

# Burgers equation with random forcing

Yuri Bakhtin

Courant Institute, NYU

August 2018

# Burgers equation

$$u_t + uu_x = \nu u_{xx} + f, \quad (x, t) \in \mathbb{R} \times \mathbb{R}$$

$\nu \geq 0$  : viscosity

In this talk: space-time random  $f$  averaging to 0

- Invariant distributions
- Global stationary solutions
- One Force — One Solution Principle (1F1S)
- Infinite-volume limits for associated directed polymers ( $\nu > 0$ ) and action minimizers ( $\nu = 0$ )
- $\nu \downarrow 0$
- Compact/periodic case (1990's–2000's )
- Noncompact case (2010's)
- We will start with reminders about Burgers equation

# Burgers equation: fluid dynamics interpretation

Evolution of velocity field  $u$  in  $\mathbb{R}^1$

$$u_t + uu_x = \nu u_{xx} + f, \quad (t, x) \in \mathbb{R} \times \mathbb{R}$$

l.h.s. = acceleration of particle at  $(t, x)$ :

$$\dot{x}(t) = u(t, x(t))$$

$$\ddot{x}(t) = (\text{chain rule}) = u_t + u_x \dot{x} = u_t + uu_x$$

- $\nu = 0$ : particles do not interact until they bump into each other creating shock waves.
- $\nu > 0$ : smoothing of the velocity profile

Energy: pumped in by  $f$ , dissipated through friction



# Burgers equation: via HJ equation

$$u_t + uu_x = \nu u_{xx} + f$$

$$u = U_x, \quad f = F_x$$

HJ with quadratic Hamiltonian; KPZ

$$U_t + \frac{(U_x)^2}{2} = \nu U_{xx} + F, \quad (t, x) \in \mathbb{R} \times \mathbb{R}$$

$F$  : external potential. If space-time white noise, then KPZ

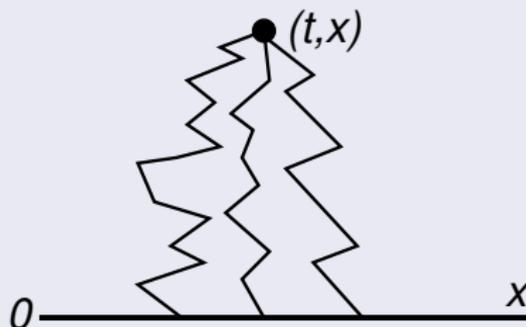
# Cauchy problem for $\nu > 0$

Hopf–Cole substitution (1950-1951), also Florin (1948)

$$u = U_x = -2\nu(\log v)_x \quad \implies \quad v_t = \nu v_{xx} - \frac{F}{2\nu} v$$

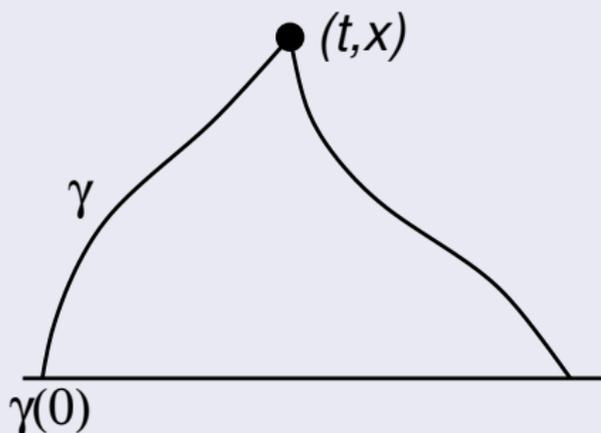
Feynman–Kac formula

$$v(t, x) = \mathbb{E} \left[ e^{-\frac{1}{2\nu} \int_0^t F(t-s, x + \sqrt{2\nu} W_s) ds} v(0, x + \sqrt{2\nu} W_t) \right]$$



