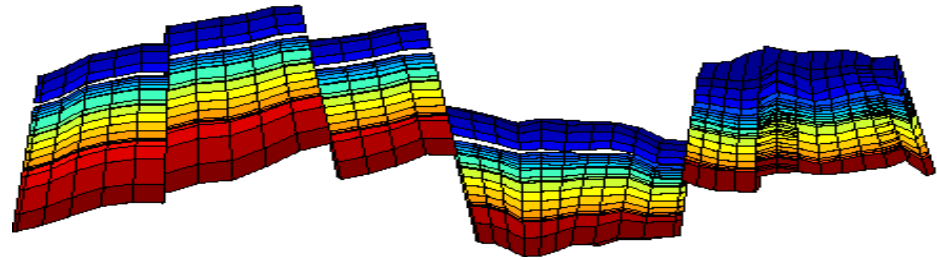
$H$  - height of formation  
 $h$  - height of CO<sub>2</sub>  
 $s$  - relative height,  $h/H$

$\lambda_{\alpha}$  - pseudo mobility  
 $p_t$  - pressure at top surface  
 $\parallel$  - parallel to top surface

The "transport" equation have obtained a parabolic term, by strong gravity coupling to pressure equation.

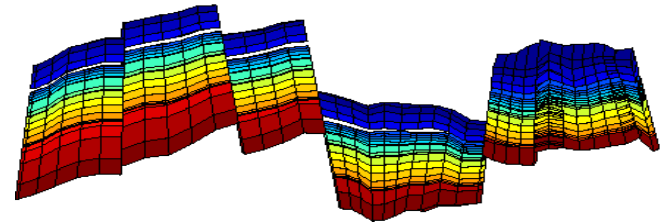
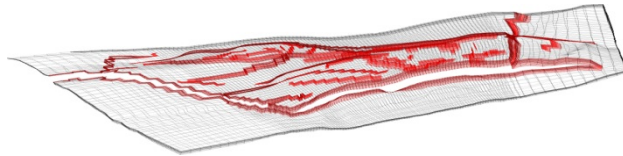
# High order

- Pressure
  - Heterogeneity permeability
  - Large uncertainty
  - No gain?
- Transport ( DG?)
  - Splitting to transport problem?
  - Explicit methods excluded, need to be implicit



# MIMETIC, MPFA, ..

- Pressure equation
  - Problematic for aspect ratio: anisotropy (MPFA/mimetic(?))
  - More expensive : (Mimic 3 times dof, 2 times bandwidth)

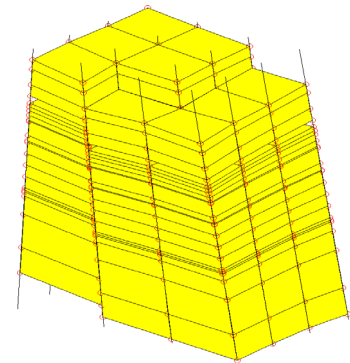
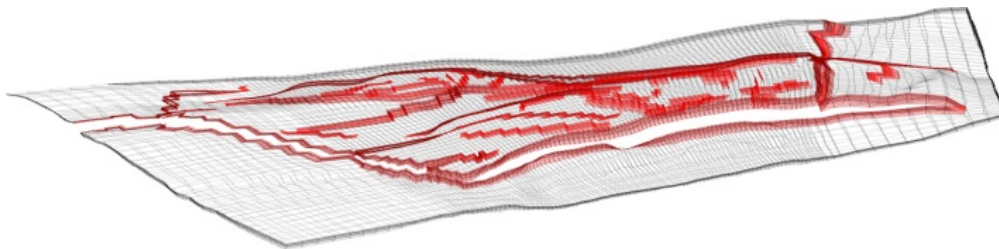
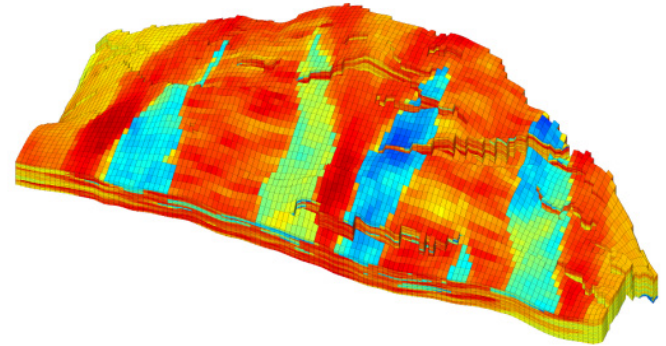


- Limited experience: Nonlinear methods
- Coupled system
  - Formulation ? (Mixed, mimetic,...)
  - Stability for hyperbolic part: Upwinding ?, numerical flux ?
  - Physical effects
    - Gravity, Capillary pressure, wells and dissolution



# Others

- Parallelization
  - Communication costs due to need for implicit solver
  - Difficulty of partitioning due to
    - Channelized flow
    - Long horizontal Wells, give nonlocal connections
- Methods using simplexes
  - Aspect ration imply to many grids



# Our view on specific challenges for reservoir simulation

- Large aspect ratio
  - Reservoirs: 10 km laterally , 50-200 m vertically
- Discontinuities:
  - Permeability
  - Relative permeability
  - Capillary pressure
- Grid and model parameter are strongly connected
  - strange grids, general polyhedral cells
- Coarse grid
  - Grid cells typically 100m laterally , 4 m vertically
  - Transport hyperbolic
- Strong coupling between "elliptic" and "hyperbolic" variables
  - Large scale: gravity
  - Smaller scale: capillary pressure
- Non local connections:
  - Wells or fast flowing channels
  - Parallelization

# Conclusion: What is needed

- Research should focus on:
  - Methods for general challenging grid with generic implementation
  - Methods which work for elliptic, parabolic and hyperbolic problems
  - Methods for strongly coupled problems
  - Tensor Mobilities
- Specific purpose simulators
  - Codes using modern methods for correctly simplified systems
- Accept for simplifications
  - In reservoir simulation an fully implicit solve using TPFA and mobility upwinding is often assumed to be the truth.
- Work flows including:
  - Simple models
  - Numerical (specific) upscaled/reduced models
  - Trusted simulations/"Full physics simulations."
- Open source
  - Simulators to challenge industry simulators
  - Implementations of current research
- Open Data
  - Real reservoir models as benchmark

