Convex hulls of planar random walks



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Joint work with Chang Xu, University of Strathclyde

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On each of n unsteady steps, a drunken gardener drops a seed. Once the flowers have bloomed, what is the minimum length of fencing needed to enclose the garden? What is its area?



Let Z_1, Z_2, \ldots be independent, identically distributed random vectors in \mathbb{R}^2 .

The Z_k will be the increments of the planar random walk S_n , $n \ge 0$, started at the origin in \mathbb{R}^2 , defined by

$$S_0=0, \hspace{0.2cm} ext{and} \hspace{0.2cm} S_n=\sum_{k=1}^n Z_k \hspace{0.2cm} ext{for} \hspace{0.1cm} n\geq 1.$$

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We are interested in the convex hull hull $(S_0, ..., S_n)$, i.e., the smallest convex set that contains $\{S_0, ..., S_n\}$.

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In particular, the $n \rightarrow \infty$ limit behaviour of the random variables

- L_n = the perimeter length of hull(S_0, \ldots, S_n);
- A_n = the area of hull(S_0, \ldots, S_n).

Standing assumption: $\mathbb{E}(||Z_1||^2) < \infty$ (sometimes more).

For the mean drift vector of the walk we write $\mu = \mathbb{E} Z_1$.

There is going to be a clear distinction between the zero drift case ($\mu = 0$) and the non-zero drift case ($\|\mu\| > 0$).

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For example, if

$$r_n := \inf\{\|x\| : x \in \mathbb{R}^2 \setminus \mathsf{hull}(S_0, \ldots, S_n)\},\$$

then, under mild conditions:

- the zero-drift walk visits all angles at arbitrary distances, so $r_n \rightarrow \infty$, i.e., the convex hull tends to the whole of \mathbb{R}^2 ;
- the walk with non-zero drift is transient in a limiting direction, so lim_{n→∞} r_n < ∞.

Some heuristics allow us to guess the typical scalings with *n* of our quantities of interest:

$$\begin{array}{c|c} \mu = 0 \quad \mu \neq 0\\ \hline L_n & n^{1/2} & n\\ A_n & n & n^{3/2} \end{array}$$

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We then seek distributional limit theorems. That is, for quantity Q_n is there a distributional limit for

$$n^{-\alpha}Q_n$$
 or $n^{-\beta}(Q_n-\mathbb{E}Q_n)$?

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Given some self-averaging, we might seek laws of large numbers: $n^{-\gamma}Q_n \longrightarrow$ non-zero constant, a.s.

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It turns out that each of the four cases in the table do satisfy a distributional limit theorem: one limit distribution is Gaussian; the other three are not.

Outline



- 2 Cauchy's formula
- **3** Scaling limits and Brownian hulls
- 4 Scaling limit in the non-zero drift case
- 5 Perimeter length in the non-zero drift case

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6 Concluding remarks

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Some history

Spitzer & Widom (1961) and Baxter (1961) showed that

$$\mathbb{E} L_n = 2 \sum_{k=1}^n \frac{1}{k} \mathbb{E} \| S_k \|.$$

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So, under mild conditions:

- the zero-drift case has $\mathbb{E} L_n \simeq \sqrt{n}$;
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So, under mild conditions:

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- the case with drift has $\mathbb{E} L_n \simeq n$.

Snyder & Steele (1993) showed that

$$\frac{1}{n} \mathbb{V}\mathrm{ar}(L_n) \le \frac{\pi^2}{2} \left(\mathbb{E} \, \|Z_1\|^2 - \|\mu\|^2 \right). \tag{1}$$

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Snyder & Steele deduced from (1) the strong law

$$\lim_{n\to\infty}n^{-1}L_n=2\|\mu\|, \text{ a.s.}$$

Some questions

The work of Snyder & Steele raised some natural questions.

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- Is *n* the correct order for $\mathbb{V}ar(L_n)$?
- Is there a distributional limit theorem for *L_n*?
- If so, is the limit distribution normal?

