# Oblivious quadrature for long-time computation of waves

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Based on work with: Volker Gruhne, María López Fernández (Zurich), Christian Lubich (Tübingen), Francisco-Javier Sayas (Delaware), Achim Schädle (Düsseldorf) Oblivious quadrature for long-time computation of waves and the coupling of implicit/explicit time-stepping

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# Outline

#### 1 A model problem

2 Coupling of different time-discretizations

#### Oblivious quadrature for long time computation

#### 4 Conclusions

## A model problem: Damped wave equation

Consider, for some bounded domain  $\Omega$  with boundary  $\Gamma,$ 

$$\begin{aligned} &\frac{1}{c(x)^2}\partial_t^2 u + \alpha \partial_t u - \Delta u = f, & \text{in } \Omega \times \mathbb{R}_{>0}, \\ &u(\cdot, 0) = u_0, \quad \partial_t u(\cdot, 0) = v_0, & \text{in } \Omega, \\ &\partial_\nu u = -\sqrt{\partial_t^2 + \alpha \partial_t} \, u, & \text{on } \Gamma \times \mathbb{R}_{>0}, \end{aligned}$$

with f,  $u_0$ ,  $v_0$ , c(x) - 1, compactly supported in  $\Omega$  and  $\alpha > 0$ .

- We can think of this as the damped wave equation with corresponding zero-order absorbing boundary condition.
- Note that u = 0 near  $\Gamma$  at time t = 0.

# Motivation behind the problem

Some properties of the  $\sqrt{\partial_t^2 + \alpha \partial_t}$ :

- A non-local operator with infinite memory.
- Taking the Laplace transform

$$\left(\mathscr{L}\sqrt{\partial_t^2 + \alpha \partial_t}\right)(s) = \sqrt{s^2 + \alpha s}$$

we obtain an operator analytic and polynomially bounded in  $\mathbb{C}\setminus(-\infty,0]$  – an operator of parabolic type.

Motivation for considering:

• Similarities with 2D and damped wave equation fundamental solutions:

$$\frac{H(t-r)}{4\sqrt{t^2-r^2}} - 2D \qquad \frac{e^{-\sqrt{s^2+\alpha s} r}}{4\pi r} - 3D \text{ damped in Laplace domain.}$$

• Gives a simple example of a coupled linear hyperbolic/parabolic system, where the coupling of different time-discretizations is of interest.

Meaning of  $\sqrt{\partial_t^2 + \alpha \partial_t}$ .

• For sufficiently smooth causal f and  $F(s) = (\mathcal{L}f)(s)$ 

$$(\mathscr{L}(\partial_t f))(s) = sF(s).$$

Note that  $\partial_t f$  can be understood as the convolution

 $\delta'*f.$ 

Similarly

$$\sqrt{\partial_t^2 + \alpha \partial_t} f(t) = \int_{\sigma + i\mathbb{R}} e^{st} \sqrt{s^2 + \alpha s} F(s) \, \mathrm{d}s$$

and can also be understood as a convolution, which is continuous and causal if

$$|\mathscr{L}f(s)| \leq C|s|^{-\mu}$$

for  $\mu > 2$  and Re  $s \ge \sigma > 0$ .





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# Variational formulation and spatial discretization

Let  $S_h \subset H^1(\Omega)$  be a piecewise linear finite element space. Find  $u_h(\cdot, t) \in S_h$  such that

$$(\partial_t^2 u_h + \alpha \partial_t u_h, v)_{L^2(\Omega)} + (\nabla u_h, \nabla v)_{L^2(\Omega)} + \left\langle \sqrt{\partial_t^2 + \alpha \partial_t} u_h, v \right\rangle_{L^2(\Gamma)} = (f, v)_{L^2(\Gamma)}$$

and  $u_h(0) = u_{0,h}$ ,  $\partial_t u_h(0) = v_{0,h}$ .

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and  $u_h(0) = u_{0,h}$ ,  $\dot{u}_h(0) = v_{0,h}$ .