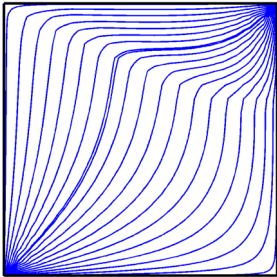


# More advanced operator splitting

$$\nabla \cdot \vec{v} = q, \quad \vec{v} + \lambda K [\nabla p - \lambda_w \rho_w + \lambda_n \rho_n) \vec{g}] = 0$$

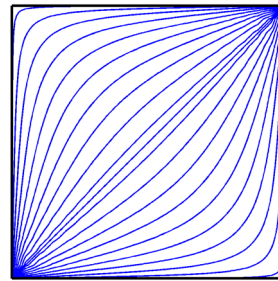
$$\phi \frac{\partial s_w}{\partial t} + \nabla \cdot [f_w(\vec{v} + \lambda_n(\rho_w - \rho_n)K\vec{g})] = q_w.$$

$$\vec{v} = \vec{v}_a + \vec{v}_c$$



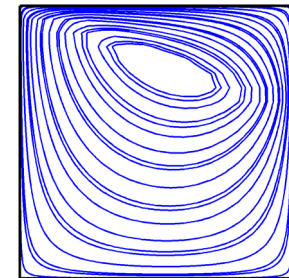
$$\nabla \cdot \vec{v} = q$$

$$\vec{v} + \lambda K [\nabla p - \omega(S)\vec{g}] = 0$$



$$\nabla \cdot \vec{v}_a = q$$

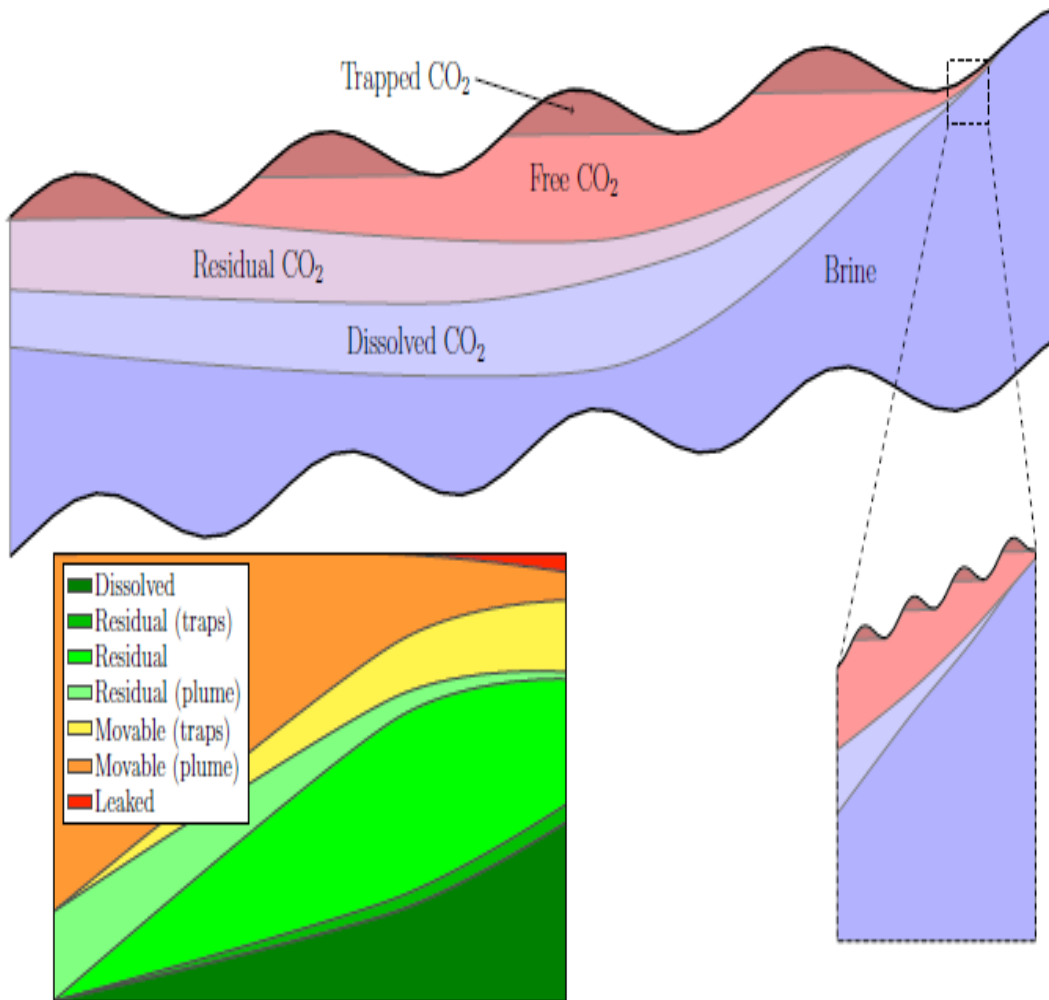
$$\vec{v}_a + \lambda K [\nabla p_a] = 0$$