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The answers to these questions turn out be be essentially

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- yes, yes, no in the zero drift case, and
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First, we introduce an important tool from convex geometry: Cauchy's formula.

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Cauchy's formula

Let $\mathbf{e}_{\theta} = (\cos \theta, \sin \theta)$, unit vector in direction θ . Set

$$M_n(\theta) = \max_{0 \le k \le n} (S_k \cdot \mathbf{e}_{\theta}), \quad m_n(\theta) = \min_{0 \le k \le n} (S_k \cdot \mathbf{e}_{\theta}).$$

Cauchy's perimeter formula from convex geometry:

$$L_n = \int_0^\pi \left(M_n(\theta) - m_n(\theta) \right) \mathrm{d}\theta.$$



Cauchy's formula

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A first consequence: classical fluctuation theory for random walk on $\ensuremath{\mathbb{R}}$ gives

$$\mathbb{E} M_n(\theta) = \sum_{k=1}^n k^{-1} \mathbb{E} \left[(S_k \cdot \mathbf{e}_{\theta})^+ \right],$$

a formula attributed variously to Kac, Hunt, Dyson, and Chung, and which can be proved combinatorially, or analytically as a consequence of the Spitzer–Baxter–Pollaczek fluctuation theory identities. Then

$$\mathbb{E} L_n = \sum_{k=1}^n k^{-1} \mathbb{E} \int_0^{2\pi} |S_k \cdot \mathbf{e}_\theta| \mathrm{d}\theta = 2 \sum_{k=1}^n k^{-1} \mathbb{E} ||S_k||,$$

which is the Spitzer-Widom formula.

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The zero drift case

Suppose $\mu = 0$. The random walk has Brownian motion as its scaling limit.

So one would expect that the convex hull of the random walk is described in the limit by the convex hull of Brownian motion. The latter was studied by Lévy; more recently by El

Bachir (1983) and others.

We need to know a little about convex hulls of continuous paths, and need to set things up on the right space(s).



Consider continuous $f : [0, T] \to \mathbb{R}^d$ with f(0) = 0; say $f \in \mathcal{C}^0_d$. (*T* is not very important—enough to take $T \equiv 1$.)

With the supremum norm $\rho_{\infty}(f, g) = \sup_{x} ||f(x) - g(x)||$ we get a metric space $(\mathcal{C}_{d}^{0}, \rho_{\infty})$.

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The path segment (\equiv interval image) $f[0, t] = \{f(s) : s \in [0, t]\}$ is compact.

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That is, hull f[0, t] is an element of the metric space $(\mathcal{K}_d^0, \rho_H)$ of compact convex subsets of \mathbb{R}^d containing 0, with the Hausdorff metric.

Metric space $(\mathcal{K}^0_d, \rho_H)$ of compact convex subsets of \mathbb{R}^d containing 0, with the Hausdorff metric.

Given $K \in \mathcal{K}^0_d$ and r > 0, let $K^r := \{x \in \mathbb{R}^d : \rho(x, K) \le r\}$. For $A, B \in \mathcal{K}^0_d$,

$$\rho_{\mathcal{H}}(\mathcal{A}, \mathcal{B}) \leq r \quad \Leftrightarrow \quad \mathcal{A} \subseteq \mathcal{B}^r \text{ and } \mathcal{B} \subseteq \mathcal{A}^r.$$

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Lemma 1 For each t, the map $f \mapsto hull f[0, t]$ is a continuous function from (C^0_d, ρ_∞) to $(\mathcal{K}^0_d, \rho_H)$.

Scaling limit

Given random walk $S_n = \sum_{k=1}^n Z_k$ on \mathbb{R}^d , define

$$X_n(t) := n^{-1/2} \left(S_{\lfloor nt \rfloor} + (nt - \lfloor nt \rfloor) Z_{\lfloor nt \rfloor + 1} \right).$$

So for each $n, X_n \in C_d^0$. Let $b_t, t \ge 0$ denote standard Brownian motion on \mathbb{R}^d .

