

# Navier-Stokes equations with constrained $L^2$ energy of the solution

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joint works with Mauro Mariani (Roma 1) and Gaurav Dhariwal (York)

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- Caglioti *et.al* [5] studied 2D NSEs in  $\mathbb{R}^2$  with constraints

$$E(\omega) = \int_{\mathbb{R}^2} \psi(x) \omega(x) dx = \int_{\mathbb{R}^2} |u(x)|^2 dx = a,$$

$$I(\omega) = \int_{\mathbb{R}^2} |x|^2 \omega(x) dx = b,$$

where

$$\omega = \operatorname{curl} u, \quad \psi = -(\Delta)^{-1} \omega.$$

- They proved that for a certain stationary solution  $\omega_{MF}$  of the Euler equation (in the vorticity form) with constraints  $a, b$ , for every initial data  $\omega_0$  "close enough"  $\omega_{MF}$  with the same constraints  $a, b$ ;

$$\omega(t) \rightarrow \omega_{MF}, \text{ as } t \rightarrow \infty,$$

where  $\omega(t)$  is the solution of the NSEs (in the vorticity form) with initial data  $\omega_0$  and the same constraints.

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- Rybka [7] and Caffarelli & Lin [4] studied heat equation with constraint

$$|u|_{L^2} = 1. \quad (1)$$

- The heat equation is given by

$$\frac{\partial u}{\partial t} = -A u, \quad (2)$$

where  $A u = -\Delta u$  is a self adjoint operator on  $H$ .

- We define a Hilbert manifold

$$\mathcal{M} = \{u \in H : |u|_H = 1\}. \quad (3)$$

- Note that  $A u \notin T_u \mathcal{M}$  for  $u \in \mathcal{M}$  but  $\Pi_u(-A u) \in T_u \mathcal{M}$  for every  $u \in \mathcal{M}$ , where

$$\Pi_u : H \ni x \mapsto x - \langle x, u \rangle_H u \in T_u \mathcal{M} = \{y \in H : \langle u, y \rangle_H = 0\} \quad (4)$$

is the orthogonal projection.

- Since  $\Pi_u(-A u) = -A u + |A^{1/2} u|_H^2 u$ , we get

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- A special case of heat equation with Dirichlet boundary condition

$$\begin{cases} \frac{\partial u}{\partial t} = \Delta u + |\nabla u|_{L^2}^2 u \\ u(0) = u_0 \end{cases} \quad (6)$$

- Note that the heat equation (2) can be seen as an  $L^2$ -gradient flow of energy

$$\mathcal{E}(u) = \frac{1}{2} \int_{\mathcal{O}} |\nabla u(x)|^2 dx, \quad (7)$$

as formally

$$-\nabla_{L^2} \mathcal{E}(u) = \Delta u.$$

- Similarly, the constrained heat equation (6) can be seen as the gradient flow of  $\mathcal{E}$  restricted to the manifold  $\mathcal{M}$  with  $L^2$ -metric on the "tangent bundle".

In fact one can prove that the solution of (6) with  $u_0 \in H_0^1(\mathcal{O}) \cap \mathcal{M}$  satisfies

$$\mathcal{E}(u(t)) + \int_0^t |\Delta u(s) + |\nabla u|_{L^2}^2 u(s)|_{L^2}^2 ds = \mathcal{E}(u(0)) \quad (8)$$

from which one can deduce the global existence.

- An essential step in proving the global existence is to establish the invariance of  $\mathcal{M}$ .