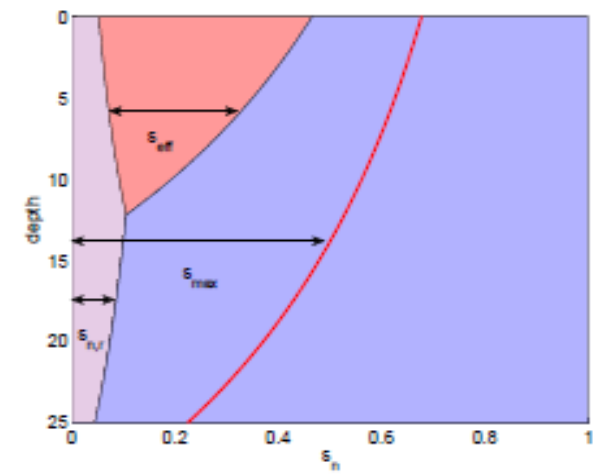
$$\nabla \cdot \vec{v}_c = 0$$

$$\vec{v}_c + \lambda K [\nabla p_c - \omega(S)\vec{g}] = 0$$

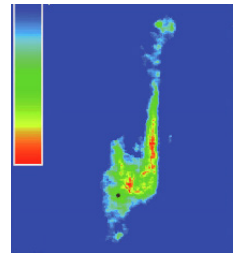
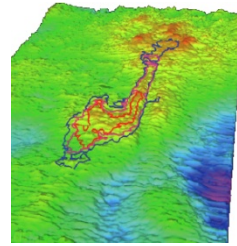
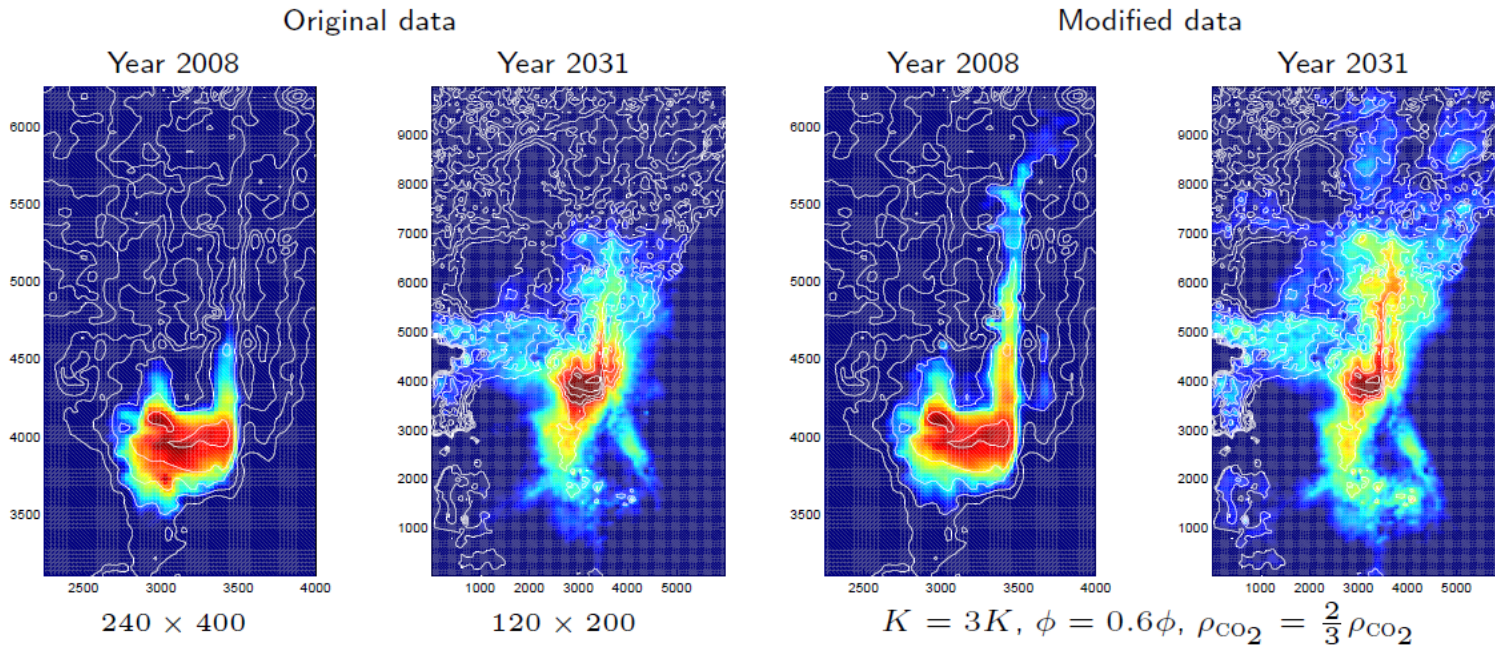
# Vertical equilibrium calculations: inventory



- Phase model:
  - incompressible
  - compressible
  - dissolution
- Relative permeability models
  - sharp interface
  - capillary fringe
  - detailed hysteric model
  - upscaling of subscale variations



