M-Theory and Matrix Models

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Introduction

- Why M-Theory?
- Whats new in M-Theory
- The M5-Brane

2 My Research

- Matrix Models in a Large Flux
- Representation Theory
- More Matrix Models
- Multiple D4's and M5's

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Why M-Theory? Whats new in M-Theory The M5-Brane

Superstrings

There are 5 different superstring theories which describe open and closed strings



Why M-Theory? Whats new in M-Theory The M5-Brane

D-Branes

- There are dualities between the 5 different theories, for example T-duality describes how we can relate IIA to IIB theories.
- Open strings have end points that live on D-branes
- D-p-branes are (p+1)-dimensional objects that move through D dimensional spacetime, they can have open/closed bc's

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Why M-Theory? Whats new in M-Theory The M5-Brane

D-Branes

 A bosonic brane action would typically look like the following

$$S_{DBI} = T_p \int \mathrm{d}^{p+1} \sigma \sqrt{-\mathrm{det} P(G + 2\pi lpha' F)}$$

These branes have a tension which is some power of g_s and l_s

 A p-brane couples to a p+1 form potential, you can add these potentials to the D-brane action

$$S = S_{DBI} + \int A_{p+1}$$

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Why M-Theory? Whats new in M-Theory The M5-Brane

The Discovery of M-Theory

- M-theory was discovered as a strongly coupled limit to IIA theory
- This comes from a Kaluza Klein argument where

$$M_{11}^2 = -p_m p^m = 0, \quad p_{11} = N/R_{11},$$

where M_{11} is the mass of the graviton in 11D SUGRA/M-Theory

• The D0-brane has mass $(I_s g_s)^{-1}$ and KK modes have N units of U(1) charge

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The Discovery of M-Theory

- Matching up the two masses gives $R_{11} = I_s g_s$, $g_s \to \infty$ gives us extra large dimension
- Eleven dimensional SUGRA has a 3-form potential
- M-theory has the same potential, yielding an electrically coupled M2 and a magnetically coupled M5 brane.
- Worldvolume theories for these branes would be 3 and 6 dimensional CFTs

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Why M-Theory? Whats new in M-Theory The M5-Brane

AdS/CFT... Because no strings talk is complete without it

- We can look at the AdS/CFT correspondence here too!
- The correspondence tells us that a stack of M2-branes has bulk background $AdS_4 \times S^7$, this was known from the 11-dimensional supergravity result of the M2.
- Bagger and Lambert discovered the theory of multiple M2-branes in 2007
- In 11 dimensions $\mathcal{N}=8$ is the maximal supersymmetry we could have.

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Why M-Theory? Whats new in M-Theory The M5-Brane

Whats new in M-Theory

- BL proposed that the $\mathcal{N} = 8$, SO (8)_R theory of multiple M2 branes is a *Chern-Simons gauge theory* of level k.
- The revolutionary idea was that the scalars X^I took values in a 3-algebra [·, ·, ·] : V × V × V → V.

$$egin{aligned} \mathcal{L} &= - \, rac{1}{2} D^\mu X^I D_\mu X^I + rac{i}{2} ar{\Psi} \Gamma^\mu D_\mu \Psi + rac{i}{4} ar{\Psi} \Gamma_{IJ} [X^I, X^J, \Psi] \ &- V(X) + rac{k}{2} arepsilon^{\mu
u\lambda} (ilde{A}_\mu \partial_
u ilde{A}_\lambda + rac{2}{3} ilde{A}_\mu ilde{A}_
u ilde{A}_\lambda) \end{aligned}$$

where

$$V(X) = \frac{1}{12} \operatorname{Tr}([X', X^J, X^K], [X', X^J, X^K])$$

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Why M-Theory? Whats new in M-Theory The M5-Brane

Whats new in M-Theory

• Using the notation $\tilde{A}_{\mu}{}^{c}{}_{d} = A_{\mu ab} f^{abc}{}_{d}$, we can write the susy transforms:

$$\begin{split} \delta X^{I} &= i \bar{\epsilon} \Gamma^{I} \Psi \\ \delta \Psi &= D_{\mu} X^{I} \Gamma^{\mu} \Gamma^{I} \epsilon - \frac{1}{6} [X^{I}, X^{J}, X^{K}] \Gamma^{IJK} \epsilon \\ \delta \tilde{A}_{\mu} &= i \bar{\epsilon} \Gamma_{\mu} \Gamma_{I} X^{I} \Psi, \end{split}$$