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We consider NSEs

$$\begin{cases} \frac{\partial u}{\partial t} + Au + B(u, u) = 0 \\ u(0) = u_0 \end{cases} \quad (9)$$

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$$\begin{cases} \frac{\partial u}{\partial t} - \nu \Delta u + u \cdot \nabla u + \nabla p = 0, \\ \operatorname{div} u = 0, \\ u(0, \cdot) = u_0(\cdot). \end{cases}$$

Here

$$B(u, u) = \Pi(u \cdot \nabla u) \quad (10)$$

where  $\Pi : L^2(\mathcal{O}) \rightarrow H$  is the orthogonal projection.

$$\begin{aligned} H = \{ & u \in L^2(\mathcal{O}) : \operatorname{div} u = 0 \\ & \text{and } u|_{\partial\mathcal{O}} \cdot n = 0 \quad (\text{Dirichlet b.c.}) \\ & \text{or } \int_{\mathcal{O}} u(x) dx = 0 \quad (\text{Torus}) \} \end{aligned} \quad (11)$$

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- We put  $\mathcal{M} = \{u \in \mathbb{H} : |u|_{L^2} = 1\}$ .
- The projected version of (9) can be found in a similar way as before.
- Note

$$\Pi_u(B(u, u)) = B(u, u) - \underbrace{\langle B(u, u), u \rangle_{\mathbb{H}}}_{=0} u = B(u, u). \quad (12)$$

So we get

$$\begin{cases} \frac{\partial u}{\partial t} + Au + B(u, u) = |\nabla u|_{L^2}^2 u \\ u(0) = u_0 \in V \cap \mathcal{M}, \end{cases} \quad (13)$$

where  $V = H_0^{1,2} \cap \mathcal{M}$  or  $H^{1,2} \cap \mathcal{M}$ .

- We can show existence of a local maximal solution  $u(t), t < \tau$  which lies on  $\mathcal{M}$ .
- However to prove the global existence one needs to assume that we deal with periodic boundary conditions (or torus), because then

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$$\|u\|_V^2 = |u|_H^2 + |\nabla u|_{L^2}^2 = |u|_H^2 + 2\mathcal{E}(u)$$

and the  $L^2$ -norm of  $u(t)$  doesn't explode. In order to show that  $\|u(t)\|_V^2$  doesn't explode, it suffices to show that  $|\nabla u(t)|_{L^2}$  neither does.

- Formally, we have

$$\begin{aligned} \frac{1}{2} \frac{d}{dt} |\nabla u(t)|_{L^2}^2 &= \langle u', Au \rangle_{L^2} = \langle -Au - B(u, u) + |\nabla u|_{L^2}^2 u, Au \rangle_{L^2} \\ &= -|Au|_{L^2}^2 + |\nabla u|_{L^2}^4. \end{aligned} \quad (14)$$

- But recall

$$\nabla_{\mathcal{M}} \mathcal{E}(u) = \Pi_u(\nabla_u \mathcal{E}(u)) = \Pi_u(Au) = Au - |\nabla u|_{L^2}^2 u. \quad (15)$$

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- Hence  $|Au|_{L^2}^2 - |\nabla u|_{L^2}^4 \geq 0$  and

$$\frac{1}{2}|\nabla u(t)|_{L^2}^2 + \int_0^t |\nabla_{\mathcal{M}}\mathcal{E}(u(s))|_{L^2}^2 ds = \frac{1}{2}|\nabla u_0|_{L^2}^2, \quad t \in [0, T]. \quad (17)$$

Thus we can summarise our results in the following theorem :

## Theorem 1

*For every  $u_0 \in V \cap \mathcal{M}$  there exists a unique global solution  $u$  of the constrained NSEs (13) such that  $u \in X_T$  for all  $T > 0$ .*

Here  $X_T = \mathcal{C}([0, T]; V) \cap L^2(0, T; D(A))$ .



- We assume that  $W = (W_1, \dots, W_m)$  is  $\mathbb{R}^m$ -valued Wiener process,  $c_1, \dots, c_m$  and  $\hat{C}_1, \dots, \hat{C}_m$  are respectively vector fields and associated linear operators given by

$$\hat{C}_j u = c_j(x) \cdot \nabla u, \quad \operatorname{div} c_j = 0, \quad j \in \{1, \dots, m\}.$$

- Since

$$C_j u = \Pi \hat{C}_j u, \quad j \in \{1, \dots, m\},$$

is skew symmetric in  $H$ , these operators don't produce any correction term when projected on  $T_u \mathcal{M}$ .

