

Spectral Approach to Homogenization of Periodic Differential Operators

Tatiana Suslina

St. Petersburg State University

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Plan

- Introduction
- Statement of the problem
- The effective operator
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Introduction

Homogenization theory studies differential equations with rapidly oscillating coefficients. One is interested in the behavior of the solutions in the small period limit.

Homogenization theory studies differential equations with rapidly oscillating coefficients. One is interested in the behavior of the solutions in the small period limit. A broad literature is devoted to homogenization problems. First of all, we mention the books

- A. Bensoussan, J.-L. Lions, G. Papanicolaou. Asymptotic analysis for periodic structures, 1978.
- E. Sanchez-Palencia. Nonhomogeneous media and vibration theory, 1980.
- N. S. Bakhvalov, G. P. Panasenko. Homogenization: averaging of processes in periodic media, 1984.
- V. V. Zhikov, S. M. Kozlov, O. A. Oleinik. Homogenization of differential operators, 1993.

One of the methods in homogenization theory is a **spectral approach** based on the Floquet-Bloch theory and the spectral perturbation theory.

Mention the following papers where the spectral method was used:

- E. V. Sevost'yanova, *Asymptotic expansion of the solution of a second-order elliptic equation with periodic rapidly oscillating coefficients*, Math. USSR-Sbornik, 1982.
- V. V. Zhikov, *Spectral approach to asymptotic diffusion problems*, Diff. Equations, 1989.
- C. Conca, R. Orive, M. Vanninathan, *Bloch approximation in homogenization and applications*, SIAM J. Math. Anal., 2002.

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We will discuss the **operator-theoretic (spectral) approach** to homogenization problems that was suggested and developed in a series of papers by **M. Birman** and **T. Suslina** (in 2001–2008).

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The main idea of our approach is that the homogenization can be studied as a **spectral threshold effect** at the bottom of the spectrum of a periodic elliptic operator.

Consider the simplest homogenization problem. Let $\varepsilon > 0$ be a small parameter. In $L_2(\mathbb{R}^d)$, consider the operator

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$$A_\varepsilon = -\operatorname{div} g(\mathbf{x}/\varepsilon)\nabla.$$

Here $g(\mathbf{x})$ is positive definite and bounded $(d \times d)$ -matrix-valued function, periodic with respect to some lattice of periods. The operator A_ε is the acoustics operator, it describes a periodic acoustical medium with rapidly oscillating parameters.

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From physical point of view the convergence $u_\varepsilon \rightarrow u_0$ means **homogenization of the medium**: a medium with rapidly oscillating parameters in the small period limit behaves like a homogeneous medium with constant effective parameters. Mathematicians are interested in the character of convergence and estimates of the error $u_\varepsilon - u_0$.

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Such estimates are called **operator error estimates** in homogenization theory. In order to obtain estimate (2), it is useful to apply the **scaling transformation**. We have the following identity:

$$\|(A_\varepsilon + I)^{-1} - (A^0 + I)^{-1}\|_{L_2 \rightarrow L_2} = \varepsilon^2 \|(A + \varepsilon^2 I)^{-1} - (A^0 + \varepsilon^2 I)^{-1}\|_{L_2 \rightarrow L_2},$$

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$$\|(A + \varepsilon^2 I)^{-1} E_\delta^\perp\|_{L_2(\mathbb{R}^d) \rightarrow L_2(\mathbb{R}^d)} \leq \delta^{-1}.$$

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Statement of the problem

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By $\tilde{\Gamma}$ we denote the dual lattice. Let $\tilde{\Omega}$ be the Brillouin zone of $\tilde{\Gamma}$.

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$$A = f(\mathbf{x})^* b(\mathbf{D})^* g(\mathbf{x}) b(\mathbf{D}) f(\mathbf{x}), \quad \mathbf{D} = -i\nabla.$$

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Here $g(\mathbf{x})$ is an $(m \times m)$ -matrix, $f(\mathbf{x})$ is an $(n \times n)$ -matrix, and $b(\mathbf{D})$ is an $(m \times n)$ -matrix DO. It is assumed that $m \geq n$.