- We plan to discretize  $\dot{u}$  and  $\partial_t^{-1}$  with different discretization schemes.
- Testing with  $v = \dot{u}_h$  we obtain the energy identity (for f = 0)

$$E(t) = E(0) - \int_0^t \alpha \|\dot{u}_h\|_{L^2(\Omega)}^2 d\tau - \int_0^t \left\langle \sqrt{1 + \alpha \partial_t^{-1}} \, \dot{u}_h, \dot{u}_h \right\rangle_{L^2(\Gamma)} d\tau.$$

where

$$E(t) = \frac{1}{2} \|\dot{u}_h\|_{L^2(\Omega)}^2 + \frac{1}{2} \|\nabla u_h\|_{L^2(\Omega)}^2.$$

## Positivity of the boundary term [LB, Lubich, Sayas 2014]

Lemma

For a sufficiently smooth causal  $\varphi(\cdot, t) \in H^{1/2}(\Gamma)$ 

$$\int_0^t \left\langle \sqrt{1 + \alpha \partial_t^{-1}} \, \varphi, \varphi \right\rangle_{L^2(\Gamma)} d\tau \ge \int_0^t \|\varphi\|^2 d\tau.$$

**Proof:** For  $\sigma > 0$  consider

$$\int_{\mathbb{R}} e^{-2\sigma\tau} \left\langle \sqrt{1+\alpha\partial_t^{-1}} \varphi, \varphi \right\rangle_{L^2(\Gamma)} d\tau = \int_{\mathbb{R}} \sqrt{1+\alpha s^{-1}} \|\Phi(s)\|^2 d\omega,$$

where,  $s = \sigma + \mathrm{i}\omega$ ,  $\Phi(s) = \mathscr{L}\varphi(s)$ . The proof is finished by noticing that

$$\operatorname{\mathsf{Re}} \sqrt{1 + \alpha s^{-1}} \ge 1 \implies$$
$$\int_{\mathbb{R}} e^{-2\sigma\tau} \left\langle \sqrt{1 + \alpha \partial_t^{-1}} \varphi, \varphi \right\rangle_{L^2(\Gamma)} d\tau \ge \int_{\mathbb{R}} e^{-2\sigma\tau} \|\varphi\|^2 d\tau.$$

Discretizing  $\sqrt{\partial_t^2 + \alpha \partial_t}$  - Convolution quadrature [Lubich '88] •  $\partial_t u(t) \approx \partial_{\Delta t} u(t) = \frac{u(t) - u(t - \Delta t)}{\Delta t}$ . Then  $(\mathscr{L}\partial_{\Delta t}u)(s) = \left(\frac{1 - e^{-s\Delta t}}{\Delta t}\right) U(s) = s_{\Delta t}U(s).$ 

Note  $s_{\Delta t} = s(1 + O(s\Delta t))$ .

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Expanding

$$\sqrt{1 + \alpha s_{\Delta t}^{-1}} = \sum_{j=0}^{\infty} \omega_j e^{-sj\Delta t}$$

we get that

$$\sqrt{1+lpha\partial_{\Delta t}^{-1}}u(t)=\sum_{j=0}^{\infty}\omega_ju(t-t_j).$$

Computing the weights  $\omega_j$  and extensions

• The weights are Taylor coefficients of the analytic function

$$\sqrt{1 + \alpha \frac{\Delta t}{1 - z}} = \sum_{j=0}^{\infty} \omega_j z^j$$

and can hence be efficiently computed using contour integrals and FFTs.

• Similarly higher order  $A(\theta)$ -stable linear multistep or Runge-Kutta methods can be used as the basis for discretization.