# Simulation of Sleipner Layer 9

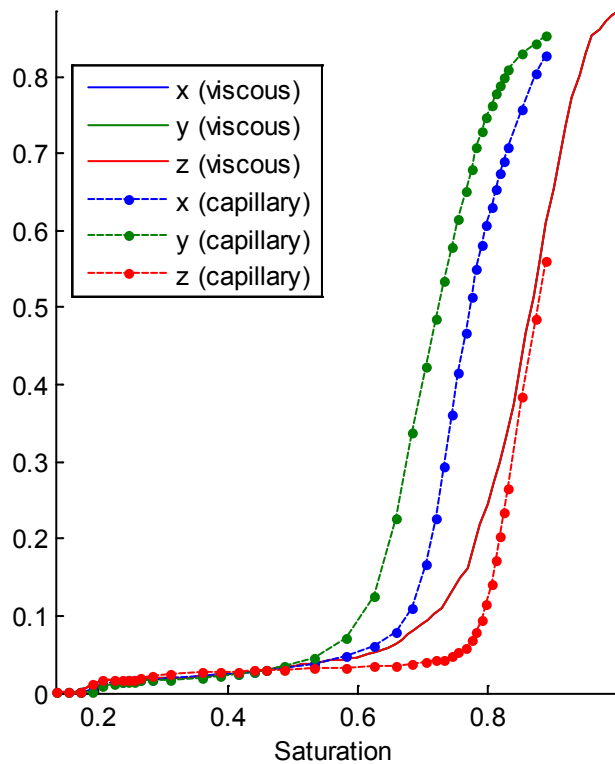


## Experience

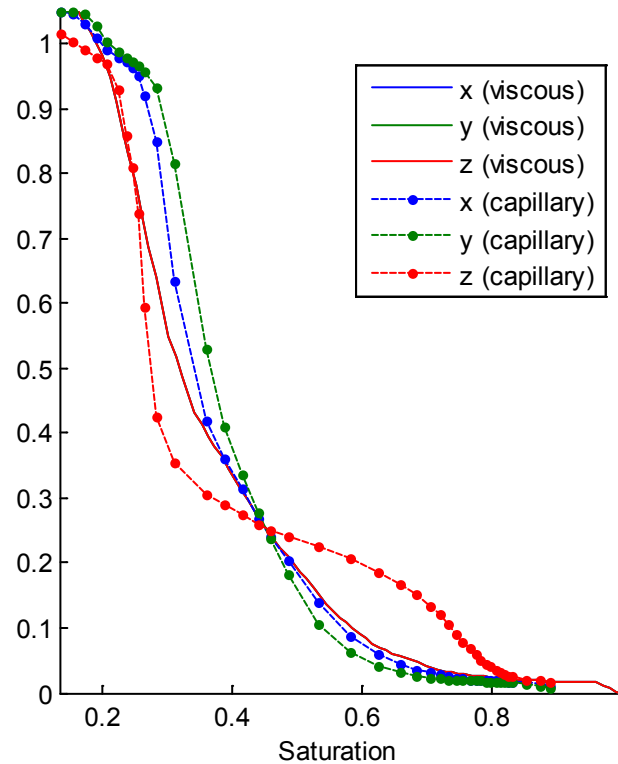
- Depth-integrated models are highly efficient and sufficiently accurate to predict long-term plume migration
- Often more accurate than unresolved 3D simulations
- Gravity dominated flow highly sensitive to small changes in top surface

# Relperm upscaling:

Relative permeability (Viscous/capillary limit), water phase



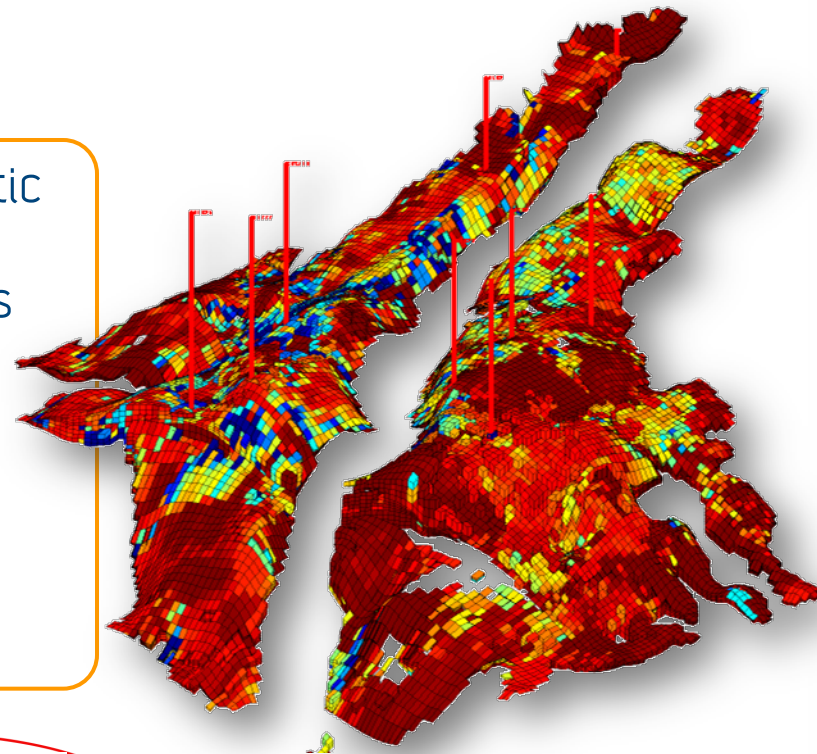
Relative permeability (Viscous/capillary limit), oil phase



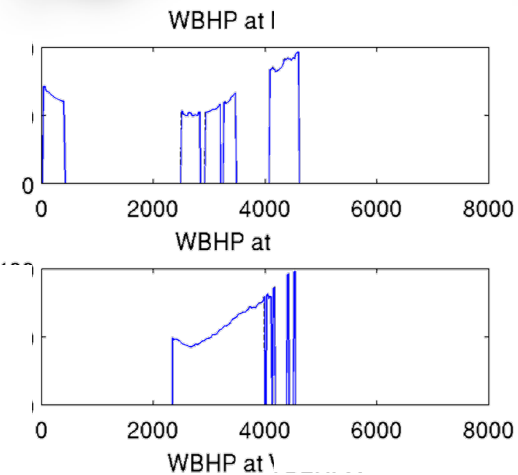
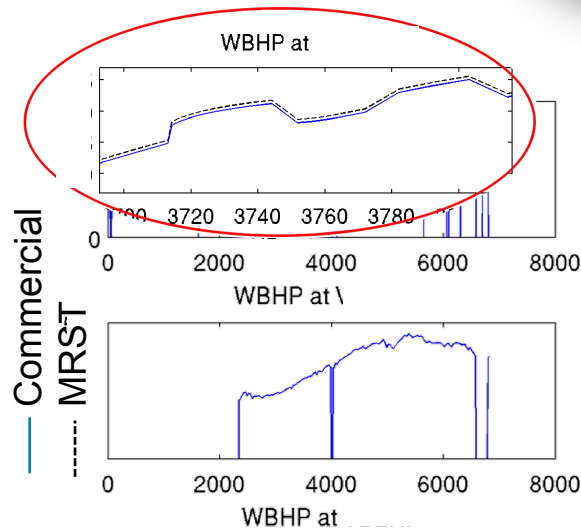


# Fully implicit code

- Based on automatic differentiation for automatic generation of Jacobians
- Gradients obtained through adjoint simulations
- Current models
  - Oil/water (+ polymer/surfactant)
  - Oil/gas
  - 3-phase black oil (live oil/dry gas)