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Suppose that $g(\mathbf{x})$ and $f(\mathbf{x})$ are Γ -periodic and such that

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The operator $b(\mathbf{D})$ is given by

$$b(\mathbf{D}) = \sum_{j=1}^d b_j D_j,$$

where b_j are constant $(m \times n)$ -matrices. We assume that the symbol

$b(\boldsymbol{\xi}) = \sum_{j=1}^d b_j \xi_j$ satisfies

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This condition is equivalent to

$$\alpha_0 \mathbf{1}_n \leq b(\boldsymbol{\theta})^* b(\boldsymbol{\theta}) \leq \alpha_1 \mathbf{1}_n, \quad |\boldsymbol{\theta}| = 1, \quad 0 < \alpha_0 \leq \alpha_1 < \infty. \quad (3)$$



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The precise definition of A is given in terms of the quadratic form

$$a[\mathbf{u}, \mathbf{u}] = \int_{\mathbb{R}^d} \langle g(\mathbf{x})b(\mathbf{D})(f(\mathbf{x})\mathbf{u}(\mathbf{x})), b(\mathbf{D})(f(\mathbf{x})\mathbf{u}(\mathbf{x})) \rangle dx,$$
$$\text{Dom } a = \{\mathbf{u} \in L_2(\mathbb{R}^d; \mathbb{C}^n) : f\mathbf{u} \in H^1(\mathbb{R}^d; \mathbb{C}^n)\}.$$

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$$c_0 \|\mathbf{D}(f\mathbf{u})\|_{L_2}^2 \leq a[\mathbf{u}, \mathbf{u}] \leq c_1 \|\mathbf{D}(f\mathbf{u})\|_{L_2}^2, \quad \mathbf{u} \in \text{Dom } a.$$

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Example. The acoustics operator: $\hat{A} = -\text{div } g(\mathbf{x})\nabla = \mathbf{D}^* g(\mathbf{x})\mathbf{D}$.

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Main object

Our main objects are the operators

$$\widehat{A}_\varepsilon = b(\mathbf{D})^* g^\varepsilon(\mathbf{x}) b(\mathbf{D}), \quad A_\varepsilon = (f^\varepsilon(\mathbf{x}))^* b(\mathbf{D})^* g^\varepsilon(\mathbf{x}) b(\mathbf{D}) f^\varepsilon(\mathbf{x}).$$

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Problem

Our goal is to study the behavior of the resolvents $(\widehat{A}_\varepsilon + I)^{-1}$ and $(A_\varepsilon + I)^{-1}$ for small ε .

The effective matrix. The effective operator

Definition of the effective matrix

Let $\Lambda(\mathbf{x})$ be the $(n \times m)$ -matrix-valued Γ -periodic solution of the problem

$$b(\mathbf{D})^* g(\mathbf{x})(b(\mathbf{D})\Lambda(\mathbf{x}) + \mathbf{1}_m) = 0, \quad \int_{\Omega} \Lambda(\mathbf{x}) d\mathbf{x} = 0.$$

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Then the *effective matrix* g^0 is an $(m \times m)$ -matrix given by

$$g^0 = |\Omega|^{-1} \int_{\Omega} \tilde{g}(\mathbf{x}) d\mathbf{x}, \quad \tilde{g}(\mathbf{x}) := g(\mathbf{x})(b(\mathbf{D})\Lambda(\mathbf{x}) + \mathbf{1}_m).$$

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It turns out that the matrix g^0 is positive definite.

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Proposition

The effective matrix satisfies the estimates (known as the *Voight-Reuss bracketing*)

$$\underline{g} \leq g^0 \leq \bar{g}.$$

Here

$$\bar{g} = |\Omega|^{-1} \int_{\Omega} g(\mathbf{x}) \, d\mathbf{x}, \quad \underline{g} = \left(|\Omega|^{-1} \int_{\Omega} g(\mathbf{x})^{-1} \, d\mathbf{x} \right)^{-1}.$$

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The operator

$$\widehat{A}^0 = b(\mathbf{D})^* g^0 b(\mathbf{D})$$

is called the *effective operator* for \widehat{A} .

