

RCOX models: Graphical Gaussian models with edge and vertex symmetries

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Joint work with

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and

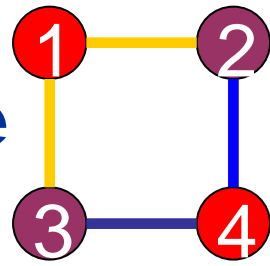
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Særen Hæjsgaard and S????ren H????jsgaard*



AARHUS UNIVERSITET

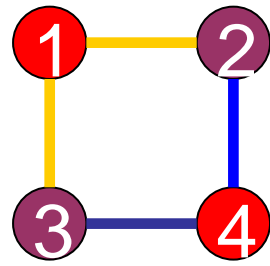
Faculty of Agricultural Sciences

Take-home message and Outline



- **New types of graphical Gaussian models**
 - With colours; as in the logo
 - Attribute specific meanings to the colours
- **An R-package (gRc) for inference in these models**
- **Motivation**
- **RCO'X' models: RCON, RCOR, RCOP**
- **Estimation algorithms**
- **Software**

Idea...

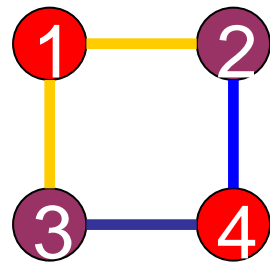


- Apply graphical (Gaussian) models to large matrices, e.g. in gene expression
- Problem: $d \gg n$, many genes few replicates

Graphical model for $Y \sim N_d(0, \Sigma)$

- When $d > n$, MLE of Σ does not exist (in saturated model)
- Impose restrictions on $K = \Sigma^{-1}$ to achieve more parsimonious model;
- In addition to conditional independence, restrict parameters to being identical

Concentration and derived quantities



- Model for $y \sim N_d(0, \Sigma)$, $K = (k^{ij}) = \Sigma^{-1}$.
- The partial (conditional) covariance :

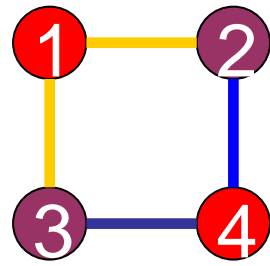
$$\text{cov}(y_i, y_j | \text{rest}) = \frac{-k^{ij}}{\det K^{ij}} \text{ where } K^{ij} = \begin{bmatrix} k^{ii} & k^{ij} \\ k^{ij} & k^{jj} \end{bmatrix}$$

- The partial (conditional) correlation:

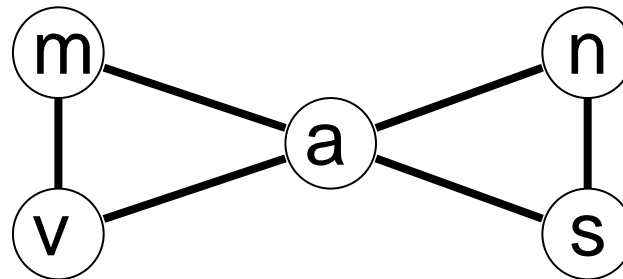
$$\text{cor}(y_i, y_j | \text{rest}) = \rho^{ij} = \frac{-k^{ij}}{\sqrt{k^{ii} k^{jj}}}$$

- Conditional independence: $y_i \perp\!\!\!\perp y_j | \text{rest}$ iff $k^{ij} = 0$

Example: Mathematics marks

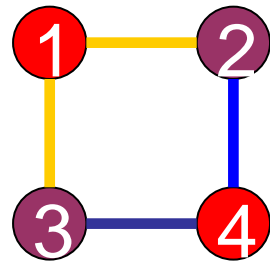


- Mathmark data (Mardia, Kent, Bibby): 88 students marks on (a)lgebra, a(n)alysis, (m)echanics, (v)ectors and (s)tatistics
- Stepwise backward selection gives butterfly model



- Convention: Black and white are neutral colours - corresponding parameters are unrestricted.