- M2-branes are 1/2 BPS and so we choose $\Gamma^{012}\epsilon = \epsilon$
- Let's discuss a bit more about Lie 3-algebras

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Whats new in M-Theory

A Lie 3-algebra is a vector space with a basis
 T^a, a = 1,..., N endowed with a trilinear product

 $[T^a, T^b, T^c] = f^{abc}{}_d T^d,$

- We can derive a generalised Jacobi Id called the fundamental identity by using a derivation on this product.
- The N = 8 theory required f^{abc}_d = f^[abc]_d, only solution prop to e^{abcd}. So BL theory has an SO(4) ≅ SU(2) × SU(2) gauge symmetry.
- Reformulate as a bi-fundamental gauge theory.

Why M-Theory? Whats new in M-Theory The M5-Brane

Whats new in M-Theory

- BL theory only describes **two** coincident branes! Also the Chern-Simons level is restricted to k = 1, 2
- ABJM wrote down a *bifundamental* SCCS matter theory which has *only* $\mathcal{N} = 6$ susy, but this described *N* coincident branes for any integer *k*.
- The moduli space of the ABJM theory is ℝ⁸/ℤ_k, k ∈ ℤ for a U(N) × U(N) gauge theory.
- ABJM theory does not need to use 3 algebras, the potential of the theory is calculated from a superpotential in the usual manner.

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Why M-Theory? Whats new in M-Theory The M5-Brane

Whats new in M-Theory

- It is possible to enhance the N = 6 ABJM theory to get the full N = 8 theory by the use of monopole operators.
- The M2-brane picture is pretty well understood now.
- On to the M5-brane...

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Why M-Theory? Whats new in M-Theory The M5-Brane

Whats new in M-Theory

- Much less is known about the M5-brane.
- Gravity side has $AdS_7 \times S^4$.
- Field theory is given by an $\mathcal{N} = (2,0)$ supermultiplet $(B_{\mu\nu}, X^I, \Psi), I = 6, ..., 10.$
- Difficult to write a gauge kinetic term for the field strength $H_3 = dB_2$.
- $\int_{\Sigma_6} H_3 \wedge H_3 = 0$
- Possible to write down a non-covariant action for a single M5-brane which is gauge fixed, (PST 1997).

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Matrix Models in a Large Flux Representation Theory More Matrix Models Multiple D4's and M5's

Introduction

- Expect Riemannian geometry to break down at Plank scales.
- Spacetime becomes quantised and coordinates become quantum operators.
- Open strings ending on D-branes with a *B*-field turned on give a noncommutative geometry

$$[X^{\mu}, X^{\nu}] = i\theta^{\mu\nu}.$$

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Introduction

 M2-branes end on M5-branes. Has been shown that M5-brane geometry in the presence of 3-form C-field is

$$[\mathbf{X}^{\mu},\mathbf{X}^{\nu},\mathbf{X}^{\lambda}]=i\theta^{\mu\nu\lambda}.$$

• Lie 3-bracket given by fundamental identity:

[[f, g, h], k, l] = [[f, k, l], g, h] + [f, [g, k, l], h] + [f, g, [h, k, l]]

 Constraint is too strong and we do not understand the representation theory.

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Introduction

• We propose the 'Quantum Nambu Bracket':

$$[f, g, h] := fgh + ghf + hfg - fhg - gfh - hgf$$

- We will show that the quantum geometry $[X^{\mu}, X^{\nu}, X^{\lambda}] = i\theta^{\mu\nu\lambda}$ is given by the QNB.
- Refer to the above geometry as the 'Quantum Nambu Geometry'.

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A II B Background

- Consider background $AdS_5 \times S^5$.
- Background has a dilaton, axion, C₂, C₄.
- Turn on 3-form Flux for a D1-brane in the AdS₅ sector only.
- It has been shown that consistency requires the spacetime to take the form

 $\mathbb{R}^3 \times AdS_2 \times S^5.$

• Note for later that the RR 2-form potential is given by

$$C_2 = f \epsilon_{ijk} X^i dX^j dX^k.$$

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D1 MM in a Large Flux

- *N* parallel D1-branes action given by DBI + CS action
- Myers proposed a generalisation of the CS term given by

$$S_{CS} = \mu_1 \int \mathrm{Tr} P(e^{i\lambda \mathbf{i}_{\Phi} \mathbf{i}_{\Phi}} \sum_n C_n) e^{\lambda F}.$$

• Here $\mu_1 = 1/(g_s 2\pi \alpha')$, $\lambda = 2\pi \alpha'$ and $X' = 2\pi \alpha' \Phi'$. Our background has B = 0.