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Donsker's Theorem Suppose $\mathbb{E}(||Z_1||^2) < \infty$, $\mu = 0$, and $\mathbb{E}(Z_1Z_1^{\top}) = I$. Then $X_n \Rightarrow b$ in the sense of weak convergence on $(\mathcal{C}_d^0, \rho_\infty)$.

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Note hull $X_n[0, 1] = n^{-1/2}$ hull $(S_0, ..., S_n)$. Then with Lemma 1 and the continuous mapping theorem, we get:

Theorem 2 Under the same conditions, $n^{-1/2} hull(S_0, ..., S_n) \Rightarrow hull b[0, 1]$ in the sense of weak convergence on $(\mathcal{K}_d^0, \rho_H)$.

Now take d = 2.

The neatest way to define area \mathcal{A} and perimeter length \mathcal{L} of a set $K \in \mathcal{K}_2^0$ is:

$$\mathcal{A}(\mathcal{K}):=|\mathcal{K}|, ext{ and } \mathcal{L}(\mathcal{K}):=\lim_{r\downarrow 0}\left(rac{|\mathcal{K}^r|-|\mathcal{K}|}{r}
ight),$$

where $|\cdot|$ is Lebesgue measure; the limit exists by the Steiner formula of integral geometry.

In particular,

$$\mathcal{L}(K) = \begin{cases} \mathcal{H}_1(\partial K) & \text{if } \operatorname{int}(K) \neq \emptyset \\ 2\mathcal{H}_1(\partial K) & \text{if } \operatorname{int}(K) = \emptyset \end{cases}$$

where \mathcal{H}_1 is one-dimensional Hausdorff measure.

Lemma 3 The maps $K \mapsto \mathcal{A}(K)$ and $K \mapsto \mathcal{L}(K)$ are continuous functions from $(\mathcal{K}_2^0, \rho_H)$ to (\mathbb{R}_+, ρ) .

Note
$$\mathcal{L}(\operatorname{hull} X_n[0,1]) = \mathcal{L}(n^{-1/2} \operatorname{hull}(S_0, \dots, S_n)) = n^{-1/2} L_n;$$

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Theorem 4 Suppose $\mathbb{E}(||Z_1||^2) < \infty$, $\mu = 0$, and $\mathbb{E}(Z_1Z_1^{\top}) = I$. Then

$$n^{-1/2}L_n \stackrel{d}{\longrightarrow} \ell_1$$
, and $n^{-1}A_n \stackrel{d}{\longrightarrow} a_1$,

where $\ell_1 = \mathcal{L}(hull b[0, 1])$ and $a_1 = \mathcal{A}(hull b[0, 1])$ are the perimeter length and area, respectively, of the convex hull of planar Brownian motion run for unit time.

Some comments.

• The variables ℓ_1 and a_1 are positive and non-degenerate, and so non-Gaussian.

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Some comments.

- The variables ℓ_1 and a_1 are positive and non-degenerate, and so non-Gaussian.
- A formula of Letac and Takács (1978–80) says $\mathbb{E} \ell_1 = \sqrt{8\pi}$, while El Bachir (1983) showed $\mathbb{E} a_1 = \pi/2$, so (with a little extra work) we get in the zero-drift case that

$$n^{-1/2}\mathbb{E} L_n \to \sqrt{8\pi}$$
, and $n^{-1}\mathbb{E} A_n \to \frac{\pi}{2}$.

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$$n^{-1/2}\mathbb{E} L_n \to \sqrt{8\pi}, \text{ and } n^{-1}\mathbb{E} A_n \to \frac{\pi}{2}.$$

Under mild conditions, we also have that

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 Var $L_n \to$ Var ℓ_1 , and n^{-2} Var $A_n \to$ Var a_1 .

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 Goldman (1996) manages to do an explicit computation for the planar Brownian bridge, but it is tricky.