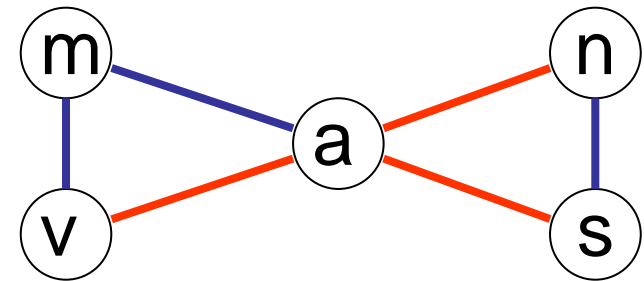
Concentrations for mathmarks



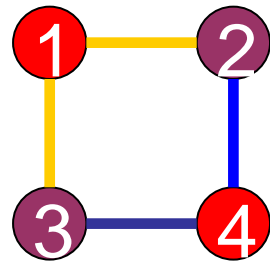
Concentrations ($\times 1000$):

	mechanics	vectors	algebra	analysis	statistics
mechanics	5.24	-2.44	-2.74	0.01	-0.14
vectors	-2.44	10.43	-4.71	-0.79	-0.17
algebra	-2.74	-4.71	26.95	-7.05	-4.70
analysis	0.01	-0.79	-7.05	9.88	-2.02
statistics	-0.14	-0.17	-4.70	-2.02	6.45

- **Some concentrations ≈ 0**
- **Some concentrations \approx identical**



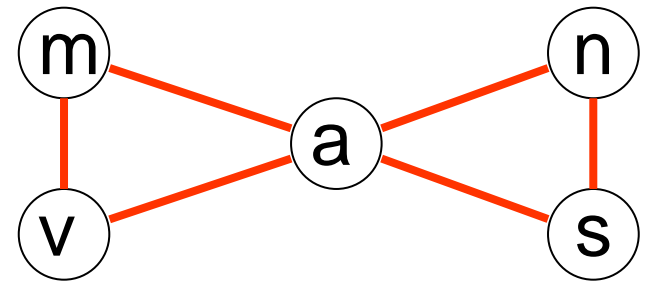
Partial correlations for mathmarks



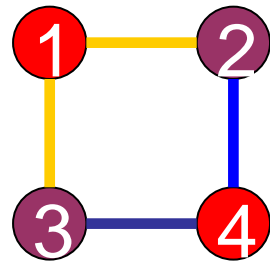
Partial correlations:

	mechanics	vectors	algebra	analysis	statistics
(m)echanics	1.00	-0.30	-0.20	0.00	0.00
(v)ectors	-0.30	1.00	-0.30	-0.10	0.00
(a)lgebra	-0.20	-0.30	1.00	-0.40	-0.40
a(n)alysis	0.00	-0.10	-0.40	1.00	-0.30
(s)tatistics	0.00	0.00	-0.40	-0.30	1.00
Partial variances	190.67	95.91	37.10	101.18	155.04

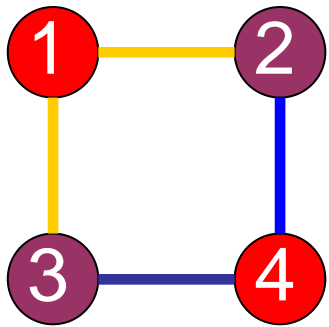
- Some partial correlations \approx identical



RCON (Restricted CONcentration) models



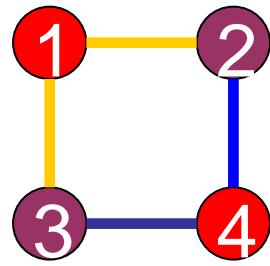
Model: $Y \sim N_d(0, \Sigma)$



$$K = \Sigma^{-1} = \begin{bmatrix} k^{11} & k^{12} & k^{13} & 0 \\ k^{12} & k^{22} & 0 & k^{24} \\ k^{13} & 0 & k^{33} & k^{34} \\ 0 & k^{24} & k^{34} & k^{44} \end{bmatrix}$$

- Markov properties as for graphical Gaussian model
- Entries of K with same colour restricted to being identical \rightarrow 4 rather than 8 parameters.