Results: approximation for the resolvent

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Theorem 1 [M. Birman and T. Suslina]

Let $\widehat{A}_\varepsilon = b(\mathbf{D})^* g^\varepsilon b(\mathbf{D})$, and let $\widehat{A}^0 = b(\mathbf{D})^* g^0 b(\mathbf{D})$ be the effective operator. Then

$$\|(\widehat{A}_\varepsilon + I)^{-1} - (\widehat{A}^0 + I)^{-1}\|_{L_2 \rightarrow L_2} \leq C\varepsilon, \quad 0 < \varepsilon \leq 1. \quad (4)$$

The constant C depends only on the norms $\|g\|_{L_\infty}$, $\|g^{-1}\|_{L_\infty}$, on α_0 , α_1 , and the parameters of the lattice Γ .

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If $f \neq \mathbf{1}$, the resolvent of the operator $A_\varepsilon = (f^\varepsilon)^* b(\mathbf{D})^* g^\varepsilon b(\mathbf{D}) f^\varepsilon$ cannot be approximated by the resolvent of some operator with constant coefficients.

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Theorem 2 [M. Birman and T. Suslina]

We have

$$\|(A_\varepsilon + I)^{-1} - (f^\varepsilon)^{-1}(\widehat{A}^0 + \overline{Q})^{-1}((f^\varepsilon)^*)^{-1}\|_{L_2 \rightarrow L_2} \leq C\varepsilon, \quad 0 < \varepsilon \leq 1. \quad (5)$$

Here

$$\overline{Q} = |\Omega|^{-1} \int_{\Omega} (f(\mathbf{x})f(\mathbf{x})^*)^{-1} d\mathbf{x}.$$

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Estimates (4) and (5) are **order-sharp**, and the constants in estimates are well controlled.

Results: more accurate approximation for the resolvent

In order to describe more accurate approximation of the resolvent, we need to introduce a **corrector** $K(\varepsilon)$:

$$K(\varepsilon) = K_1(\varepsilon) + K_1(\varepsilon)^* + K_3. \quad (6)$$

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$$(\Pi_\varepsilon \mathbf{u})(\mathbf{x}) = (2\pi)^{-d/2} \int_{\widetilde{\Omega}/\varepsilon} e^{i\langle \mathbf{x}, \boldsymbol{\xi} \rangle} \widehat{\mathbf{u}}(\boldsymbol{\xi}) d\boldsymbol{\xi},$$

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$\widehat{\mathbf{u}}(\boldsymbol{\xi})$ is the Fourier image of $\mathbf{u}(\mathbf{x})$. The operator K_3 is given by

$$K_3 = -(\widehat{A}^0 + I)^{-1} b(\mathbf{D})^* L(\mathbf{D}) b(\mathbf{D})(\widehat{A}^0 + I)^{-1},$$

where $L(\mathbf{D})$ is the first order differential operator with the symbol

$$L(\boldsymbol{\xi}) = |\Omega|^{-1} \int_{\Omega} (\Lambda(\mathbf{x})^* b(\boldsymbol{\xi})^* \widetilde{g}(\mathbf{x}) + \widetilde{g}(\mathbf{x})^* b(\boldsymbol{\xi}) \Lambda(\mathbf{x})) dx.$$

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Theorem 3 [M. Birman and T. Suslina]

We have

$$\|(\widehat{A}_\varepsilon + I)^{-1} - (\widehat{A}^0 + I)^{-1} - \varepsilon K(\varepsilon)\|_{L_2 \rightarrow L_2} \leq C\varepsilon^2, \quad 0 < \varepsilon \leq 1. \quad (8)$$

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In particular, this is possible in the following cases: a) if $d \leq 4$, b) for the scalar operator $\widehat{A} = \mathbf{D}^* g(\mathbf{x}) \mathbf{D} = -\operatorname{div} g(\mathbf{x}) \nabla$, where $g(\mathbf{x})$ has real entries.

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A similar but more complicated result is true for operators A_ε (we will not dwell on this).