# HJBHLO variational principle for $\nu = 0$

$$U(t, x) = \inf_{\substack{\gamma: [0, t] \rightarrow \mathbb{R} \\ \gamma(t) = x}} \left\{ U_0(\gamma(0)) + \frac{1}{2} \int_0^t \dot{\gamma}^2(s) ds + \int_0^t F(s, \gamma(s)) ds \right\}.$$



$$u(t, x) = \begin{cases} U_x(t, x) \\ \dot{\gamma}(t). \end{cases}$$

**Euler–Lagrange equation**

$$\ddot{\gamma}(t) = f(t, \gamma(t))$$

$F = 0 \implies$  straight lines

# Ergodic theory for random forcing, inviscid case

E,Khanin,Mazel,Sinai (Ann.Math. 2000)

Potential forcing on the circle  $\mathbb{T}^1$ :

$$F(t, x) = \sum F_j(x) \dot{W}_j(t)$$

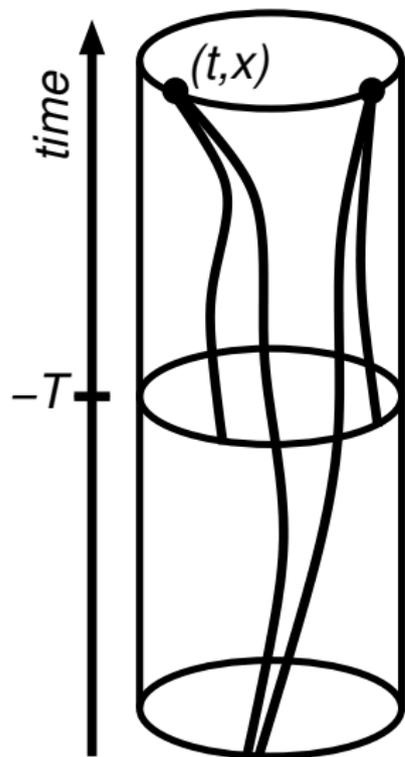
## Theorem

*Ergodic components:*

$$\left\{ u : \int_{\mathbb{T}^1} u = c \right\}$$

*One Force – One Solution Principle (1F1S) on each component.*

# One Force – One Solution (1F1S)



Initial conditions at time  $-T$ :  
identical 0 or other. Take  $-T$  to  $-\infty$ .

Slope stabilizes to some  $u(t, x)$ ,  
global attracting solution

$u(t, x) = \Phi(\text{forcing in the past})$   
 $Law(u(t, x)) = \text{stationary distribution}$

Hyperbolicity: exponential closeness of  
minimizers in reversed time.

Solutions of HJB: Busemann functions

Bounds on velocity of minimizers

# Invariant measures for Markov processes generated by random dynamical systems

## Ledrappier–Young (1980's)

In general, any invariant measures of a Markov process generated by a random dynamical system can be represented via *sample measures*

$$\mu(\cdot) = \int_{\Omega} \mathbf{P}(d\omega) \mu_{\omega}(\cdot),$$

where  $\mu_{\omega}$  depends only on  $\omega|_{(-\infty, 0]}$

## 1F1S

$\mu_{\omega}$  are Dirac  $\delta$ -measures for almost every  $\omega$ .

## Compact setting

- Gomes, Iturriaga, Khanin, Padilla (2000's): On  $\mathbb{T}^d$
- Bakhtin (2007): On  $[0, 1]$  with random boundary conditions
- Boritchev, Khanin (2013): Simplified proof of hyperbolicity
- Khanin, Zhang (2017): Hyperbolicity in  $\mathbb{T}^d$
- Mixing rates based on hyperbolicity: Boritchev (2018) on  $\mathbb{T}^1$ ; Iturriaga, Khanin, Zhang (recent) on  $\mathbb{T}^d$ :
- Hairer, Mattingly(2018) Strong Feller property for space-time white-noise KPZ
- Dirr, Souganidis (2005), Debussche and Vovelle (2015): extensions by “PDE methods”
- Chueshov, Scheutzow, Flandoli, Gess(2004,...) Synchronization by noise in monotone systems

# Noncompact Setting

## Quasi-compact setting

Hoang, Khanin (2003), Suidan (2005), Bakhtin (2013)

## Truly noncompact setting

Two models where ergodic program goes through.

