

EXAMINATION PAPER

Examination Session: May/June Year: 2024

Exam Code:

MATH4337-WE01

Title:

Uncertainty Quantification IV

Time:	2 hours	
Additional Material provided:		
Materials Permitted:		
Calculators Permitted:	No	Models Permitted: Use of electronic calculators is forbidden.

Instructions to Candidates:	Answer all questions. Section A is worth 40% and Section B is worth 60%. Within each section, all questions carry equal marks. Students must use the mathematics specific answer book.

Revision:



SECTION A

- Q1 We wish to emulate an expensive 1D computer model f(x) over the input range $x \in [0,1]$. We set up a standard Bayes Linear emulator, specifying a squared exponential prior covariance structure, with $\sigma^2 = 1$, $\theta = 1/3$, and prior expectation E[f(x)] = -1. A single run is performed at the location $x^{(1)} = 0.3$, yielding the output $D = f(x^{(1)}) = -2$.
 - **1.1** Find an expression for the emulator expectation $E_D[f(x)]$.
 - **1.2** Find an expression for the emulator variance $\operatorname{Var}_D[f(x)]$.
 - **1.3** There is interest in determining the lowest value that f(x) could possibly take. Find the input location x that minimises the lower end of the 3-sigma emulator prediction interval.
- Q2 We wish to emulate an expensive computer model f(x) with 2D input $x \in \mathcal{X}_0 = [0,1]^2$ and scalar output $f \in \mathbb{R}$. We use a standard Bayes Linear emulator with prior expectation E[f(x)] = 0, and specify covariance structure

$$\operatorname{Cov}[f(x), f(x')] = \sigma^2 c(x - x')$$

where c(x - x') represents the correlation function. Two runs have been performed and these are at locations $x^{(1)}$ yielding $D_1 = f(x^{(1)})$ and at $x^{(2)}$ yielding $D_2 = f(x^{(2)})$, where $x^{(1)} \neq x^{(2)}$. The vector of run outputs is denoted $D = (D_1, D_2)^T$.

2.1 By explicitly constructing Var[D], show that its inverse is given by

$$\operatorname{Var}[D]^{-1} = \frac{1}{\sigma^2(1-v^2)} \begin{pmatrix} 1 & -v \\ -v & 1 \end{pmatrix}$$

where $v = c(x^{(1)} - x^{(2)})$.

2.2 Hence show that the emulator expectation $E_D[f(x)]$ is given by:

$$E_D[f(x)] = \frac{1}{1 - v^2} \left\{ \left[w_1(x) - v \, w_2(x) \right] D_1 + \left[w_2(x) - v \, w_1(x) \right] D_2 \right\}$$

where $w_1(x) = c(x - x^{(1)})$ and $w_2(x) = c(x - x^{(2)})$.

- **2.3** Demonstrate that the emulator expectation will interpolate the run data. State a constraint on c(x-x') that is required for this interpolation to be continuous.
- **2.4** Show that the emulator variance $\operatorname{Var}_D[f(x)]$ is given by:

$$\operatorname{Var}_{D}[f(x)] = \frac{\sigma^{2}}{1 - v^{2}} \Big\{ 1 - v^{2} - w_{1}(x)^{2} - w_{2}(x)^{2} + 2v w_{1}(x)w_{2}(x) \Big\}$$





SECTION B

Q3 A Bayes linear emulator with basis functions $g_j(x)$, unknown coefficients β_j and weakly stationary process u(x), takes the form:

$$f(x) = \sum_{j=1}^{p} \beta_j g_j(x) + u(x) = g(x)^T \beta + u(x)$$

Prior specifications for $\beta \equiv (\beta_1, \dots, \beta_p)^T$ and u(x) are given by:

$$E[\beta] = \mu_{\beta}, \qquad \operatorname{Var}[\beta] = \Sigma_{\beta}, \qquad E[u(x)] = 0,$$
$$\operatorname{Cov}[u(x), u(x')] = \sigma^2 c(x - x'), \qquad \operatorname{Cov}[\beta, u(x)] = 0,$$

where c(x - x') represents the usual squared exponential covariance structure and where Σ_{β} is of full rank. We define the model output from n runs to be $D = (f(x^{(1)}), \ldots, f(x^{(n)}))^T$ and also $U = (u(x^{(1)}), \ldots, u(x^{(n)}))^T$ with $\operatorname{Var}[U] \equiv \Omega$ where Ω is an $n \times n$ covariance matrix with individual elements $\Omega_{ij} = \sigma^2 c(x^{(i)} - x^{(j)})$. We also define the $n \times p$ design matrix X with elements $X_{ij} = g_j(x^{(i)})$.