Implied restrictions (I): Equal contributions in regression



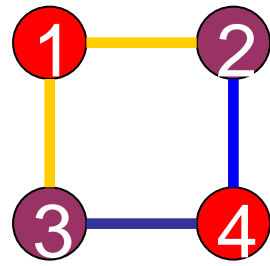
- Regressing y_1 on y_2, y_3, y_4

$$y_1 = a_1 - (k^{12}/k^{11}) y_2 - (k^{13}/k^{11}) y_3$$

- so y_2 and y_3 contribute equally because $k^{12} = k^{13}$

$$K = \Sigma^{-1} = \begin{bmatrix} k^{11} & k^{12} & k^{13} & 0 \\ k^{12} & k^{22} & 0 & k^{24} \\ k^{13} & 0 & k^{33} & k^{34} \\ 0 & k^{24} & k^{34} & k^{44} \end{bmatrix}$$

Implied restrictions (II): Parallel regressions

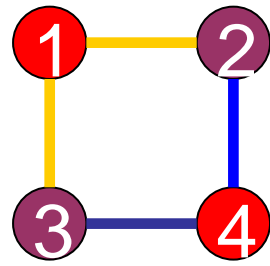


- Regressions of y_2, y_3 on y_1, y_4 are parallel

$$\begin{aligned} \begin{bmatrix} y_2 \\ y_3 \end{bmatrix} &= \begin{bmatrix} a_2 \\ a_3 \end{bmatrix} - \begin{bmatrix} k^{22} & 0 \\ 0 & k^{33} \end{bmatrix}^{-1} \begin{bmatrix} k^{21} & k^{24} \\ k^{31} & k^{34} \end{bmatrix} \begin{bmatrix} y_1 \\ y_4 \end{bmatrix} \\ &= \begin{bmatrix} a_2 \\ a_3 \end{bmatrix} - \begin{bmatrix} k^{21}/k^{22} & k^{24}/k^{22} \\ k^{31}/k^{33} & k^{34}/k^{33} \end{bmatrix} \begin{bmatrix} y_1 \\ y_4 \end{bmatrix} \end{aligned}$$

- because $k^{12} = k^{13}$, $k^{24} = k^{34}$ and $k^{22} = k^{33}$

Implied restrictions (III): Partial covariances and concentrations



- This RCON model has also identical partial covariances

$$\text{cov}(y_1, y_2 | y_3, y_4) = \frac{-k^{12}}{|K^{12}|} = \frac{-k^{13}}{|K^{13}|} = \text{cov}(y_1, y_3 | y_2, y_4)$$

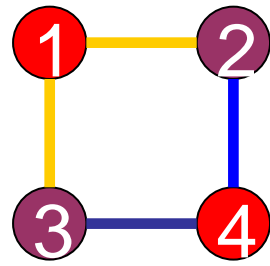
- – and identical partial correlations

$$\text{cor}(y_1, y_2 | y_3, y_4) = \frac{-k^{12}}{\sqrt{k^{11}k^{22}}} = \frac{-k^{13}}{\sqrt{k^{11}k^{33}}} = \text{cor}(y_1, y_3 | y_2, y_4)$$

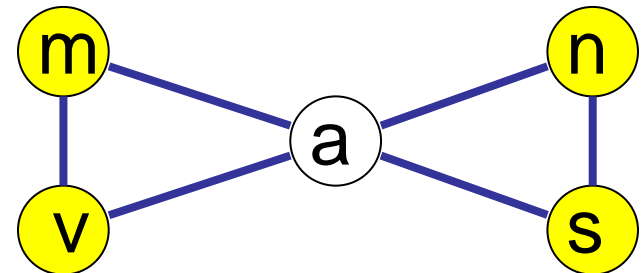
$$K = \Sigma^{-1} = \begin{bmatrix} k^{11} & k^{12} & k^{13} & 0 \\ k^{12} & k^{22} & 0 & k^{24} \\ k^{13} & 0 & k^{33} & k^{34} \\ 0 & k^{24} & k^{34} & k^{44} \end{bmatrix}$$

Not
generally
the case!!!

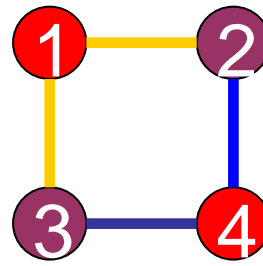
Example – mathematics marks



- Focus on butterfly model
 - EdgeColourClass: Edges with same colour
 - VertexColourClass: Vertices with same colour
- Note: Black and white are neutral colours; no restrictions
- Successively apply (with LR-test, 5% level)
 - JoinEdgeColourClasses()
 - JoinVertexColourClasses()

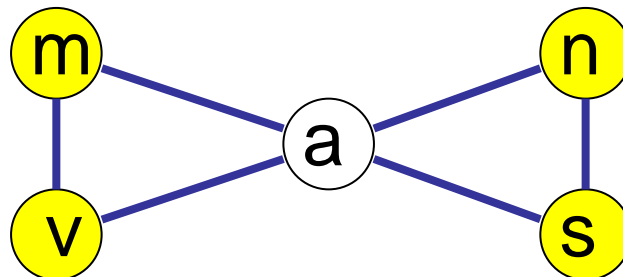


Mathematics marks...