- Thus the stochastic NSE

$$du + [A u + B(u, u)] dt = \sum_{j=1}^m C_j u \circ dW_j = \underbrace{\sum_{j=1}^m C_j u dW_j + \frac{1}{2} \sum_{j=1}^m C_j^2 u dt}_{\text{Stratonovich} = \text{Itô} + \text{correction}}$$

under the constraint is given by

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- We assume that  $W = (W_1, \dots, W_m)$  is  $\mathbb{R}^m$ -valued Wiener process,  $c_1, \dots, c_m$  and  $\hat{C}_1, \dots, \hat{C}_m$  are respectively vector fields and associated linear operators given by

$$\hat{C}_j u = c_j(x) \cdot \nabla u, \quad \operatorname{div} c_j = 0, \quad j \in \{1, \dots, m\}.$$

- Since

$$C_j u = \Pi \hat{C}_j u, \quad j \in \{1, \dots, m\},$$

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## Definition 2

We say that there exists a **martingale solution** of (18) iff there exist

- a stochastic basis  $(\hat{\Omega}, \hat{\mathcal{F}}, \hat{\mathbb{F}}, \hat{\mathbb{P}})$  with filtration  $\hat{\mathbb{F}} = \{\hat{\mathcal{F}}_t\}_{t \geq 0}$ ,
- an  $\mathbb{R}^m$ -valued  $\hat{\mathbb{F}}$ -Wiener process  $\hat{W}$ ,
- and an  $\hat{\mathbb{F}}$ -progressively measurable process  $u : [0, T] \times \hat{\Omega} \rightarrow V \cap \mathcal{M}$  with  $\hat{\mathbb{P}}$ -a.e. paths

$$u(\cdot, \omega) \in \mathcal{C}([0, T]; V_w) \cap L^2(0, T; D(A)),$$

such that for all  $t \in [0, T]$  and all  $v \in D(A)$ :

$$\begin{aligned} \langle u(t), v \rangle + \int_0^t \langle Au(s), v \rangle ds + \int_0^t \langle B(u(s)), v \rangle ds &= \langle u_0, v \rangle \\ + \int_0^t |\nabla u(s)|_{L^2}^2 \langle u(s), v \rangle ds + \frac{1}{2} \int_0^t \sum_{j=1}^m \langle C_j^2 u(s), v \rangle ds &+ \int_0^t \sum_{j=1}^m \langle C_j u(s), v \rangle dW_j, \end{aligned} \tag{19}$$

the identity hold  $\hat{\mathbb{P}}$ -a.s.

## Theorem 3 (Assume that our domain is the 2-d torus)

Then for every  $u_0 \in V \cap \mathcal{M}$ , there exists a martingale solution to the stochastic constrained NSEs (18).

Sketch of the proof : Galerkin approximation :

Let  $\{e_j\}$  be ONB of  $H$  and eigenvectors of  $A$ .

$H_n := \text{lin}\{e_1, \dots, e_n\}$  is the finite dimensional Hilbert space

$P_n : H \rightarrow H_n$  be the orthogonal projection operator given by  $P_n u = \sum_{i=1}^n \langle u, e_i \rangle e_i$ .

We consider the following "projection" of onto  $H_n$ :

$$\begin{cases} du_n &= - [P_n A u_n + P_n B(u_n) - |\nabla u_n|_{L^2}^2 u_n] dt + \sum_{j=1}^m P_n C_j u_n \circ dW_j, \quad t \geq 0, \\ u_n(0) &= \frac{P_n u_0}{|P_n u_0|_{L^2}}, \quad \text{for } n \text{ large enough} \end{cases} \quad (20)$$

We fix  $T > 0$ . Equation (20) is a stochastic ODE on a finite dimensional compact manifold  $\mathcal{M}_n = \{u \in H_n : |u|_{L^2} = 1\}$ .

Hence it has a unique  $\mathcal{M}$ -valued solution (with continuous paths). Moreover,  $\forall q \geq 2$

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These depend deeply on the property that

$$\langle B(u), Au \rangle_{\mathbb{H}} = 0, \quad u \in D(A).$$

and a very specific assumption

- We assume  $c_1, \dots, c_m$  are constant vector fields.