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D1 MM in a Large Flux

• Expanding S_{CS} gives

$$S_{CS} = \mu_1 \int \text{Tr}[\lambda F_{\chi} + C_2 + i\lambda^2 F i_{\Phi} i_{\Phi} C_2 + i\lambda i_{\Phi} i_{\Phi} C_4 - \frac{\lambda^3}{2} F i_{\Phi}^4 C_4]$$

$$:= S_{\chi} + S_{C_2} + S_{C_4}$$

 We will see only S_{C2} contributes in the double scaling limit of a large field strength.

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D1 MM in a Large Flux

Substituing our expression for C₂ gives

$$S_{C_2}/\mu_1 = f \int d^2 \sigma \operatorname{Tr}(\frac{1}{2} \epsilon_{ijk} X^i D_\alpha X^j D_\beta X^k \epsilon^{\alpha\beta}) + f \int d^2 \sigma \operatorname{Tr}(i F X^i X^j X^k \epsilon_{ijk})$$

• Here $\alpha = 0, 1, i = 2, 3, 4, i' = 5, 6, 7, 8, 9.$

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D1 MM in a Large Flux

By including a YM term (from DBI), can find EOM

contribution of:	S_{C_2}	$i_{\Phi}^2 C_4$	i ⁴ _Φ C ₄
EOM of X ⁱ :	$O(\frac{f}{\alpha'})$	$O(\frac{1}{f \alpha'^2})$	0
EOM of $X^{i'}$:	0	$O(\frac{1}{f^4 \alpha'^2})$	$O(\frac{1}{f^4 \alpha'^2})$

• The YM term is given by

$${\cal S}_{YM}/\mu_1 = lpha'^2 \int \sqrt{-\det G_{lphaeta}} \; {\cal F}_{lphaeta} {\cal F}_{lpha'eta'} {\cal G}^{lphalpha'} {\cal G}^{etaeta'}$$

So for large *f* and taking *ϵ* → 0, we have a double scaling limit

$$\alpha' \sim \epsilon,$$

 $f \sim \epsilon^{-a}, \quad a > 0.$

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D1 MM in a Large Flux

• Choice
$$1/2 < a < 2$$
 gives us

$$\lim_{\epsilon\to 0} S_{D1} = S_{C_2}.$$

 So the double scaling limit gives us the low energy action for N D1-branes in a large F₃ background.

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Equations of Motion and Quantum Nambu Geometry

$$\begin{split} \varepsilon^{\alpha\beta}\varepsilon_{ijk}[X^{j},D_{\beta}X^{k}X^{i}] + \varepsilon^{\alpha\beta}\varepsilon_{ijk}[D_{\beta},X^{i}X^{j}X^{k}] &= 0, \\ \frac{3}{2}\varepsilon_{ijk}D_{\alpha}X^{j}D_{\beta}X^{k}\varepsilon^{\alpha\beta} + \varepsilon_{ijk}[F;X^{j},X^{k}]' &= 0, \end{split}$$

- [A; B, C]' := [B, C]A + A[B, C] + BAC CAB
- $\operatorname{Tr}[A, B, C]D = \operatorname{Tr}[D; B, C]'A$, in analogy to the relation $\operatorname{Tr}D[A, B] = \operatorname{Tr}[D, A]B$.

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Equations of Motion and Quantum Nambu Geometry

Solutions:

- $D_{\alpha}X^i = 0$,
- *F* = 0,
- [Xⁱ, X^j] = iθε^{ij} is allowed but there is another more interesting solution,
- $[X^i, X^j, X^k] = i\theta\epsilon^{ijk}$

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A Representation with Z_3 Symmetry

- Can construct a rep with 'raising/lowering' operators.
- Look at a different rep, want to consider reps on a 3-dim real space.