- Bakhtin, Cator, Khanin (JAMS 2014): space-time homogeneous Poissonian forcing
- Bakhtin (EJP, 2016): space-homogeneous i.i.d. kick forcing

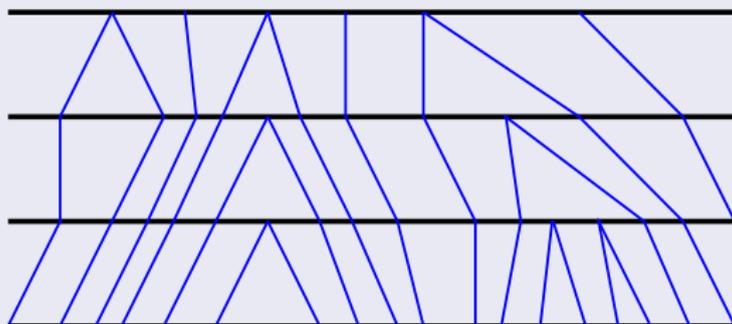
# Space-continuous kick forcing

Forcing applies only at times  $n \in \mathbb{Z}$

$$F(t, x) = \sum_{n \in \mathbb{Z}} F_{n, \omega}(x) \delta(t - n),$$

$(F_n)_{n \in \mathbb{Z}}$ : i.i.d., stationary, decorrelation, tails

$$\text{Action}(\gamma) = U(\gamma(0)) + \frac{1}{2} \sum_{k=m}^{n-1} (\gamma_{k+1} - \gamma_k)^2 + \sum_{k=m}^{n-1} F_{k, \omega}(\gamma_k)$$



# Minimizers (geodesics) for FPP,LPP-type models; Busemann functions

- C.D.Howard, C.M.Newman (late 1990's)
- M.Wüthrich (2002)
- E.Cator, L.Pimentel (2010–2012)

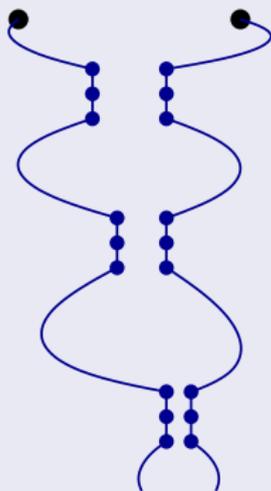
## Theorem

- *For each  $v \in \mathbb{R}$  there is a unique global solution  $u_v(t, x)$  with average velocity  $v$ .*
- *$u_v(t, \cdot)$  is determined by the history of the forcing up to  $t$  (1F1S)*
- *$u_v$  is a one-point pullback attractor for initial conditions with average velocity  $v$ .*
- *For any  $t$ ,  $u_v(t, x)$  is a stationary mixing process in  $x$ .*

## Theorem

Let  $v \in \mathbb{R}$ . Then, with probability one:

- For most  $(t, x)$  there is a unique one-sided minimizer with slope  $v$ . Finite minimizers converge to infinite ones.
- $\liminf_{m \rightarrow -\infty} \frac{|\gamma_m^1 - \gamma_m^2|}{|m|^{-1}} = 0$ .
- Busemann functions and global solutions are uniquely defined by partial limits



# Shape function for point-to-point minimizers

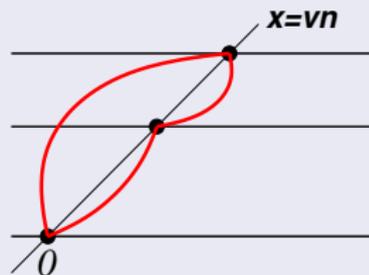
Best p2p action:  $A^{m,n}(x, y) = \inf \{A^{m,n}(\gamma) : \gamma_m = x, \gamma_n = y\}$