Results: approximation of the resolvent in the energy norm

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The analog of Theorem 4 is true for more general operator A_ε .

Method: the scaling transformation

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Scaling transformation. Let T_ε be the unitary **scaling operator** in $L_2(\mathbb{R}^d; \mathbb{C}^n)$:

$$(T_\varepsilon \mathbf{u})(\mathbf{x}) = \varepsilon^{d/2} \mathbf{u}(\varepsilon \mathbf{x}).$$

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A similar identity is true for $(\widehat{A}^0 + I)^{-1}$. Hence,

$$\|(\widehat{A}_\varepsilon + I)^{-1} - (\widehat{A}^0 + I)^{-1}\|_{L_2 \rightarrow L_2} = \varepsilon^2 \|(\widehat{A} + \varepsilon^2 I)^{-1} - (\widehat{A}^0 + \varepsilon^2 I)^{-1}\|_{L_2 \rightarrow L_2}.$$

Method: the scaling transformation

Consequently, the required estimate

$$\|(\widehat{A}_\varepsilon + I)^{-1} - (\widehat{A}^0 + I)^{-1}\|_{L_2 \rightarrow L_2} \leq C\varepsilon$$

is equivalent to

$$\|(\widehat{A} + \varepsilon^2 I)^{-1} - (\widehat{A}^0 + \varepsilon^2 I)^{-1}\|_{L_2(\mathbb{R}^d) \rightarrow L_2(\mathbb{R}^d)} \leq C\varepsilon^{-1}. \quad (10)$$

Method: the direct integral expansion

Applying the **Floquet-Bloch theory**, we decompose \widehat{A} in the direct integral of the operators $\widehat{A}(\mathbf{k})$ acting in $L_2(\Omega; \mathbb{C}^n)$ and depending on the parameter $\mathbf{k} \in \mathbb{R}^d$ called the *quasimomentum*.

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$$(\mathcal{U}f)(\mathbf{k}, \mathbf{x}) = |\widetilde{\Omega}|^{-1/2} \sum_{\mathbf{a} \in \Gamma} e^{-i\langle \mathbf{k}, \mathbf{x} + \mathbf{a} \rangle} f(\mathbf{x} + \mathbf{a}), \quad \mathbf{x} \in \Omega, \mathbf{k} \in \widetilde{\Omega}.$$

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Next, \mathcal{U} extends by continuity to a unitary mapping

$$\mathcal{U} : L_2(\mathbb{R}^d; \mathbb{C}^n) \rightarrow L_2(\widetilde{\Omega} \times \Omega; \mathbb{C}^n) = \int_{\widetilde{\Omega}} \oplus L_2(\Omega; \mathbb{C}^n) d\mathbf{k}.$$

Method: the direct integral expansion

The operator $\widehat{A}(\mathbf{k})$ acts in $L_2(\Omega; \mathbb{C}^n)$ and is given by

$$\widehat{A}(\mathbf{k}) = b(\mathbf{D} + \mathbf{k})^* g(\mathbf{x}) b(\mathbf{D} + \mathbf{k})$$

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with periodic boundary conditions. Precisely, $\widehat{A}(\mathbf{k})$ is a selfadjoint operator in $L_2(\Omega; \mathbb{C}^n)$ corresponding to the closed nonnegative quadratic form

$$\widehat{a}(\mathbf{k})[\mathbf{u}, \mathbf{u}] = \int_{\Omega} \langle g(\mathbf{x}) b(\mathbf{D} + \mathbf{k})\mathbf{u}, b(\mathbf{D} + \mathbf{k})\mathbf{u} \rangle dx, \quad \mathbf{u} \in H_{\text{per}}^1(\Omega; \mathbb{C}^n).$$

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Under our assumptions the form $\widehat{a}(\mathbf{k})$ satisfies the two-sided estimates

$$c_0 \int_{\Omega} |(\mathbf{D} + \mathbf{k})\mathbf{u}|^2 dx \leq \widehat{a}(\mathbf{k})[\mathbf{u}, \mathbf{u}] \leq c_1 \int_{\Omega} |(\mathbf{D} + \mathbf{k})\mathbf{u}|^2 dx, \quad \mathbf{u} \in H_{\text{per}}^1(\Omega; \mathbb{C}^n). \quad (11)$$