Example for  $\alpha = 1/2$ ,  $\Delta t = 1/100$ :

j	0	1	2	3
$\omega_j$	1.0024969	0.0024938	0.0024907	0.0024876

# Fully discrete system

Writing  $t_j = j\Delta t$  and  $u_j$  an approximation of  $u_h(t_j)$  the fully discrete system reads

$$\frac{1}{\Delta t^2}(u_{n+1}-2u_n+u_{n-1},v)+(\alpha \dot{u}_n,v)+(\nabla u_n,\nabla v) \\ +\left\langle \sqrt{1+\alpha \partial_{\Delta t}^{-1}}\,\dot{u}(t_n),v\right\rangle = (f_n,v),$$

where  $\dot{u}_n = \frac{1}{2\Delta t}(u_{n+1} - u_{n-1}).$ 

• To obtain an energy identity test again with  $v = \dot{u}_n$  (for f = 0) and sum over n to obtain

$$E_{N+1/2} = E_{1/2} - \Delta t \sum_{n=0}^{N} \alpha \|\dot{u}_n\|^2 - \Delta t \sum_{n=0}^{N} \left\langle \sqrt{1 + \alpha \partial_{\Delta t}^{-1}} \dot{u}(t_n), \dot{u}_n \right\rangle,$$

where the discrete energy

$$E_{n+1/2} = \frac{1}{2} \left\| \frac{u_{n+1} - u_n}{\Delta t} \right\|^2 + \frac{1}{2} (\nabla u_n, \nabla u_{n+1})$$

is positive under the usual CFL condition.

# Positivity of the discretized boundary term [LB, Lubich, Sayas 2014]

#### Lemma

We have

$$\sum_{n=0}^{N} \left\langle \sqrt{1+\alpha \partial_{\Delta t}^{-1}} v(t_n), v_n \right\rangle \geq 0.$$

Proof is similar and requires that

$$\operatorname{\mathsf{Re}}\sqrt{1+lpha/s^{\Delta t}}>0.$$

• This is true as long as  $s^{\Delta t}$  avoids the negative real axis.

• For  $s = i\omega$ ,  $s^{\Delta t}$  traverses the boundary of the stability region, hence the above holds for  $A(\theta)$ -stable methods.

#### Different time-steps: version 1

The time-step may be severely restricted by the CFL condition. So use

$$\kappa = \Delta t/k, \qquad k \in \mathbb{N},$$

in the interior. Denote  $t_{n,\ell} = n\Delta t + \ell \kappa = n\Delta t + (\ell/k)\Delta t$  and  $u_{n,\ell}$  the corresponding approximation.

$$\frac{1}{\kappa^2}(u_{n,\ell+1}-2u_{n,\ell}+u_{n,\ell-1},\mathbf{v})+(\alpha \dot{u}_{n,\ell},\mathbf{v})+(\nabla u_{n,\ell},\nabla \mathbf{v}) \\ +\left\langle \sqrt{1+\alpha\partial_{\Delta t}^{-1}}\dot{u}(t_{n,\ell}),\mathbf{v}\right\rangle = (f_{n,\ell},\mathbf{v}),$$

where  $\dot{u}_{n,\ell} = \frac{1}{2\kappa} (u_{n,\ell+1} - u_{n,\ell-1}).$ 

 To obtain an energy identity test again with v = u<sub>n,ℓ</sub> and sum over n and ℓ to obtain

$$E_{N,1/2} = E_{0,1/2} - \kappa \sum_{\ell=0}^{k-1} \sum_{n=0}^{N} \alpha \|\dot{u}_n\|^2 - \kappa \sum_{\ell=0}^{k-1} \sum_{n=0}^{N} \left\langle \sqrt{1 + \alpha \partial_{\Delta t}^{-1}} \dot{u}(t_{n,\ell}), \dot{u}_{n,\ell} \right\rangle$$

# Comments on version 1

Note

$$\sqrt{1+\alpha\partial_{\Delta t}^{-1}}\,\dot{u}(t_{n,\ell})=\sum_{j=0}^{\infty}\omega_j\dot{u}_{n-j,\ell}.$$

• The boundary term is again positive since it is positive for each  $\ell$ :

$$\sum_{n=0}^{N} \left\langle \sqrt{1 + \alpha \partial_{\Delta t}^{-1}} \, \dot{u}(t_{n,\ell}), \dot{u}_{n,\ell} \right\rangle \geq 0.$$

• Only need to compute *N* weights and each convolution requires *N* multiplications, rather than *kN*.