Let  $K_c = \max_{j \in 1, \dots, m} |c_j|_{\mathbb{R}^2}$ .

## Lemma 4

Let  $p \in \left[1, 1 + \frac{1}{K_c^2}\right)$  and  $\rho > 0$ . Then there exist positive constants  $C_1(p, \rho)$ ,  $C_2(p, \rho)$  and  $C_3(\rho)$  such that if  $\|u_0\|_{\mathbb{V}} \leq \rho$ , then

$$\sup_{n \geq 1} \mathbb{E} \left( \sup_{r \in [0, T]} \|u_n(r)\|_{\mathbb{V}}^{2p} \right) \leq C_1(p, \rho), \quad (21)$$

$$\sup_{n \geq 1} \mathbb{E} \int_0^T \|u_n(s)\|_{\mathbb{V}}^{2(p-1)} |Au_n(s) - |\nabla u_n(s)|_{L^2}^2 u_n(s)|_{\mathbb{H}}^2 ds \leq C_2(p, \rho), \quad (22)$$

and

$$\sup_{n \geq 1} \mathbb{E} \int_0^T |u_n(s)|_{D(A)}^2 ds \leq C_2(1) + C_1(2)T =: C_3(\rho). \quad (23)$$

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We put

$$\mathcal{Z}_T = \mathcal{C}([0, T]; H) \cap L_w^2(0, T; D(A)) \cap L^2(0, T; V) \cap \mathcal{C}([0, T]; V_w),$$

and  $\mathcal{T}_T$  the corresponding topology.

In order to prove that the laws of  $u_n$  are tight on  $\mathcal{Z}_T$ . Apart from a priori estimates we also need one additional property to be satisfied :

Lemma 5 (Aldous condition in H)

$\forall \varepsilon > 0, \forall \eta > 0 \exists \delta > 0$  : for every stopping time  $\tau_n : \Omega \rightarrow [0, T]$

$$\sup_{n \in \mathbb{N}} \sup_{0 \leq \theta \leq \delta} \mathbb{P}(|u_n(\tau_n + \theta) - u_n(\tau_n)|_H \geq \eta) < \varepsilon. \quad (24)$$

Lemma 5 can be proved by applying Lemma 4 to equations (20).

Corollary 6

The laws of  $(u_n)$  are tight on  $\mathcal{Z}_T$ , i.e.  $\forall \varepsilon > 0 \exists K_\varepsilon \subset \mathcal{Z}_T$  compact, such that

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By the application of the Prokhorov and the Jakubowski-Skorokhod Theorems (since  $\mathcal{Z}_T$  is not a Polish space, we need Jakubowski) we deduce that there exists a subsequence, a probability space  $(\hat{\Omega}, \hat{\mathcal{F}}, \hat{\mathbb{P}})$ ,  $\mathcal{Z}_T$ -valued random variables  $\tilde{u}_n$  such that

$$\text{Law}(\tilde{u}_n) = \text{Law}(u_n),$$

and there exists  $\tilde{u}: \hat{\Omega} \rightarrow \mathcal{Z}_T$  random variable such that

$$\tilde{u}_n \rightarrow \tilde{u} \quad \text{in } \hat{\mathbb{P}} - a.s.$$

Then, using Kuratowski Theorem, we can deduce that the sequence  $\tilde{u}_n$  satisfies the same a priori estimates as  $u_n$ . In particular  $\forall p \in [1, 1 + \frac{1}{K_c^2})$

$$\sup_{n \geq 1} \mathbb{E} \left( \sup_{r \in [0, T]} \|\tilde{u}_n(r)\|_{\mathbb{V}}^{2p} \right) \leq C_1(p), \quad (25)$$

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The choice of  $\mathcal{Z}_T$  allows to deduce that  $\forall \psi \in H(\text{or } V)$  and  $s, t \in [0, T]$ :

- (a)  $\lim_{n \rightarrow \infty} \langle \tilde{u}_n(t), P_n \psi \rangle = \langle \tilde{u}(t), \psi \rangle, \quad \tilde{\mathbb{P}}\text{-a.s.},$
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We are close to conclude the proof of Theorem 3. We are just left to deal with the Itô integral.