$$[X^1, X^2, X^3] = i\theta$$

Introduce a unitary operator,

$$\begin{array}{ll} U|\omega\rangle = & |\rho^2\omega\rangle, \quad \rho^3 = \mathbf{1} \in \mathbb{C} \\ U^{\dagger}|\omega\rangle = & |\rho\omega\rangle, \end{array}$$

and assuming

$$X^{1}|\omega
angle = (\omega + a)|\omega + 1
angle,$$

one obtains

$$egin{aligned} U^{\dagger}X^{1}U|\omega
angle &=& (
ho^{2}\omega+a)|\omega+
ho
angle, \ U^{\dagger^{2}}X^{1}U^{2}|\omega
angle &=& (
ho\omega+a)|\omega+
ho^{2}
angle \ angle =& egin{aligned} &(
ho\omega+a)|\omega+
ho^{2}
angle \ angle &=& egin{aligned} &($$

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M-Theory and Matrix Models

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A Representation with Z_3 Symmetry

 If the fields X¹, X² and X³ are unitarily related to each other by

$$egin{array}{rcl} X^2 = & U^\dagger X^1 U, \ X^3 = & U^\dagger X^2 U, \end{array}$$

then

$$\begin{array}{ll} X^{1}|\omega\rangle & = (\omega + a)|\omega + 1\rangle, \\ X^{2}|\omega\rangle & = \rho^{2}(\omega + a\rho)|\omega + \rho\rangle, \\ X^{3}|\omega\rangle & = \rho(\omega + a\rho^{2})|\omega + \rho^{2}\rangle \end{array}$$

and we see that

$$[X^1,X^2,X^3]|\omega
angle=3(a^2-a)(
ho-
ho^2)|\omega
angle$$

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II B Matrix Model

- Expand around the QNG and examine emerging gauge theories
- Denote the covariant derivative $iD^{\alpha} = i\partial^{\alpha} + A^{\alpha}$, $\alpha = 0, 1$ as

$$iD^{lpha} = X^{lpha}$$

• We can show that S_{D1} can be written as

$$\mathcal{S}_{D1} = rac{f}{g_s l_s^2} \int d^2 \sigma \, \mathrm{Tr} X^a X^b X^c X^d X^e \epsilon_{abcde},$$

• Large *N* reduction gives

$$S_{IIB} = \frac{f}{g_s l_s^2} \operatorname{Tr} X^a X^b X^c X^d X^e \epsilon_{abcde}, \quad a, b, c, d, e = 0, 1, 2, 3, 4.$$

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M-Theory Matrix Model

- IIB background invariant under KV ∂_i , i = 2, 3, 4.
- Compactify x² on circle of radius R₂ and T-dualize

$$\textit{S}^1 \times \mathbb{R}^2 \times \textit{AdS}_2 \times \textit{S}^5$$

- D1-brane \rightarrow D2-brane under this T-duality
- In IIA theory with D2-brane action

$$S_{D2}=rac{f}{g_{s}l_{s}}\int d^{3}\sigma X^{a}X^{b}X^{c}X^{d}X^{e}\epsilon_{abcde}$$

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M-Theory Matrix Model

- In II A theory, we have D0, D2, D4, D6, D8-branes.
- M-theory on a circle in the infinite momentum frame gives us only states with positive D0-charge
- Under the same double scaling, we are left with

$$S_{D0} = \frac{1}{g_s l_s} \int P(C^{(1)}) = \frac{f}{g_s l_s} \int dt \epsilon_{ij} X^i D_t X^j, \quad i, j = 3, 4$$

 BFSS model describes M-theory in infinite momentum frame using QM - D0-branes

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M-Theory Matrix Model

- D2-action describes D0-branes too
- Dimensionally reduce D2-action
- In the large flux curved background, M-theory action is

$$S_{M} = \frac{if}{g_{s}l_{s}} \int dt \operatorname{Tr} D_{t} X^{b} X^{c} X^{d} X^{e} \epsilon_{bcde}, \quad b, c, d, e = 1, 2, 3, 4$$

where $X^0 = -iD_t$

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II A Matrix Model

- Write constants in terms of M-theory radius R_{11} , compactify on x^2 , perform 11-2 flip
- The flip changes the M-theory direction on the torus. All this means is

$$R_2 = g_s I_s, \qquad R_{11} = N$$

with lightcone momentum $p_+ = 1$

• Obtain the IIA matrix model

$$S_{IIA} = rac{f}{N} \int d^2 \sigma \, {
m Tr} X^a X^b X^c X^d X^e \epsilon_{abcde},$$

where a, b, c, d, e = 0, 1, 2, 3, 4

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Multiple D4-branes

Consider a fluctuation around the QNG

$$X^{i} = x^{i} \mathbf{1}_{K \times K} + A^{i}(\sigma, x^{j})$$

The IIA action becomes

$$\mathcal{S}_5 = rac{f}{N} \int_{\Sigma_5} \mathrm{tr} X^a X^b X^c X^d X^e \epsilon_{abcde}$$

where $\int_{\Sigma_5} = \int d^2 \sigma \int_X$ and \int_X is an integral on QNG