• But we still need to compute the whole convolution for each  $t_{n,\ell}$ . Can this be improved?

## A bad version

Let us throw caution to the wind and try

$$\frac{1}{\kappa^2}(u_{n,\ell+1} - 2u_{n,\ell} + u_{n,\ell-1}, \mathbf{v}) + (\alpha \dot{u}_{n,\ell}, \mathbf{v}) + (\nabla u_{n,\ell}, \nabla \mathbf{v}) \\ + \left\langle \sqrt{1 + \alpha \partial_{\Delta t}^{-1}} \dot{u}(t_n), \mathbf{v} \right\rangle = (f_{n,\ell}, \mathbf{v}),$$

First compute with the stable version:



## A bad version

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$$\frac{1}{\kappa^2}(u_{n,\ell+1} - 2u_{n,\ell} + u_{n,\ell-1}, \mathbf{v}) + (\alpha \dot{u}_{n,\ell}, \mathbf{v}) + (\nabla u_{n,\ell}, \nabla \mathbf{v}) \\ + \left\langle \sqrt{1 + \alpha \partial_{\Delta t}^{-1}} \dot{u}(t_n), \mathbf{v} \right\rangle = (f_{n,\ell}, \mathbf{v}),$$

Instability occurs eventually with the ad-hoc version:



#### Version 2: cheaper and stable

Idea: Apply the boundary operator to a different approximation of  $\dot{u}$ :

$$\frac{1}{\kappa^2}(u_{n,\ell+1}-2u_{n,\ell}+u_{n,\ell-1},v)+(\alpha \dot{u}_{n,\ell},v)+(\nabla u_{n,\ell},\nabla v) \\ +\left\langle\sqrt{1+\alpha\partial_{\Delta t}^{-1}}\,\tilde{\dot{u}}(t_n),v\right\rangle=(f_{n,\ell},v).$$

• Testing with  $v = \dot{u}_{n,\ell}$  we obtain

$$E_{N,1/2} = E_{0,1/2} - \kappa \sum_{\ell=1}^{k} \sum_{n=0}^{N} \alpha \|\dot{u}_{n}\|^{2} - \kappa \sum_{\ell=1}^{k} \sum_{n=0}^{N} \left\langle \sqrt{1 + \alpha \partial_{\Delta t}^{-1}} \, \tilde{\dot{u}}(t_{n}), \dot{u}_{n,\ell} \right\rangle$$
  
=  $E_{0,1/2} - \Delta t \sum_{n=0}^{N} \alpha \|\dot{u}_{n}\|^{2} - \Delta t \sum_{n=0}^{N} \left\langle \sqrt{1 + \alpha \partial_{\Delta t}^{-1}} \, \tilde{\dot{u}}(t_{n}), \frac{1}{k} \sum_{\ell=1}^{k} \dot{u}_{n,\ell} \right\rangle.$ 

• Energy balance is obtained by choosing

$$\widetilde{\dot{u}}_n = \frac{1}{k} \sum_{\ell=1}^k \dot{u}_{n,\ell}.$$

## Comments on version 2

- Now the convolution is only evaluated N times.
- The convergence order has been reduced.
- The boundary and domain values of *u* are strongly coupled.
- In [Abboud et al. ,2011] the authors consider a predictor-corrector strategy to solve a similar system.
- With all the versions the memory connected to the boundary is infinite.

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# Weights and inverse Laplace transform

• Another representation of  $\omega_j$ s is useful for n > 1

$$\omega_n = \frac{\Delta t}{2\pi i} \int_{\sigma + i\mathbb{R}} \sqrt{1 + \alpha/s} \, e_n(s\Delta t) ds$$

where for Backward Euler

$$e_n(z) = rac{1}{(1-z)^{n+1}},$$
 Note:  $rac{1}{1-z} = e^z + O(z^2).$ 

• Similar to inverse Laplace computations use

$$\omega_n = \frac{\Delta t}{2\pi i} \int_{\Gamma} \sqrt{1 + \alpha/s} \, e_n(s\Delta t) \mathrm{d}s,$$

with  $\Gamma$  a hyperbola or Talbot contour and discretize by a truncated trapezoid rule.