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Define

$$M_n(t) = \sum_{j=1}^m \int_0^t P_n C_j u_n(s) dW_j(s).$$

$M_n$  is a martingale on  $(\Omega, \mathcal{F}, \mathbb{P})$ . Moreover

$$\begin{aligned} M_n(t) &= u_n(t) - P_n u_n(0) + \int_0^t P_n A u_n(s) ds + \int_0^t P_n B(u_n(s)) ds \\ &\quad - \int_0^t |\nabla u_n(s)|_{L^2}^2 u_n(s) ds - \frac{1}{2} \sum_{j=1}^m \int_0^t (P_n C_j)^2 u_n(s) ds \end{aligned} \quad (28)$$

The equation (28) can also be used on  $(\hat{\Omega}, \hat{\mathcal{F}}, \hat{\mathbb{P}})$  to define a process  $\tilde{M}_n$ , i.e.

$$\begin{aligned} \tilde{M}_n(t) &= \tilde{u}_n(t) - P_n \tilde{u}_n(0) + \int_0^t P_n A \tilde{u}_n(s) ds + \int_0^t P_n B(\tilde{u}_n(s)) ds \\ &\quad - \int_0^t |\nabla \tilde{u}_n(s)|_{L^2}^2 \tilde{u}_n(s) ds - \frac{1}{2} \sum_{j=1}^m \int_0^t (P_n C_j)^2 \tilde{u}_n(s) ds \end{aligned} \quad (29)$$

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Using the earlier convergence results and *a priori* estimates (25), (26), we can prove that

$$\begin{aligned} \tilde{M}_n(t) \rightarrow \tilde{M}(t) &:= \tilde{u}(t) - \tilde{u}(0) + \int_0^t A\tilde{u}(s) ds + \int_0^t B(\tilde{u}(s)) ds \\ &- \int_0^t |\nabla\tilde{u}(s)|_{L^2}^2 \tilde{u}(s) ds - \frac{1}{2} \sum_{j=1}^m \int_0^t C_j^2 \tilde{u}(s) ds. \end{aligned} \quad (30)$$

From equality (30) one can deduce that

- (i)  $\tilde{M}$  is  $\tilde{\mathbb{F}}$ -martingale.
- (ii)  $\text{Cov}(\tilde{M}_n) \rightarrow \text{Cov}(\tilde{M}) = \sum_{j=1}^m \int_0^t C_j \tilde{u}(s) (C_j \tilde{u}(s))^* ds$ .

This allows to use the martingale representation theorem to deduce that there exists a bigger probability space  $(\bar{\Omega}, \bar{\mathcal{F}}, \bar{\mathbb{P}}, \bar{\mathbb{P}})$  and a Wiener process  $\bar{W}$  on the same probability space such that

$$\bar{M}(t) = \int_0^t \sum_{j=1}^m C_j \bar{u}(s) d\bar{W}_j(s).$$

Hence we proved Theorem 3.

Using the earlier convergence results and *a priori* estimates (25), (26), we can prove that

$$\begin{aligned} \tilde{M}_n(t) &\rightarrow \tilde{M}(t) := \tilde{u}(t) - \tilde{u}(0) + \int_0^t A\tilde{u}(s) ds + \int_0^t B(\tilde{u}(s)) ds \\ &\quad - \int_0^t |\nabla\tilde{u}(s)|_{L^2}^2 \tilde{u}(s) ds - \frac{1}{2} \sum_{j=1}^m \int_0^t C_j^2 \tilde{u}(s) ds. \end{aligned} \quad (30)$$

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Hence we proved Theorem 3.










## Theorem 7

*Pathwise Uniqueness holds for the the stochastic constrained NSEs (18).*

## Theorem 8

*The stochastic constrained NSEs (18) have a unique strong solution for each  $u_0 \in \mathbb{V} \cap \mathcal{M}$ . Moreover, the paths of this solution belong to the space  $X_T$  for all  $T > 0$ . In particular, the paths are  $\mathbb{V}$ -valued continuous (strongly and not only weakly).*

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