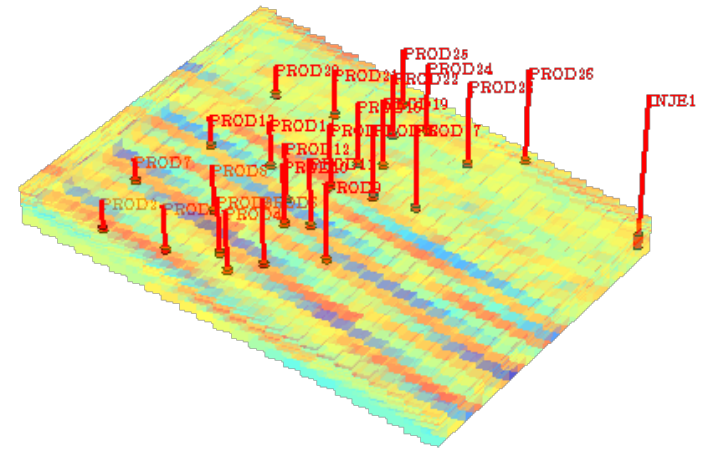
- Benchmarked against commercial simulator on real field black oil model
- ~20 years of historic data
- Virtually identical results



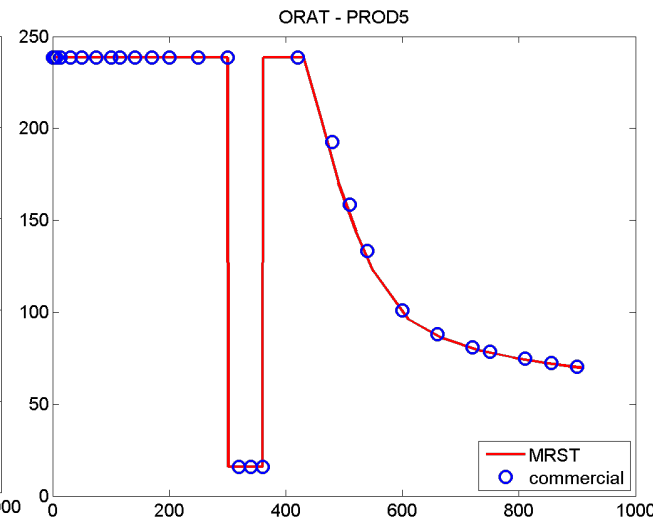
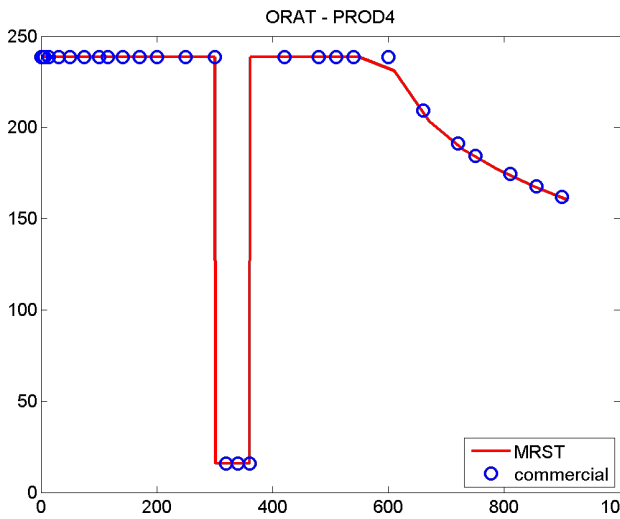
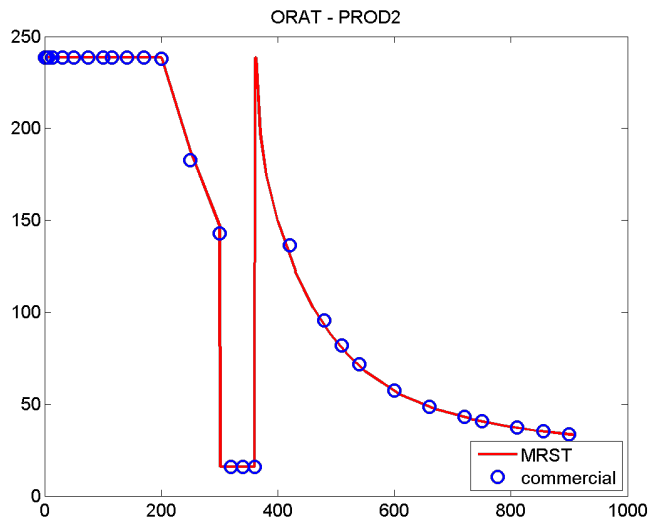
# Numerical Example (Black oil)

## SPE9 – 3 phase black-oil

- 1 water injector, rate-controlled – switches to bhp
- 25 producers, oil-rate controlled – most switch to bhp
- Appearance of free gas due to pressure drop
- Almost perfect match between MRST and commercial simulator