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Functionals

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- We'd like an exact formula for these variances.
 Goldman (1996) manages to do an explicit computation for the planar Brownian bridge, but it is tricky.
 Using Cauchy's formula and a formula of Rogers & Shepp (2006) on the correlation of the maxima of correlated one-dimensional Brownian motions, one can show

$$\mathbb{E}\left[\ell_1^2\right] = 4\pi \int_{-\pi/2}^{\pi/2} \mathrm{d}\theta \int_0^\infty \mathrm{d}u \cos\theta \frac{\cosh(u\theta)}{\sinh(u\pi/2)} \tanh\left(\frac{(2\theta+\pi)u}{4}\right),$$

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which gives $\mathbb{V}ar \ell_1 \approx 1.0350$.

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6 Concluding remarks

To get a non-degenerate scaling limit, we now must scale space by factor 1/n in the direction of the drift and by factor $1/\sqrt{n}$ in the orthogonal direction.

Specifically, let
$$\psi_n^{\mu}(x) = \left(\frac{x \cdot \hat{\mu}}{n \|\mu\|}, \frac{x \cdot \hat{\mu}_{\perp}}{\sqrt{n\sigma_{\mu_{\perp}}^2}}\right)$$
;
Here $\sigma_{\mu_{\perp}}^2 = \mathbb{E}\left[\left(Z \cdot \hat{\mu}_{\perp}\right)^2\right]$.

Let \tilde{b} denote the process on \mathbb{R}^2 given by $\tilde{b}(t) = (t, w(t))$, where *w* is standard Brownian motion on \mathbb{R} .

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The analogue of Donsker's theorem is as follows.

Suppose
$$\mathbb{E}(||Z_1||^2) < \infty$$
, $\mu \neq 0$, and $\sigma_{\mu_{\perp}}^2 > 0$. Then $\psi_n^{\mu}(X_n) \Rightarrow \tilde{b}$ weakly on $(\mathcal{C}_2^0, \rho_{\infty})$.



The affine map ψ_n^{μ} preserves the convex hull, so:

Theorem 5 Suppose $\mathbb{E}(||Z_1||^2) < \infty$, $\mu \neq 0$, and $\sigma_{\mu_{\perp}}^2 > 0$. Then $\psi_n^{\mu}(hull(S_0, \dots, S_n)) \Rightarrow hull \tilde{b}[0, 1]$ weakly on $(\mathcal{K}_2^0, \rho_H)$.

Theorem 5 Suppose $\mathbb{E}(||Z_1||^2) < \infty$, $\mu \neq 0$, and $\sigma_{\mu_{\perp}}^2 > 0$. Then $\psi_n^{\mu}(hull(S_0, \ldots, S_n)) \Rightarrow hull \tilde{b}[0, 1]$ weakly on $(\mathcal{K}_2^0, \rho_H)$.

Now note
$$\mathcal{A}(\psi_n^{\mu}(\text{hull}(S_0,\ldots,S_n))) = n^{-3/2} \|\mu\|^{-1} (\sigma_{\mu_{\perp}}^2)^{-1/2} A_n.$$

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Theorem 5 Suppose $\mathbb{E}(||Z_1||^2) < \infty$, $\mu \neq 0$, and $\sigma_{\mu_{\perp}}^2 > 0$. Then $\psi_n^{\mu}(hull(S_0, \ldots, S_n)) \Rightarrow hull \tilde{b}[0, 1]$ weakly on $(\mathcal{K}_2^0, \rho_H)$.

Now note
$$\mathcal{A}(\psi^{\mu}_{n}(\operatorname{hull}(S_{0},\ldots,S_{n}))) = n^{-3/2} \|\mu\|^{-1} (\sigma^{2}_{\mu_{\perp}})^{-1/2} A_{n}.$$

Theorem 6 Suppose $\mathbb{E}(||Z_1||^2) < \infty$, $\mu \neq 0$, and $\sigma_{\mu_{\perp}}^2 > 0$. Then $n^{-3/2} ||\mu||^{-1} (\sigma_{\mu_{\perp}}^2)^{-1/2} A_n \stackrel{d}{\longrightarrow} \tilde{a}_1,$ where $\tilde{a}_1 = \mathcal{A}(hull \tilde{b}[0, 1]).$

Some comments.