• To obtain uniform quadrature errors us different contours Γ<sub>i</sub> for

$$t_n \in [B^{n-1}\Delta t, 2B^n\Delta t).$$

#### Oblivious quadrature [Schädle, López Fernández, Lubich 2005] Split the discrete convolution as

$$v_{n+1} = \sum_{j=0}^{n} \omega_{n-j} u_j = v_{n+1}^{(0)} + \cdots + v_{n+1}^L,$$

with

$$v_{n+1}^{(0)} = \omega_0 u_n$$
 and  $v_{n+1}^{(i)} = \sum_{j=b_i}^{b_{i-1}-1} \omega_{n-j} u_j$ ,

where  $b_0 = N$ ,  $b_L = 0$ , and for  $i \in [b_i, b_{i-1} - 1]$  we have  $n - j \in [B^{i-1}, 2B^i - 2]$ .

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where  $b_0 = N$ ,  $b_L = 0$ , and for  $i \in [b_i, b_{i-1} - 1]$  we have  $n - j \in [B^{i-1}, 2B^i - 2]$ .

$$v_{n+1}^{(i)} = \sum_{j=b_i}^{b_{i-1}-1} \omega_{n-j} u_j = \frac{1}{2\pi i} \int_{\Gamma_i} e_{n-(b_{i-1}-1)}(sh) \sqrt{1+\alpha/s} y^{(i)}(hs) ds$$

with

$$y^{(i)}(hs) = h \sum_{j=b_i}^{b_{i-1}-1} e_{(b_{i-1}-1)-j}(hs) u_j.$$

Oblivious quadrature [Schädle, López Fernández, Lubich 2005]

Some comments regarding the algorithm:

•  $y^{(i)}(hs)$  is the Backward-Euler approximation at  $t = b_{i-1}h$  to

$$u'=sy+g(t), \qquad y(b_ih)=0.$$

- This ODE needs to be solved for *L* contours  $\Gamma_i$  and the corresponding 2K + 1 quadrature points  $s_k^{(i)} = \varphi_i(x_k)$ .
- There are only  $(2K + 1)L = O(\log N \log \frac{1}{\epsilon})$  evaluations of  $\sqrt{1 + \alpha/s}$  ((K + 1)L when using symmetry).
- To compute N steps after t<sub>n</sub> > r, required number of multiplications is O(N log N) with O(log N) memory stored.

Relation to time-domain boundary integral equations Laplace domain fundamental solutions  $K(r, s) = (\mathscr{L}k)(r, s)$ 

2D: 
$$K(r,s) = \frac{1}{2\pi} K_0(rs)$$
, damped 3D:  $K(r,s) = \frac{e^{-\sqrt{s^2 + \alpha s} r}}{4\pi r}$ .

• Note  $K(s, r)e^{sr}$  bounded for Re s > 0 – causality. But more is true.

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#### Late-time behaviour of fundamental solution [LB,Gruhne 2011]

Dissipative and 2D wave equations have infinite memory but the kernel has a parabolic behaviour for t > r:

$$|K(r,s)e^{rs}| \leq C|s|^{\mu}, \qquad s \in \mathbb{C} \setminus (-\infty,0]$$

 $\mu = -1/2$  for  $\mathcal{K}_0(\cdot)$  and  $\mu = 0$  for 3D dissipative wave equation.

For how to combine this observation with oblivious quadrature ideas see work in progress with López-Fernández and Schädle.

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## Conclusions

- Coupling of explicit/implicit schemes based on energy balance.
- Relevant also to the coupling of FEM/BEM in the time domain as the time-domain boundary integral equations are discretizaed by implicit mehods.
- Oblivious quadrature reduces memory requirements and is also applicable to wave propagation problems and time-domain boundary integral equations.