Subadditivity:

$$A^{0,n}(0, vn) \leq A^{0,m}(0, vm) + A^{m,n}(vm, vn)$$

so

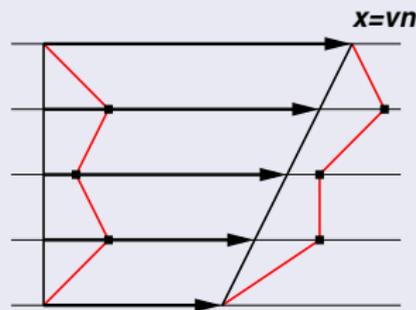
$$\lim_{t \rightarrow \infty} \frac{A^{0,n}(0, vn)}{n} = \alpha(v)$$



Shape function  $\alpha$   
(effective Lagrangian)

$$\alpha(v) = \alpha(0) + \frac{v^2}{2}$$

(due to shear invariance)

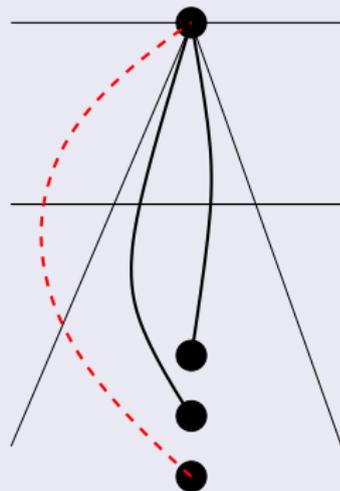
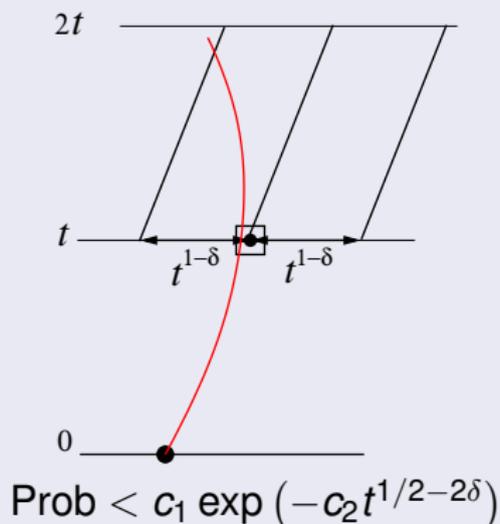


# Deviations from linear growth, straightness, existence

## Theorem

For  $u \in (c_3 n^{1/2} \ln^2 n, c_4 n^{3/2} \ln n]$ ,

$$P \left\{ |A^{0,n}(0, vn) - \alpha(v)n| > u \right\} \leq c_1 \exp \left\{ -c_2 \frac{u}{n^{1/2} \ln n} \right\},$$



# The rest of the program for zero viscosity/temperature

- Uniqueness, with countably many exceptions (shocks) — uses shear invariance
- Weak hyperbolicity (minimizers approach each other in reverse time) — a soft lack-of-space argument
- Global solutions as Busemann functions for partial limits
- 1F1S: uniqueness of solution, attraction.
  - Potentials converge in LU;
  - $x \mapsto x - u(x)$  is a monotone function with discontinuities; convergence at every continuity point.

$$u_t + uu_x = \nu u_{xx} + f$$

## Compact case

Sinai (1991), Gomes, Iturriaga, Khanin, Padilla (2000's)

## Non-compact case: Kifer (1997)

$\mathbb{R}^d$ ,  $d \geq 3$ , small forcing,  
perturbation theory series  
(weak disorder)