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The direct integral expansion for \widehat{A} is given by the formula

$$U \widehat{A} U^{-1} = \int_{\widetilde{\Omega}} \oplus \widehat{A}(\mathbf{k}) d\mathbf{k}. \quad (12)$$

Method: the spectral properties

By (12), the required estimate (10) is equivalent to the following estimate which must be uniform in \mathbf{k} :

$$\|(\widehat{A}(\mathbf{k}) + \varepsilon^2 I)^{-1} - (\widehat{A}^0(\mathbf{k}) + \varepsilon^2 I)^{-1}\|_{L_2(\Omega) \rightarrow L_2(\Omega)} \leq C\varepsilon^{-1}, \quad \mathbf{k} \in \widetilde{\Omega}. \quad (13)$$

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$$E_1(\mathbf{k}) \leq E_2(\mathbf{k}) \leq \dots \leq E_j(\mathbf{k}) \leq \dots$$

The functions $E_j(\mathbf{k})$ are called **band functions**.

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The functions $E_j(\mathbf{k})$ are called **band functions**. Band functions $E_j(\mathbf{k})$ are continuous and periodic with respect to $\widetilde{\Gamma}$. The spectrum of the initial operator \widehat{A} has a **band structure**:

$$\text{spec } \widehat{A} = \bigcup_{j \in \mathbb{N}} \text{Ran } E_j.$$

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By (12), the required estimate (10) is equivalent to the following estimate which must be uniform in \mathbf{k} :

$$\|(\widehat{A}(\mathbf{k}) + \varepsilon^2 I)^{-1} - (\widehat{A}^0(\mathbf{k}) + \varepsilon^2 I)^{-1}\|_{L_2(\Omega) \rightarrow L_2(\Omega)} \leq C\varepsilon^{-1}, \quad \mathbf{k} \in \widetilde{\Omega}. \quad (13)$$

Spectral properties. The operators $\widehat{A}(\mathbf{k})$ have discrete spectrum. By $E_j(\mathbf{k})$, $j \in \mathbb{N}$, we denote the consecutive eigenvalues of $\widehat{A}(\mathbf{k})$:

$$E_1(\mathbf{k}) \leq E_2(\mathbf{k}) \leq \dots \leq E_j(\mathbf{k}) \leq \dots$$

The functions $E_j(\mathbf{k})$ are called **band functions**. Band functions $E_j(\mathbf{k})$ are continuous and periodic with respect to $\widetilde{\Gamma}$. The spectrum of the initial operator \widehat{A} has a **band structure**:

$$\text{spec } \widehat{A} = \bigcup_{j \in \mathbb{N}} \text{Ran } E_j.$$

Spectral bands can overlap; there may be gaps in the spectrum.

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From estimates (11) with $\mathbf{k} = \mathbf{0}$ it is clear that

$$\mathfrak{N} := \text{Ker } \widehat{A}(\mathbf{0}) = \{\mathbf{u} \in L_2(\Omega; \mathbb{C}^n) : \mathbf{u} = \mathbf{c} \in \mathbb{C}^n\}, \quad \dim \mathfrak{N} = n.$$

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From (11), by simple variational arguments it follows that

$$\min_{\mathbf{k}} E_j(\mathbf{k}) = E_j(0) = 0, \quad j = 1, \dots, n,$$

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So, the first n bands overlap and have the common bottom $\lambda = 0$, while the next band is separated from zero. Moreover,

$$E_j(\mathbf{k}) \geq c_* |\mathbf{k}|^2, \quad \mathbf{k} \in \tilde{\Omega}, \quad j = 1, \dots, n, \quad c_* > 0. \quad (14)$$

Method: analytic perturbation theory

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$$\mathbf{k} = t\boldsymbol{\theta}, \quad t = |\mathbf{k}|, \quad \boldsymbol{\theta} \in \mathbb{S}^{d-1},$$

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Method: analytic perturbation theory