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Multiple D4-branes

- Argue this describes K parallel D4-branes
- Introduce 3-form H

$$\begin{array}{lll} H^{abc} & = & -i[X^a, X^b, X^c], \\ H^{de5} & = & -i[X^d, X^e], & a, b, c, d, e = 0, 1, 2, 3, 4, \end{array}$$

where

$$H^{*\mu
u\lambda} := rac{1}{6\sqrt{-g}} \epsilon^{\mu
u\lambda
holphaeta} H_{
holphaeta}$$

is the Hodge dual of $H_{\rho\alpha\beta}$.

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Multiple D4-branes

Claim

$$\mathcal{S}_5 = \int_{\Sigma_5} \mathrm{tr} \mathcal{H}^{abc} \mathcal{H}^{de5} \ \epsilon_{abcde}$$

describes the D4's. To see the connection, we examine an abelian M5-brane theory and dimensionally reduce

 PST wrote the action for a single M5-brane in 6d by coupling to a scalar.

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Multiple D4-branes

Gauge fixing gives us the following non-covariant action

$$\mathcal{S}_{PST} = -rac{1}{4} imes \int d^6 \sigma \left(rac{1}{6} \epsilon_{abcde} H^{abc} H^{de5} + H^{*ab5} H^{*}_{ab5} \sqrt{-g}
ight)$$

- After dim reduction on x⁵, 1st term is precisely our action!
- 2nd term comes from a YM term, this is neglected in double scaling limit

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Multiple M5-branes

- Recent proposal that M5-branes on S¹ is equivalent to D4-branes with instantons.
- There is a precise mapping between instanton states and KK modes
- Seems natural to promote $X^5 = 1$ to a general field

$$H^{\mu\nu\lambda} = -i[X^{\mu}, X^{\nu}, X^{\lambda}]$$

- Different from field strength of 2-form formulation, here in terms of a 1-form
- Two formulations are related non-trivially

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Multiple M5-branes

Propose action

$$egin{aligned} S_{M5} &= -rac{1}{4} & \int_{\Sigma_6} \mathrm{tr}(rac{1}{6} \epsilon_{abcde} H^{abc} H^{de5} \ &+ (c_2 H^{abc} H_{abc} + c_3 H^{ab5} H_{ab5}) \sqrt{-g}) \end{aligned}$$

where $\Sigma_6 = \Sigma_5 \times \textit{S}^1$

• H must satisfy a Bianchi Id. Most natural one is

$$[X^{[\mu}, H^{\nu\lambda\rho]}] = 0$$

Requiring self-duality solves EOM

$$H_{ab5} = -rac{1}{6}\epsilon_{abcde}H^{cde}$$

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Multiple M5-branes

 The solution for coefficients are given by 1-parameter family

$$c_2 = -\frac{1}{18}(c_1/2), \quad c_3 = \frac{5}{6}(c_1/2)$$

• Moreover, the self-duality condition on *H* implies that the QNG is self-dual!

$$[\mathbf{x}^{\mu}, \mathbf{x}^{\nu}, \mathbf{x}^{\lambda}] = i\theta^{\mu\nu\lambda} \mathbf{1}$$

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Multiple M5-branes

• The final action for *K* parallel M5-branes (or *K* non-abelian 3-form) is

$$S_{M5,\theta} = -\frac{1}{4} \int_{x} \operatorname{tr}(\frac{1}{6} \epsilon_{abcde} H^{abc} H^{de5} + (\alpha \frac{-1}{3} H^{abc} H_{abc} + (1 - \alpha) H^{ab5} H_{ab5}) \sqrt{-g})$$

where \int_{x} is determined by the rep of the QNG.

- Only $\alpha = 1/6$ gives us the correct Bianchi Id and self-duality condition.
- The last two terms combine to give the non-abelian generalisation of the gauge fixed PST action!

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Conclusion

Results:

- New kind of geometry in string theory
- D1's in a large flux \rightarrow non-abelian 3-form on M5's.

• Identify
$$C^{\mu\nu\lambda} = \theta^{\mu\nu\lambda}$$

Future:

- More representation theory
- QFT on a QNG
- Supersymmetry

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