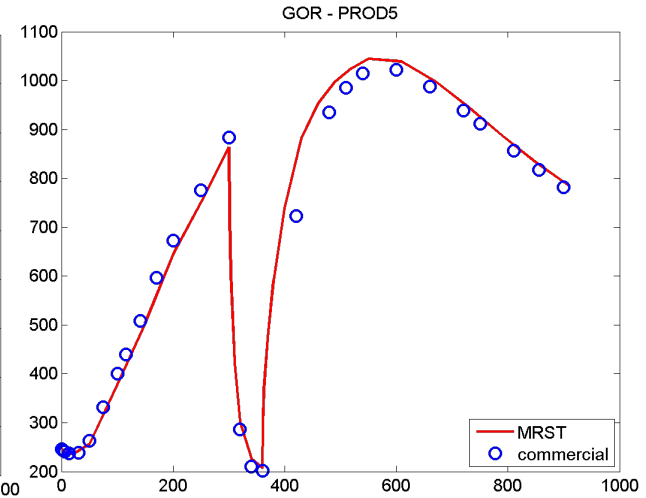
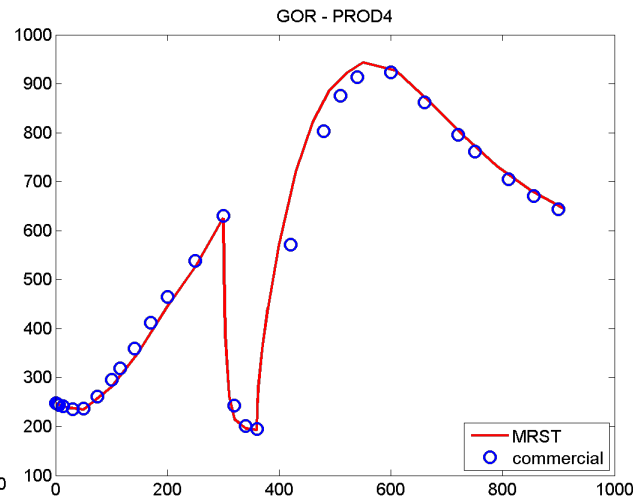
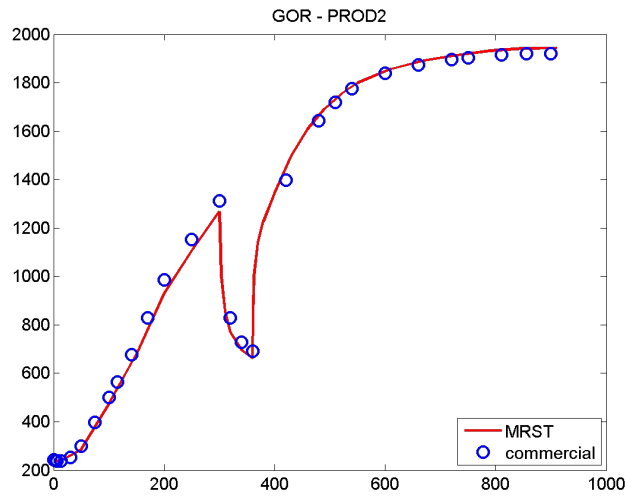


## Oil rates at producers 1, 3 and 4

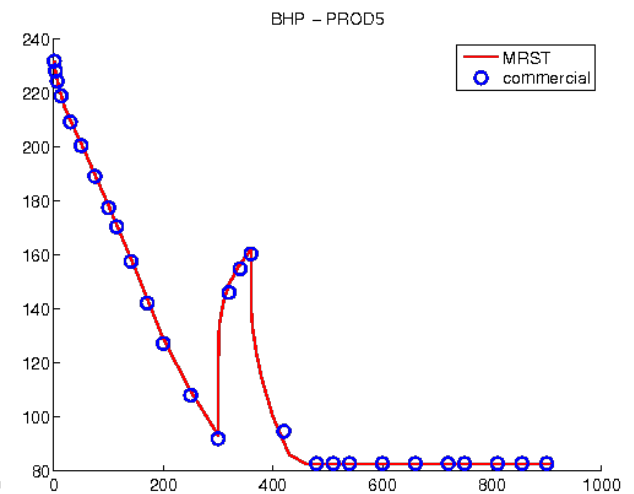
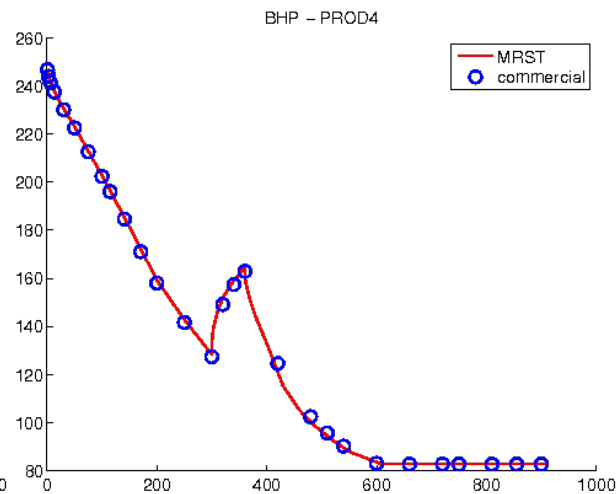
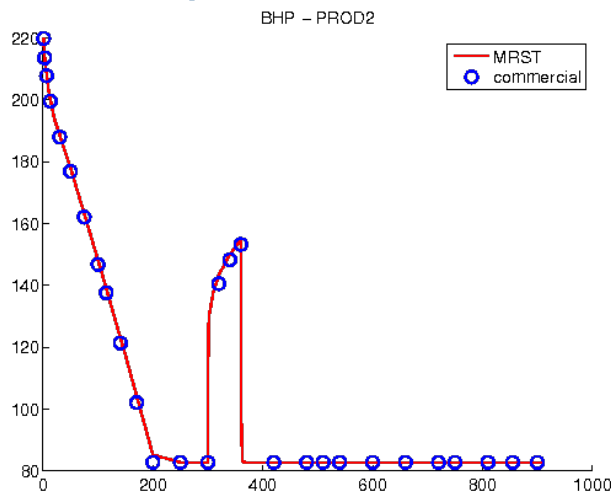


# Numerical Example (Black oil)

## GOR at a producer 1, 3 and 4



## BHP at producers 1, 3 and 4

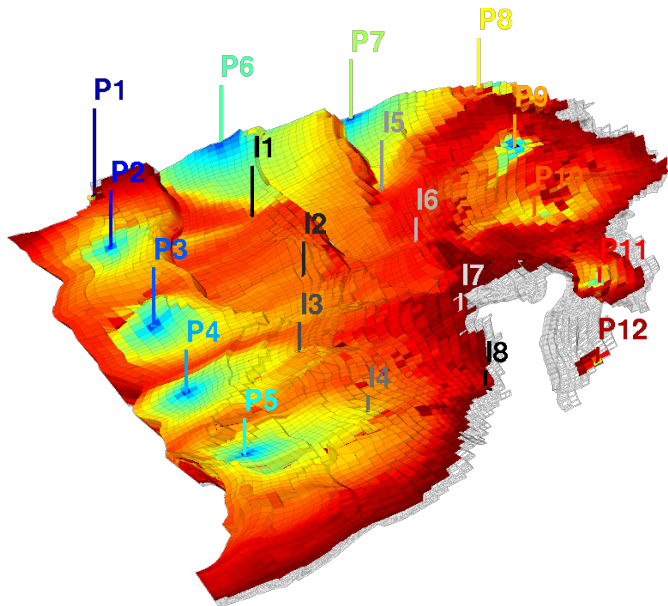


# Background: time-of-flight (TOF) and tracer equations

In this context: TOF and stationary tracer equations are solved efficiently after a single flow (pressure) solve:

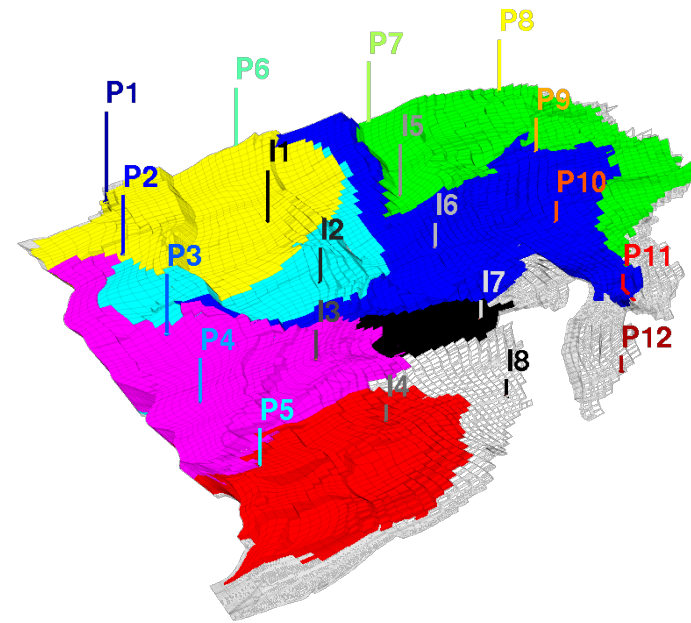
TOF: the times it takes for a *particle* to travel from

- injector to a given location
- a given location to a producer



Stationary tracer: portion of volume that *eventually* will

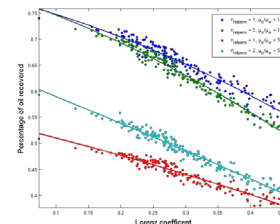
- arrive at a given producer
- come from a given injector



# Diagnostics based on time-of-flight (TOF) and tracers

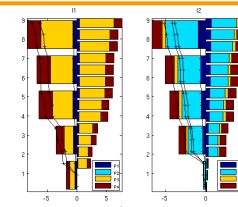
## Efficient ranking of geomodels

- Reduce ensemble prior to (upscaling and) full simulation
- Need measures that correlate well with e.g., recovery prediction



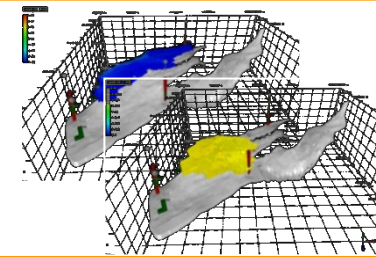
## Validation of upscaling

- Use allocation factors for assessing quality of upscaling



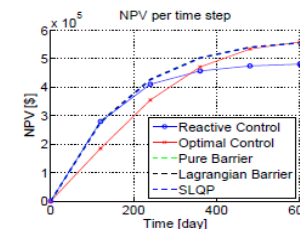
## Visualization

- See flow-paths, regions of influence, interaction regions etc
- Immediately see effect of new well-placements, model updates etc.

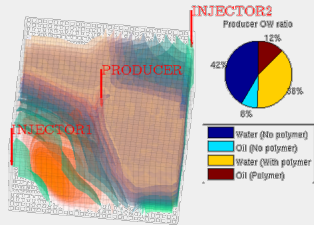


## Optimization

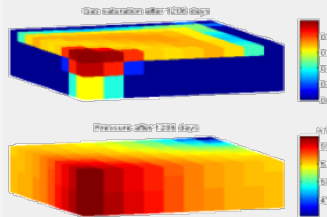
- Use as proxies in optimization to find good initial guesses.
- Need measures that correlate well to objective (e.g, NPV)



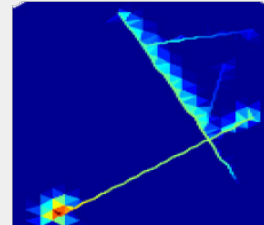
# MRST add-on modules



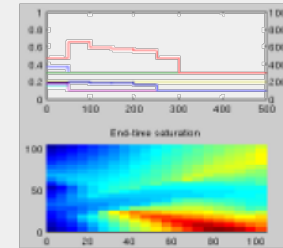
Fully implicit solvers  
(AD and gradients)



