



EXAMINATION PAPER

Examination Session: May	Year: 2017	Exam Code: MATH3021-WE01
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Title: Differential Geometry III
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Time Allowed:	3 hours	
Additional Material provided:	None	
Materials Permitted:	None	
Calculators Permitted:	No	Models Permitted: Use of electronic calculators is forbidden.
Visiting Students may use dictionaries: No		

Instructions to Candidates:	Credit will be given for: the best FOUR answers from Section A and the best THREE answers from Section B. Questions in Section B carry TWICE as many marks as those in Section A.
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Revision:	
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SECTION A

1. Let α be a plane curve given by

$$\alpha(s) = (s^2, \frac{1}{s^2}), s > 0.$$

- (a) Show that α is a regular curve.
- (b) Calculate the curvature of α .
- (c) Find the vertices of α .

2. Let $\alpha : I \rightarrow \mathbb{R}^2$ be a plane regular curve. Here I is an open interval in \mathbb{R} .

- (a) Define the centre of curvature of α at $u \in I$.
- (b) Let κ be the curvature of α , and suppose that $\kappa(u_0) \neq 0$. Denote by \mathbf{p} the centre of curvature of α at u_0 , and define a function $g : I \rightarrow \mathbb{R}$ by

$$g(u) = \|\alpha(u) - \mathbf{p}\|^2$$

Show that $g'(u_0) = g''(u_0) = 0$.

- (c) Define the evolute of α . Find the evolute of the parabola $\alpha(u) = (u, u^2)$, $u \in \mathbb{R}$.

3. Let $S = \{(x, y, z) \in \mathbb{R}^3 \mid x^2 + y^2 = 1\}$ be a cylinder.

- (a) Let $\theta_0 \in (0, \pi/2)$ be given. Find a regular curve $\alpha : \mathbb{R} \rightarrow S$ through the point $(1, 0, 0) \in S$ forming the constant angle θ_0 with all parallels of S .
- (b) Assuming the curve α from part (a) is parametrised by arc length, show that α is a geodesic.

4. Let $\alpha : I \rightarrow \mathbb{R}^3$ be a regular curve parametrised by arc length with nowhere vanishing curvature. Here I is an open interval in \mathbb{R} . The *normal plane* through $\alpha(u)$ is the plane spanned by the unit normal and binormal vectors $\mathbf{n}(u)$ and $\mathbf{b}(u)$. Assume all normal planes of α pass through a point $\mathbf{p}_0 \in \mathbb{R}^3$.

- (a) Show that α lies in a sphere centred at \mathbf{p}_0 .
- (b) Express the coefficients $\lambda(u), \mu(u), \nu(u)$ in the decomposition

$$\alpha(u) - \mathbf{p}_0 = \lambda(u)\mathbf{t}(u) + \mu(u)\mathbf{n}(u) + \nu(u)\mathbf{b}(u)$$

in terms of the curvature $\kappa(u)$, the torsion $\tau(u)$ and their derivatives. (Here $\mathbf{t}(u)$ denotes the unit tangent vector.)

5. Let $\mathbf{x} : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ be a parametrisation of a surface S in \mathbb{R}^3 .

- (a) Define the Gauss map \mathbf{N} of S .
- (b) Calculate the Gauss map of $\mathbf{x}(u, v) = (u, v, (u + v)^2)$.
- (c) Determine the image of the Gauss map of \mathbf{x} defined as in (b).

6. (a) Define the Weingarten map and the second fundamental form of a surface $S \subset \mathbb{R}^3$ with local parametrisation $\mathbf{x}(u, v)$, $(u, v) \in U \subset \mathbb{R}^2$.
- (b) Let a surface S be the graph of a smooth function $f : \mathbb{R}^2 \rightarrow \mathbb{R}$. Consider the parametrisation of S by

$$\mathbf{x}(u, v) = (u, v, f(u, v)).$$

Find necessary and sufficient conditions for the second fundamental form of S to have the matrix

$$\begin{pmatrix} L & M \\ M & N \end{pmatrix} = \begin{pmatrix} f_{uu} & f_{uv} \\ f_{uv} & f_{vv} \end{pmatrix}$$

at a point $\mathbf{x}(u_0, v_0)$ with respect to the basis $\{\mathbf{x}_u, \mathbf{x}_v\}$.

- (c) A parametrisation of S is *isothermal* if the coefficients E, F, G of the first fundamental form satisfy conditions $E = G$ and $F = 0$ at every point. Show that if $\mathbf{x} : U \rightarrow S$ is an isothermal parametrisation, then

$$\mathbf{x}_{uu}(u, v) + \mathbf{x}_{vv}(u, v) = 2E(u, v)H(u, v)\mathbf{N}(\mathbf{x}(u, v)),$$

where H is the mean curvature and \mathbf{N} is the Gauss map.

SECTION B

7. Let $S^2(1) = \{(x, y, z) \in \mathbb{R}^3 \mid x^2 + y^2 + z^2 = 1\}$ be a 2-dimensional unit sphere. For $(u, v) \in \mathbb{R}^2$, let $\mathbf{x}(u, v)$ be the point of intersection of the line in \mathbb{R}^3 through $(u, v, 0)$ and $(0, 0, 1)$ with $S^2(1)$ (different from $(0, 0, 1)$). \mathbf{x} is called a *stereographic projection* of the unit sphere.

- (a) Find an explicit formula for $\mathbf{x}(u, v)$.
- (b) Let P be the plane given by $\{z = 1\}$, and for $(x, y, z) \in \mathbb{R}^3 \setminus P$, let $\mathbf{F}(x, y, z) \in \mathbb{R}^2$ be such that $(\mathbf{F}(x, y, z), 0) \in \mathbb{R}^3$ is the intersection with the (x, y) -plane of the line through $(0, 0, 1)$ and (x, y, z) . Show that

$$\mathbf{F}(x, y, z) = \frac{1}{1 - z}(x, y).$$

- (c) Show that $\mathbf{F} \circ \mathbf{x} = \text{id} : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ and deduce that \mathbf{x} is a local parametrisation of $S^2(1) \setminus \{(0, 0, 1)\}$.
- (d) Show that \mathbf{x} is conformal.
8. (a) Let α be a regular curve contained in a surface $S \subset \mathbb{R}^3$. Define its normal curvature κ_n .
- (b) Assume that S has positive Gauss curvature. Show that the normal curvature κ_n of α is nowhere vanishing.
- (c) Assume that S has negative Gauss curvature. Let $p \in S$. Show that there exists a parametrised curve α in S containing p which has positive normal curvature κ_n at p .
9. (a) Give the definition of a minimal surface in \mathbb{R}^3 .
- (b) Show that the catenoid $\mathbf{x}(u, v) = (a \cosh v \cos u, a \cosh v \sin u, av)$, where $u \in (0, 2\pi)$, $v \in \mathbb{R}$ and $a > 0$ is a constant, is a minimal surface in \mathbb{R}^3 .
- (c) Assume that $S \subset \mathbb{R}^3$ is a minimal surface with nowhere vanishing Gauss curvature. Show that the Gauss map on S is conformal and find the conformal factor.
10. (a) State the global Gauss–Bonnet theorem explaining all the notations which you use.
- (b) Let $S \subset \mathbb{R}^3$ be a ruled surface. Show that the Gauss curvature K of S is nowhere positive.
- (c) Let S be as in (b) and assume, in addition, that S is homeomorphic to the plane and $K \neq 0$ in any point of S . Show that a geodesic on S cannot be self-intersecting.
- (d) Under the assumptions of (c), show that two different geodesics cannot have more than one point of intersection.