# Randomly kicked Burgers equation, $\nu > 0$

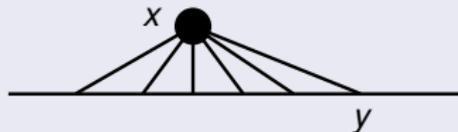
$$u_t + uu_x = \nu u_{xx} + \sum_{n \in \mathbb{Z}} f_n(x) \delta_n(t)$$

$$\text{Hopf-Cole: } u = -2\nu(\ln v)_x = -2\nu v_x/v$$

$$\begin{aligned} v(1-, x) &= \int_{\mathbb{R}} \frac{e^{-\frac{(x-y)^2}{4\nu}}}{\sqrt{4\nu}} e^{-\frac{F_{0,\omega}(y)}{2\nu}} v(0-, y) dy \\ &= \int_{\mathbb{R}} \frac{e^{-\frac{(x-y)^2}{4\nu}}}{\sqrt{4\nu}} e^{-\frac{F_{0,\omega}(y)}{2\nu} - \frac{U(0-, y)}{2\nu}} dy \end{aligned}$$

$$u(1-, x) = \int_{\mathbb{R}} (x-y) \mu_x(dy)$$

$$\mu_x(dy) = \frac{e^{-\frac{(x-y)^2}{4\nu} - \frac{U(0,y)}{2\nu}} dy}{Z_x}$$



## Feynman–Kac evolution operator

$$\Psi_{\omega}^{0,n} v(y) = \int_{\mathbb{R}} Z_{\omega}^{0,n}(x, y) v(x) dx, \quad y \in \mathbb{R}$$

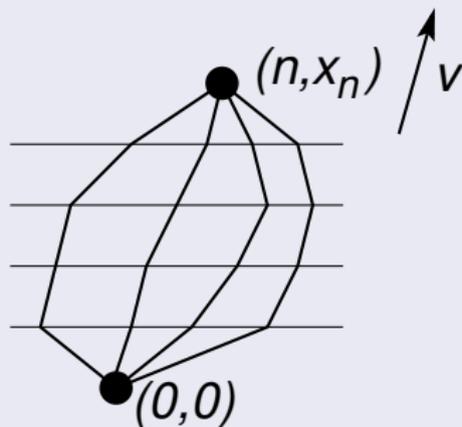
Point-to-point partition function:

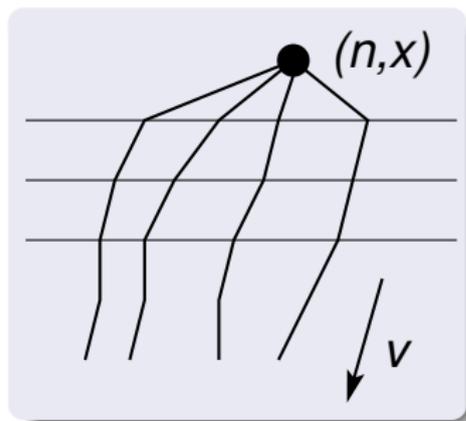
$$Z_{\omega}^{0,n}(x_0, x_n) = \int_{\mathbb{R}} \cdots \int_{\mathbb{R}} \prod_{k=0}^{n-1} \left[ \frac{e^{-\frac{(x_{k+1}-x_k)^2}{4\nu}}}{\sqrt{4\pi\nu}} e^{-\frac{F_{k,\omega}(x_k)}{2\nu}} \right] dx_1 \cdots dx_{n-1}$$

[Similar to product of positive random matrices]

# Burgers Polymers Thermodynamic limit?

$$\mu_{x_0, x_n, \omega}^{0, n}(dx_1 \dots dx_{n-1}) = \frac{\prod_{k=0}^{n-1} \left[ \frac{e^{-\frac{(x_{k+1} - x_k)^2}{4\nu}}}{\sqrt{4\pi\nu}} e^{-\frac{F_{k, \omega}(x_k)}{2\nu}} \right]}{Z_{\omega}^{0, n}(x_0, x_n)} dx_1 \dots dx_{n-1}$$





## Theorem (Bakhtin, Li: CPAM, 2018)

Fix any  $v \in \mathbb{R}$ . With probability 1,

- If  $\lim_{m \rightarrow -\infty} \frac{x_m}{m} = v$ , then

$$\lim_{m \rightarrow -\infty} \mu_{x_n, x, \omega}^{m, n} = \mu_\omega$$

[Also point-to-line limits]