The family $A(t, \theta)$ is studied in the framework of an **abstract operator-theoretic scheme**. For this scheme, it is important that this operator family admits a factorization of the form

$$A(t, \theta) = X(t, \theta)^* X(t, \theta), \quad X(t, \theta) = X_0 + tX_1(\theta).$$

Here X_0 is given by

$$X_0 = g(\mathbf{x})^{1/2} b(\mathbf{D})$$

with periodic boundary conditions, and $X_1(\theta)$ is a bounded operator:

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So, the point $\lambda = 0$ is an eigenvalue of multiplicity n for the unperturbed operator $\hat{A}(0)$. Then for $t \leq t^0$ the perturbed operator $A(t, \theta)$ has exactly n eigenvalues on the interval $[0, \delta]$, while the interval $(\delta, 3\delta)$ is free of the spectrum. We control δ and t^0 explicitly.

Method: analytic perturbation theory

By the Kato-Rellich theorem, for $t \leq t^0$ there exist **real-analytic branches of the eigenvalues** $\lambda_l(t, \theta)$ and **real-analytic branches of the eigenvectors** $\varphi_l(t, \theta)$ of the operator $A(t, \theta)$:

$$A(t, \theta)\varphi_l(t, \theta) = \lambda_l(t, \theta)\varphi_l(t, \theta), \quad l = 1, \dots, n,$$

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$$\begin{aligned} \lambda_l(t, \boldsymbol{\theta}) &= \gamma_l(\boldsymbol{\theta})t^2 + \mu_l(\boldsymbol{\theta})t^3 + \dots, & l = 1, \dots, n, \\ \varphi_l(t, \boldsymbol{\theta}) &= \omega_l(\boldsymbol{\theta}) + t\psi_l(\boldsymbol{\theta}) + \dots, & l = 1, \dots, n. \end{aligned}$$

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We have $\gamma_l(\theta) \geq c_* > 0$. The vectors $\omega_l(\theta)$, $l = 1, \dots, n$, form an orthonormal basis in \mathfrak{N} . The coefficients $\gamma_l(\theta)$ and the vectors $\omega_l(\theta)$, $l = 1, \dots, n$, are called **threshold characteristics** of $A(t, \theta)$.

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Definition of the spectral germ

The selfadjoint operator $S(\theta) : \mathfrak{N} \rightarrow \mathfrak{N}$ such that

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where g^0 is the effective matrix. It turns out that the operator family $A^0(t, \theta) = \widehat{A}^0(\mathbf{k})$ which corresponds to the effective operator has the same spectral germ as $A(t, \theta) = \widehat{A}(\mathbf{k})$.

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$$\begin{aligned} \|F(t, \theta) - P\|_{L_2(\Omega) \rightarrow L_2(\Omega)} &\leq C_1 t, \\ \|A(t, \theta)F(t, \theta) - t^2 S(\theta)P\|_{L_2(\Omega) \rightarrow L_2(\Omega)} &\leq C_2 t^3. \end{aligned}$$

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Such approximations are proved by integration of the resolvent $(A(t, \theta) - zI)^{-1}$ over the contour in \mathbb{C} which envelopes the interval $[0, \delta]$ equidistantly at the distance δ .

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Next, with the help of Theorem 5, we find a finite rank approximation of the resolvent $(A(t, \theta) + \varepsilon^2 I)^{-1}$ in terms of the spectral germ.

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Let P be the orthogonal projection of $L_2(\Omega; \mathbb{C}^n)$ onto \mathfrak{N} . Let $S(\theta) : \mathfrak{N} \rightarrow \mathfrak{N}$ be the spectral germ of $A(t, \theta)$. Then

$$\|(A(t, \theta) + \varepsilon^2 I)^{-1} - (t^2 S(\theta) + \varepsilon^2 I_{\mathfrak{N}})^{-1} P\|_{L_2(\Omega) \rightarrow L_2(\Omega)} \leq C \varepsilon^{-1},$$
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Since the effective operator family has the same germ, from Theorem 6 we deduce the required estimate (13):

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This completes the proof of Theorem 1.