- **3.1** With the above specifications, show that we can write $D = X\beta + U$.
- **3.2** Show that the expectation of the regression coefficients β adjusted by the run data D is given by:

$$\mathbf{E}_{D}[\beta] = (X^{T} \Omega^{-1} X + \Sigma_{\beta}^{-1})^{-1} \left[\Sigma_{\beta}^{-1} \mu_{\beta} + (X^{T} \Omega^{-1} X) \hat{\beta}_{GLS} \right]$$

where your answer should also contain a definition of the Generalised Least Squares estimate $\hat{\beta}_{GLS}$. *Hint*: you can use the following Matrix Identity which states that for matrices A, B, C, G of appropriate dimension:

$$AB (GAB + C)^{-1} = (BC^{-1}G + A^{-1})^{-1}BC^{-1}$$

- **3.3** Comment on the form of $E_D[\beta]$ derived in Q3.2.
- **3.4** Show that the variance of the regression coefficients β adjusted by the run data D is given by:

$$\operatorname{Var}_{D}[\beta] = (X^{T} \Omega^{-1} X + \Sigma_{\beta}^{-1})^{-1}$$

- **3.5** Comment on the form of $\operatorname{Var}_D[\beta]$ derived in **Q3.4**.
- **3.6** Examine the behaviour of $E_D[\beta]$ and $Var_D[\beta]$ in the vague β prior limit.
- **3.7** In which limiting situation would $E_D[\beta] \rightarrow \hat{\beta}_{OLS}$ and $\operatorname{Var}_D[\beta] \rightarrow \operatorname{Var}[\hat{\beta}_{OLS}]$, where $\hat{\beta}_{OLS}$ is the Ordinary Least Squares estimate for β ? Justify your answer.



- **Q4** We wish to optimise an expensive 1D function f(x) over the interval $x \in [0, 1]$ using a Bayesian Optimisation approach. We have performed a set of n runs giving model output values $D = (f(x^{(1)}), \ldots, f(x^{(n)}))^T$ and intend to use a Gaussian Process emulator. We denote the highest run output so far found as $f^+ = f(x^+)$ with $x^+ \in \{x^{(1)}, \ldots, x^{(n)}\}$ the corresponding best input so far.
 - **4.1** Define the Probability of Improvement PI(x) and the Expected Improvement EI(x) acquisition functions.
 - **4.2** Say that only a single run has been performed at $x^{(1)} = 0.7$ yielding $D = f(x^{(1)}) = 2$. We employ a Gaussian Process emulator with a squared exponential covariance structure, with $\sigma = 1$ and $\theta = 0.5$ and with constant prior expectation E[f(x)] = 0. By first evaluating the emulator expectation and variance, show that in this case PI(x) is given by:

$$PI(x) = \Phi[-2 \tanh\{2(x-0.7)^2\}^{1/2}], \text{ for } x \neq 0.7$$

where $\Phi[.]$ is the c.d.f. of the standard normal distribution.

- **4.3** By examining the derivative of PI(x), determine whether PI(x) attains a maximum in [0, 1] and find $\lim_{x\to 0.7} d[PI(x)]/dx$.
- **4.4** If we used the PI(x) acquisition function, where would it suggest we place the second run? Discuss the weaknesses of the PI(x) acquisition function, with reference to this example.
- **4.5** Show that when using a general Gaussian Process emulator, the Expected Improvement acquisition function becomes:

$$EI(x) = \sigma_D(x)\phi(z^*) + (\mu_D(x) - f^+)\Phi(z^*),$$

where $\mu_D(x)$ and $\sigma_D(x)$ denote the emulator mean and standard deviation updated by the runs D, $z^* = (\mu_D(x) - f^+)/\sigma_D(x)$ and $\phi(.)$ denotes the p.d.f. of the standard normal distribution.

4.6 By re-expressing both acquisition functions in terms of utilities, discuss why EI(x) is generally considered superior to PI(x). However, what fundamental weakness do both acquisition functions possess?