- $\mu_\omega$  is a unique infinite volume polymer measure (DLR condition) with endpoint  $(n, x)$  and slope  $v$ :

$$\mu_\omega \left\{ \gamma : \lim_{m \rightarrow -\infty} \frac{\gamma_m}{m} = v \right\} = 1$$

- Asymptotic overlap of infinite volume polymer measures

# Free energy per unit time

$$\lim_{n \rightarrow \infty} \left( -2\nu \frac{\ln Z^{0,n}(0, \nu n)}{n} \right) \stackrel{\text{a.s.}}{=} \alpha_\nu(\nu) = \alpha_\nu + \frac{\nu^2}{2}$$

Shear invariance

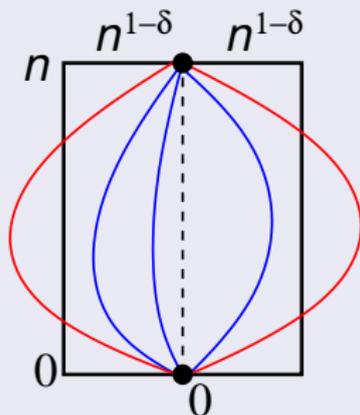
Concentration inequality

# A straightness estimate for polymers

## Lemma

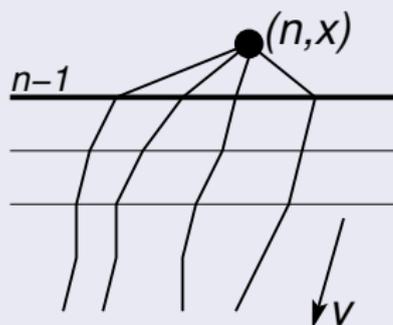
Let  $\delta \in (0, 1/4)$ . There are  $\alpha, \beta > 0$ : for large  $n$ ,

$$\mathbb{P} \left\{ \omega : \mu_{0,0,\omega}^{0,n} \left\{ \gamma : \max_{0 \leq k \leq n} |\gamma_k| > n^{1-\delta} \right\} \geq e^{-n^\alpha} \right\} \leq e^{-n^\beta}.$$



First result on transversal exponent  $\xi \leq 3/4$ : Mejane (2004)

# Stationary solutions for viscous Burgers



$S(dy)$  := distribution of the polymer location at time  $n - 1$

$$u_v(n, x) := \int_{\mathbb{R}} (x - y) S(dy)$$

## Theorem

- $u_v$  is a unique global solution with slope  $v$ .
- 1F1S: LU-convergence for  $u$ . In terms of the heat equation: the role of Busemann function is played by convergent ratios of partition functions.

# Zero viscosity (zero-temperature) limit

## Theorem (Bakhtin, Li: JSP, 2018)

As  $\nu \rightarrow 0$ ,

- *one-sided polymers converge to one-sided minimizers*
- *Global solutions of Burgers equation converge to inviscid global solutions [convergence at every continuity point of the monotone function  $x \mapsto x - u(x)$ ]*

Based on tightness.

Events of interest are of the form: {for all  $\nu, \dots$ }

# Relevant recent results for discrete FPP/LPP/polymers

In discrete settings, Busemann functions and stationary solutions for positive and zero temperature polymers were studied by Rassoul-Agha, Georgiou, Seppäläinen, Yilmaz

- More general HJB equations and Lax–Oleinik semigroups.
- General HJB equations with positive viscosity: generalized directed polymers via stochastic control
- Continuous non-white forcing, no shear invariance
- Higher dimensions: which form of hyperbolicity?
- Quantitative results
- KPZ equation, KPZ universality. CLT for solutions of Burgers HJB
- Statistics of shocks and concentration of minimizers
- Stochastic Navier–Stokes in noncompact setting

[Bakhtin, Khanin: Nonlinearity, 2018]