



## EXAMINATION PAPER

<b>Examination Session:</b> May/June	<b>Year:</b> 2020	<b>Exam Code:</b> MATH3091-WE01
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<b>Title:</b> Dynamical Systems III
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Time (for guidance only):	3 hours	
Additional Material provided:		
Materials Permitted:		
Calculators Permitted:	Yes	Models Permitted: There is no restriction on the model of calculator which may be used.

Instructions to Candidates:	<p>Credit will be given for your answers to all questions. All questions carry the same marks.</p> <p>Please start each question on a new page. Please write your CIS username at the top of each page.</p> <p>Show your working and explain your reasoning.</p>	
	<b>Revision:</b>	

**Q1** Consider the following dynamical system

$$\begin{cases} x_1' = x_1 - e^{x_2} \\ x_2' = \log |x_2| \end{cases}$$

**1.1** Find the critical points of this system.

**1.2** Are the critical points you found in part **1.1** hyperbolic?

Now consider a one-dimensional dynamical system  $x' = f(x, \mu)$  with  $f(x, \mu)$  infinitely differentiable in both of its arguments.

**1.3** State necessary conditions for the system to undergo a local bifurcation at a point  $(x_*, \mu_*)$ .

Consider now  $f(x, \mu) = (x^2 - \mu^2)(x^2 - (\mu + 2)^2)$ .

**1.4** Work out the conditions under part **1.3** and find all bifurcation points.

**1.5** Draw a bifurcation diagram. State the type of all the bifurcation points.

**Q2 2.1** Consider the ordinary differential equation

$$x''' = x'' + 2x'$$

and verify that it is equivalent to the following linear dynamical system

$$\mathbf{x}' = A \cdot \mathbf{x} \quad A = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 2 & 1 \end{pmatrix}$$

**2.2** Determine the matrix  $U$  such that  $J(A) = U^{-1}AU$  is in Jordan normal form. Verify your answer by computing its inverse and checking that this is indeed the case.

**2.3** Determine the phase flow of the linear system  $\mathbf{x}(t)$  for arbitrary values of the initial conditions

$$\mathbf{x}_0 = \begin{pmatrix} \alpha \\ \beta \\ \gamma \end{pmatrix} \quad \alpha, \beta, \gamma \in \mathbb{R}$$

**2.4** Using your result from part **2.3** above determine all possible solutions to the equation  $x''' = x'' + 2x'$  such that

(1)  $x'(0) = 0$  and  $x''(0) = 0$

(2)  $x(0) = 0$  and  $x'(0) = 0$

**Q3** In this question we will determine the phase flow of the following dynamical system on  $\mathbb{R}^2$ :

$$x' = \cos y \qquad y' = \sin x$$

**3.1** Determine the critical points of this system. It is convenient to use a pair of integers  $n, m \in \mathbb{Z}$  to label the critical points as follows

$$\mathbf{x}_{n,m} = \begin{pmatrix} x_n \\ y_m \end{pmatrix}$$

**3.2** Compute the Jacobian matrix of the vector field

$$\mathbf{f} = \begin{pmatrix} \cos y \\ \sin x \end{pmatrix}$$

and use it to determine the linearized system in a neighborhood of each critical point  $\mathbf{x}_{n,m}$ .

**3.3** Organize the Cartesian plane in a grid with vertices at the points  $\mathbf{x}_{n,m}$ . Associate to each critical point of the grid its corresponding local flow and complete the qualitative picture of the phase flow, remembering that flow lines never cross.

**3.4** Determine the invariant sets for this system.

**Q4** Consider a smooth planar system

$$\begin{aligned} x' &= f(x, y) \\ y' &= g(x, y) \end{aligned}$$

**4.1** Define what it means for such a system to be Hamiltonian.

**4.2** Assume the above system is Hamiltonian. Introduce new coordinates by an invertible linear map of the form

$$\begin{aligned} z &= ax + by \\ w &= cx + dy \end{aligned}$$

Show that the system written in terms of  $z, w$  is again Hamiltonian, and find its Hamiltonian  $\tilde{H}(z, w)$ .

Consider now  $x'' - \mu(1 - x^2)x' + x = 0$ .

**4.3** Show that this system is not Hamiltonian.

**4.4** Let  $A(t)$  be the area of a region in the  $(x, x')$  plane which is initially defined by the interior of the square with four corners  $(\pm 1, \pm 1)$  and then evolves according to the above dynamical system. Compute the initial rate of change of this area,  $dA/dt|_{t=0}$ .

**4.5** Consider now a general smooth planar system with the property that all volumes shrink monotonically. Does this imply that the system has fixed points? Prove your answer.

**Q5 5.1** State the definition of the Poincaré index for planar systems.

**5.2** What is the behavior of the Poincaré index under smooth deformations of the dynamical system?

**5.3** Prove that the Poincaré index vanishes for paths which do not enclose any fixed point in their interior.

Consider the dynamical system

$$\begin{aligned}x' &= y^2 \\ y' &= xy + a \end{aligned}.$$

**5.4** Show that the Poincaré index on the unit circle around the origin vanishes.

**5.5** For  $a = 0$ , there is a saddle point at the origin. Why does this not contradict the invariance of the index under smooth deformations?

Consider a three-dimensional dynamical system for which  $H = x^2 + y^2 - z^2$  is a first integral, and for which the flow on the disc  $D = \{(x, y) | x^2 + y^2 = 1\}$  points strictly outward.

**5.6** Use the Poincaré index to argue for the existence of a fixed point on each surface  $H = c$ ,  $c < 0$ .