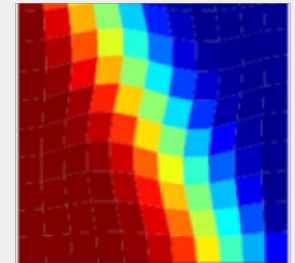
IMPES black-oil  
solvers



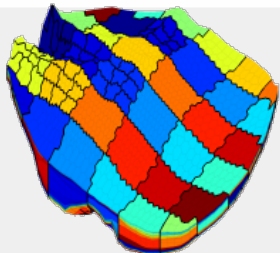
Discrete fracture  
models



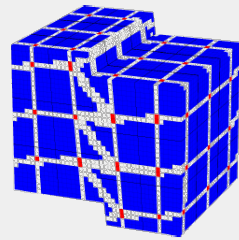
Adjoint methods



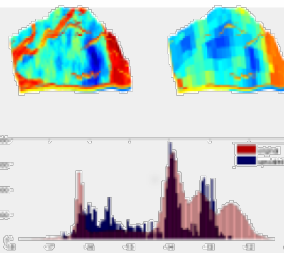
MPFA methods



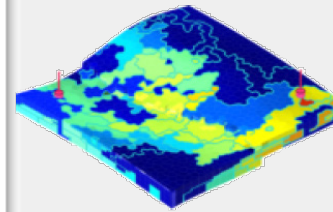
Multiscale mixed  
finite elements



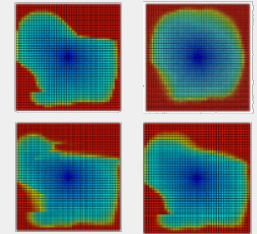
Multiscale finite  
volumes



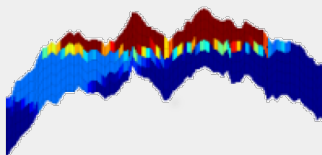
Single and two-  
phase upscaling



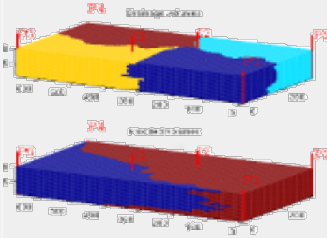
Grid coarsening



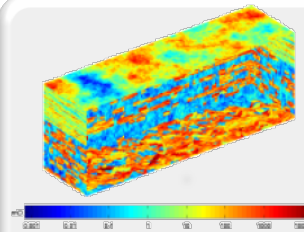
Ensemble Kalman  
filter



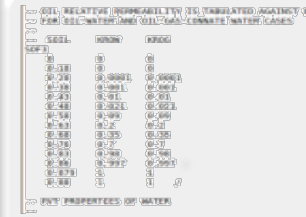
CO2 laboratory



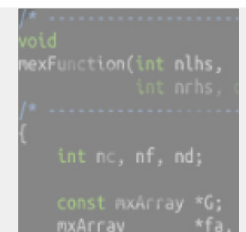
Flow diagnostics



Data sets  
(e.g. SPE 10)



Industry standard  
input formats

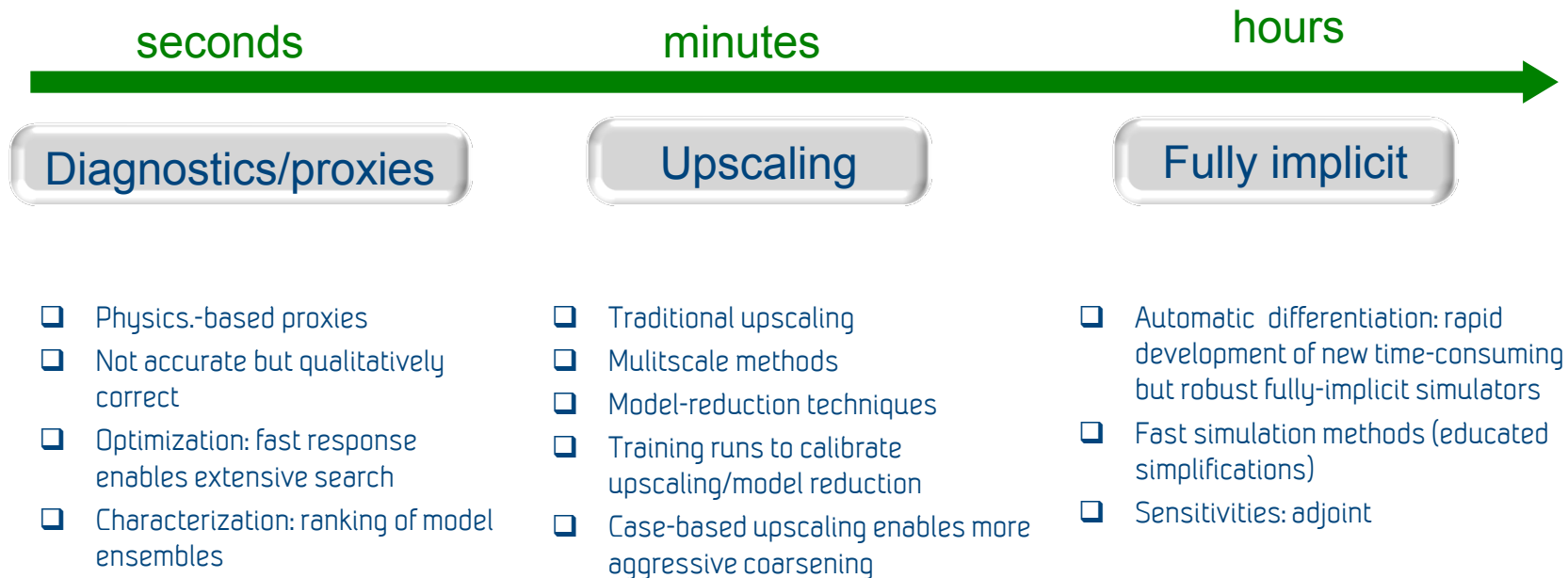


C-accelerated  
routines

# Fit-for-purpose reservoir simulation

Flexible simulators that are easy to extend with new functionality and scale with the requirement for the accuracy and computational budget

**accuracy + speed + robustness + access to gradients + model tuning**



# Black-oil model

$$\frac{d}{dt}(\phi b_o s_o) + \nabla \cdot (b_o v_o) - b_o q_o = 0$$

$$\frac{d}{dt}(\phi(b_g r_v s_g + b_o s_o)) + \nabla \cdot (b_g r_v v_g + b_o v_o) - (b_g r_v q_g + b_o q_o) = 0$$

$$\frac{d}{dt}(\phi(b_g s_g + b_o r_s s_o)) + \nabla \cdot (b_g v_g + b_o r_s v_o) - (b_g q_g + b_o r_s q_o) = 0$$

$$v_j = -\frac{k_{rj}}{\mu_j} K(\nabla p_j - \rho_j g \nabla z)$$

Water equation discretized in time:

$$\frac{V}{\Delta t}(\phi^{n+1} b_w^{n+1} s_w^{n+1} - \phi^n b_w^n s_w^n) + \nabla \cdot (b_w^{n+1} v_w^{n+1}) - b_w^{n+1} q_w^{n+1} = 0$$

Matlab code:

```
eqs{2}      = (pv/dt).*( pvMult.*bW.*sW - pvMult0.*f.bW(p0).*sW0 ) + s.div(bWvW);  
eqs{2}(wc) = eqs{2}(wc) - bWqW;
```