• The variable \tilde{a}_1 is positive and non-degenerate, and so non-Gaussian.

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- The variable \tilde{a}_1 is positive and non-degenerate, and so non-Gaussian.
- We can show that $\mathbb{E} \tilde{a}_1 = \frac{1}{3}\sqrt{2\pi}$, using an analogue of the Spitzer–Widom formula for areas due to Barndorff-Nielsen & Baxter (1963).

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- Under mild conditions, we also have that

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- We can show \mathbb{V} ar $\tilde{a}_1 > 0$.
- This scaling limit strategy is no use for the perimeter length L_n in the case μ ≠ 0, because ψ^μ_n does not act in a sensible way on lengths...

Outline

1 Introduction

- 2 Cauchy's formula
- **3** Scaling limits and Brownian hulls
- 4 Scaling limit in the non-zero drift case
- 5 Perimeter length in the non-zero drift case

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6 Concluding remarks

Perimeter length in the non-zero drift case

Theorem 7
Suppose
$$\mathbb{E}(||Z_1||^2) < \infty$$
 and $\mu \neq 0$. Then
$$\lim_{n \to \infty} \frac{1}{n} \mathbb{V}ar(L_n) = 4\sigma_{\mu}^2, \text{ where } \sigma_{\mu}^2 := \mathbb{E}[((Z_1 - \mu) \cdot \hat{\mu})^2].$$

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Theorem 8
Suppose
$$\mathbb{E}(||Z_1||^2) < \infty$$
, $\mu \neq 0$, and $\sigma_{\mu}^2 > 0$. Then
 $\frac{L_n - \mathbb{E}L_n}{\sqrt{\mathbb{V}arL_n}} \xrightarrow{d} \mathcal{N}(0, 1)$, and $\frac{L_n - \mathbb{E}L_n}{\sqrt{4n\sigma_{\mu}^2}} \xrightarrow{d} \mathcal{N}(0, 1)$.

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Remarks

(i) A little algebra shows $4\sigma_{\mu}^2 \leq 4(\mathbb{E} ||Z_1||^2 - ||\mu||^2)$.

Compare to the Snyder–Steele upper bound $n^{-1}\mathbb{V}$ ar $(L_n) \leq \frac{\pi^2}{2} (\mathbb{E} ||Z_1||^2 - ||\mu||^2).$

I.e., the constant in the Snyder–Steele upper bound is not sharp (4 $< \pi^2/2$).

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Compare to the Snyder–Steele upper bound $n^{-1} \mathbb{V}ar(L_n) \leq \frac{\pi^2}{2} (\mathbb{E} ||Z_1||^2 - ||\mu||^2).$

I.e., the constant in the Snyder–Steele upper bound is not sharp (4 < $\pi^2/2$).

(ii) $\sigma_{\mu}^2 = 0$ if and only if $Z_1 - \mu$ is a.s. orthogonal to μ .

This is the case, for instance, if Z_1 takes values (1, 1) or (1, -1), each with probability 1/2.

In this case Theorem 7 says that $\mathbb{V}ar(L_n) = o(n)$. The Snyder–Steele bound says only that $\mathbb{V}ar(L_n) \le \pi^2 n/2$. Simulations suggest that actually $\mathbb{V}ar(L_n) = O(\log n)$.

Degenerate example

 Z_1 takes values (1, 1) or (1, -1), each with probability 1/2.

This 2-dimensional walk can be viewed as a space-time diagram of a 1-dimensional simple symmetric random walk:



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Interesting combinatorics here, related to the Bohnenblust–Spitzer algorithm; see Steele (2002).