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- For the study of more general operator A_ε , we use the identity $A_\varepsilon = (f^\varepsilon)^* \widehat{A}_\varepsilon f^\varepsilon$. It follows that the resolvent of the operator A_ε is related to the generalized resolvent of \widehat{A}_ε by the identity

$$(A_\varepsilon + I)^{-1} = (f^\varepsilon)^{-1}(\widehat{A}_\varepsilon + Q^\varepsilon)^{-1}((f^\varepsilon)^*)^{-1}. \quad (15)$$

Here $Q = (ff^*)^{-1}$. We study the generalized resolvent of the operator \widehat{A}_ε and then use the identity (15).

Operators of the form \widehat{A}_ε :

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Example. Let $d = 2$. Then

$$b(\mathbf{D}) = \begin{pmatrix} D_1 & 0 \\ \frac{1}{2}D_2 & \frac{1}{2}D_1 \\ 0 & D_2 \end{pmatrix},$$

and $g(\mathbf{x})$ is a symmetric (3×3) -matrix-valued function with real entries; it is bounded, positive definite and periodic. In the isotropic case $g(\mathbf{x})$ is expressed in terms of the Lamé parameters.

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$$\widehat{A}_\varepsilon = \text{curl } h^\varepsilon(\mathbf{x}) \text{curl} - \nabla \nu^\varepsilon(\mathbf{x}) \text{div}.$$

Here $h(\mathbf{x})$ is a symmetric (3×3) -matrix-valued function with real entries, and $\nu(\mathbf{x})$ is a real-valued function. Both $h(\mathbf{x})$ and $\nu(\mathbf{x})$ are periodic, bounded and positive definite.

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$$b(\mathbf{D}) = \begin{pmatrix} -i \text{curl} \\ -i \text{div} \end{pmatrix}, \quad g(\mathbf{x}) = \begin{pmatrix} h(\mathbf{x}) & 0 \\ 0 & \nu(\mathbf{x}) \end{pmatrix}.$$

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Such operator with $\nu(\mathbf{x}) = 1$ arises in the study of the Maxwell equations in the case where the magnetic permeability is constant.

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Suppose that the bottom of the spectrum of the operator $A = \mathbf{D}^* g(\mathbf{x}) \mathbf{D} + V(\mathbf{x})$ is the point $\lambda = 0$. Then there exists a positive Γ -periodic solution $\omega(\mathbf{x})$ of the equation $A\omega = 0$. The operator A_ε admits the following factorization

$$A_\varepsilon = (\omega^\varepsilon)^{-1} \mathbf{D}^* (\omega^\varepsilon)^2 g^\varepsilon \mathbf{D} (\omega^\varepsilon)^{-1}.$$

- The two-dimensional **Pauli operator**

$$A_\varepsilon = \begin{pmatrix} P_{-, \varepsilon} & 0 \\ 0 & P_{+, \varepsilon} \end{pmatrix}, \quad P_{\pm, \varepsilon} = (\mathbf{D} - \varepsilon^{-1} \mathbf{a}^\varepsilon(\mathbf{x}))^2 \pm \varepsilon^{-2} b^\varepsilon(\mathbf{x}).$$

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Here the magnetic potential $\mathbf{a}(\mathbf{x})$ is Γ -periodic Lipschitz \mathbb{R}^2 -valued function such that $\operatorname{div} \mathbf{a} = 0$, $\int_\Omega \mathbf{a} \, d\mathbf{x} = 0$. Next, $b = \partial_1 a_2 - \partial_2 a_1$.

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$$A_\varepsilon = f^\varepsilon b(\mathbf{D}) g^\varepsilon b(\mathbf{D}) f^\varepsilon,$$

with $m = n = 2$, $g(\mathbf{x}) = f(\mathbf{x})^2$,

$$b(\mathbf{D}) = \begin{pmatrix} 0 & D_1 - iD_2 \\ D_1 + iD_2 & 0 \end{pmatrix}, \quad f(\mathbf{x}) = \begin{pmatrix} e^{\varphi(\mathbf{x})} & 0 \\ 0 & e^{-\varphi(\mathbf{x})} \end{pmatrix}.$$

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