Behaviour of L_n for this case is an open problem.

Proof idea: Martingale differences

Let
$$\mathcal{F}_n = \sigma(Z_1, \ldots, Z_n)$$
. Define $D_{n,i} = \mathbb{E}[L_n - L_n^{(i)} | \mathcal{F}_i]$.

Lemma 9 (i) $L_n - \mathbb{E} L_n = \sum_{i=1}^n D_{n,i}$. (ii) $\mathbb{V}ar(L_n) = \sum_{i=1}^n \mathbb{E} (D_{n,i}^2)$.

Sketch proof.

As Z'_i is independent of \mathcal{F}_i , $\mathbb{E}[L_n^{(i)} | \mathcal{F}_i] = \mathbb{E}[L_n^{(i)} | \mathcal{F}_{i-1}] = \mathbb{E}[L_n | \mathcal{F}_{i-1}]$.

So $D_{n,i} = \mathbb{E}[L_n | \mathcal{F}_i] - \mathbb{E}[L_n | \mathcal{F}_{i-1}]$; a standard construction of a martingale difference sequence.

$$\sum_{i=1}^{n} D_{n,i} = \mathbb{E} \left[L_n \mid \mathcal{F}_n \right] - \mathbb{E} \left[L_n \mid \mathcal{F}_0 \right] = L_n - \mathbb{E} L_n.$$

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Now use orthogonality of martingale differences.

Aside: Upper bounds

Lemma 9 with the conditional Jensen inequality gives:

$$\operatorname{Var}(L_n) \leq \sum_{i=1}^n \mathbb{E}\left[(L_n - L_n^{(i)})^2\right].$$

A related result, a version due to Steele of the Efron–Stein inequality, says

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ar $(L_n) \leq \frac{1}{2} \sum_{i=1}^n \mathbb{E} [(L_n - L_n^{(i)})^2].$

It is this latter result that Snyder & Steele used to obtain their upper bound.

Cauchy formula revisited

We need to study $D_{n,i} = \mathbb{E} [L_n - L_n^{(i)} | \mathcal{F}_i].$

We have the Cauchy formula for L_n , and similarly for $L_n^{(i)}$, so that

$$L_n - L_n^{(i)} = \int_0^{\pi} \Delta_{n,i}(\theta) \mathrm{d}\theta,$$

where

$$\Delta_{n,i}(\theta) = \left(M_n(\theta) - M_n^{(i)}(\theta)\right) - \left(m_n(\theta) - m_n^{(i)}(\theta)\right),$$

where, similarly to before,

$$M_n^{(i)}(\theta) = \max_{0 \le k \le n} (S_k^{(i)} \cdot \mathbf{e}_{\theta}), \quad m_n^{(i)}(\theta) = \min_{0 \le k \le n} (S_k^{(i)} \cdot \mathbf{e}_{\theta}).$$

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We want to understand the relationship between $M_n(\theta)$, $m_n(\theta)$ and $M_n^{(i)}(\theta)$, $m_n^{(i)}(\theta)$ (resampled versions).

WLOG suppose $\mathbb{E} Z_1 = \mu \mathbf{e}_{\pi/2} = (\mathbf{0}, \mu)$, where $\mu > \mathbf{0}$.

Then for each fixed θ , $S_n \cdot \mathbf{e}_{\theta}$ is a one-dimensional random walk.

Indeed, $S_n \cdot \mathbf{e}_{\theta} = \sum_{k=1}^n Z_k \cdot \mathbf{e}_{\theta}$, with mean increment $\mathbb{E}[Z_1 \cdot \mathbf{e}_{\theta}] = \mathbb{E}[Z_1] \cdot \mathbf{e}_{\theta} = \mu \sin \theta$, which is positive for $\theta \in (0, \pi)$.

So, with high probability, the max $M_n(\theta)$ will be achieved nearby step *n* while the min $m_n(\theta)$ will be achieved nearby step 0.

To formalize this needs the strong law of large numbers, plus some care (need some uniformity in θ).

Lemma 10 With high probability, $\Delta_{n,i}(\theta) \approx (Z_i - Z'_i) \cdot \mathbf{e}_{\theta}$ for (almost) all *i*.

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Sketch proof.

With high probability, the max $M_n(\theta)$ will be achieved nearby step n while the min $m_n(\theta)$ will be achieved nearby step 0.

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Resampling increment *i* shifts the whole subsequent trajectory in \mathbb{R}^2 by $Z'_i - Z_i$.

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It follows that for *i* neither too close to 0 nor too close to *n*, for each θ , on resampling the maxima $M_n(\theta)$ and $M_n^{(i)}(\theta)$ are achieved at the same index. Similarly for the minima.

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So $m_n(\theta) = m_n^{(i)}(\theta)$, and

$$M_n^{(i)}(\theta) = M_n(\theta) + (Z'_i - Z_i) \cdot \mathbf{e}_{\theta}.$$

See the picture!

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See the picture!

Finishing the proofs

Up to technical details, we sketched the fact that

$$D_{n,i} = \mathbb{E} \left[L_n - L_n^{(i)} \mid \mathcal{F}_i \right] \approx \int_0^{\pi} \mathbb{E} \left[(Z_i - Z'_i) \cdot \mathbf{e}_{\theta} \mid \mathcal{F}_i \right] \mathrm{d}\theta.$$

Here Z_i is \mathcal{F}_i -measurable and Z'_i is independent of \mathcal{F}_i , so

$$\mathbb{E}\left[\left(Z_i-Z_i'\right)\cdot\mathbf{e}_{\theta}\mid\mathcal{F}_i\right]=\left(Z_i-\mu\right)\cdot\mathbf{e}_{\theta}.$$

Doing the integral gives

$$D_{n,i} = \mathbb{E}\left[L_n - L_n^{(i)} \mid \mathcal{F}_i\right] \approx 2(Z_i - \mu) \cdot \hat{\mu}.$$

Finishing the proofs

Formalizing the analysis we get:

Theorem 11 Suppose $\mathbb{E}(||Z_1||^2) < \infty$ and $\mu \neq 0$. Then $n^{-1/2} \left| L_n - \mathbb{E}L_n - 2\sum_{i=1}^n (Z_i - \mu) \cdot \hat{\mu} \right| \to 0$, in L^2 .

So, perhaps surprisingly, $L_n - \mathbb{E} L_n$ is well-approximated by a sum of i.i.d. random variables.

Theorems 7 and 8 now follow from Theorem 11 easily enough.

Outline

1 Introduction

- 2 Cauchy's formula
- 3 Scaling limits and Brownian hulls
- 4 Scaling limit in the non-zero drift case
- 5 Perimeter length in the non-zero drift case

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6 Concluding remarks

Concluding remarks

The assumption that the Z_i are identically distributed is not essential to the main argument.

For example, let $G_n = \frac{1}{n+1} \sum_{i=0}^n S_i = \sum_{i=1}^n \frac{n+1-i}{n+1} Z_i$.

 G_0, G_1, \ldots is the centre-of-mass process associated with S_0, S_1, \ldots

By convexity, $hull(G_0, \ldots, G_n) \subseteq hull(S_0, \ldots, S_n)$.

If L_n^G is the perimeter length of hull(G_0, \ldots, G_n), then the statement of Theorem 11 applies to L_n^G in place of L_n with $\frac{n+1-i}{n+1}Z_i$ in place of Z_i .

In particular, the analogue of Theorem 7 says that

$$\lim_{n\to\infty}\frac{1}{n}\mathbb{V}\mathrm{ar}\left(\mathcal{L}_n^{\mathrm{G}}\right)=4\sigma_{\mu}^2/3,$$

where σ_{μ}^2 is the same as before.

Concluding remarks

A picture:



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