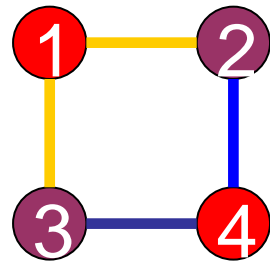


Estimated / observed concentrations ($\times 1000$) are

Concentrations	mechanics	vectors	algebra	analysis	statistics
mechanics	7.58	-3.49	-3.49	0.00	0.00
vectors	-3.49	7.58	-3.49	0.00	0.00
algebra	-3.49	-3.49	20.76	-3.49	-3.49
analysis	0.00	0.00	-3.49	7.58	-3.49
statistics	0.00	0.00	-3.49	-3.49	7.58
mechanics	5.24	-2.44	-2.74	0.01	-0.14
vectors	-2.44	10.43	-4.71	-0.79	-0.17
algebra	-2.74	-4.71	26.95	-7.05	-4.70
analysis	0.01	-0.79	-7.05	9.88	-2.02
statistics	-0.14	-0.17	-4.70	-2.02	6.45

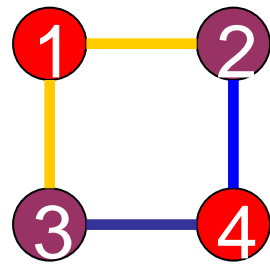


RCOR (Restricted CORrelation) models



- Restricting concentrations not scale-invariant: Identical concentrations of $y \sim N(0, \Sigma)$ not generally preserved for $Ay \sim N(0, A\Sigma A)$, where A is diagonal
- Hence RCON models are only of interest in cases where the scale of measurement for different variables are comparable
- Alternatively: Focus on restricted partial correlations

RCOR (restricted correlation) models



Write $-K$ as

$$\begin{bmatrix} \eta^{11} & 0 & 0 & 0 \\ 0 & \eta^{22} & 0 & 0 \\ 0 & 0 & \eta^{33} & 0 \\ 0 & 0 & 0 & \eta^{44} \end{bmatrix} \begin{bmatrix} 1 & \rho^{12} & \rho^{13} & 0 \\ \rho^{12} & 1 & 0 & \rho^{24} \\ \rho^{13} & 0 & 1 & \rho^{34} \\ 0 & \rho^{24} & \rho^{34} & 1 \end{bmatrix} \begin{bmatrix} \eta^{11} & 0 & 0 & 0 \\ 0 & \eta^{22} & 0 & 0 \\ 0 & 0 & \eta^{33} & 0 \\ 0 & 0 & 0 & \eta^{44} \end{bmatrix}$$

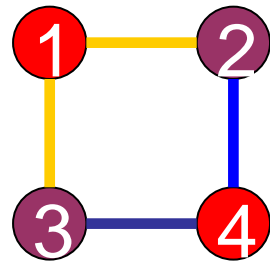
$= A_{\eta} C_{\rho} A_{\eta}$ where

A_{η} : diagonal with positive entries (inverse partial standard deviations)

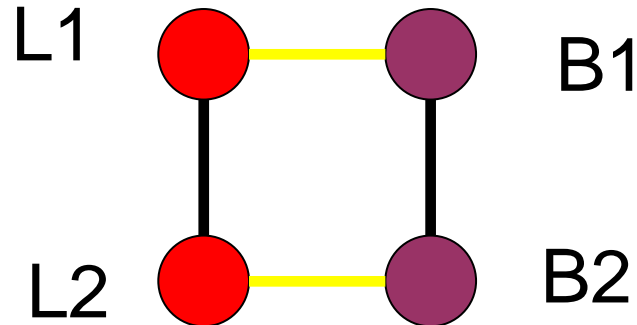
C_{ρ} : has 1s on diagonal (partial correlations)

- Entries of (A_{η}, C_{ρ}) restricted according to colouring
- Scale invariant - if vertices with same colour are rescaled identically

RCOP models ('P' for permutation symmetry)



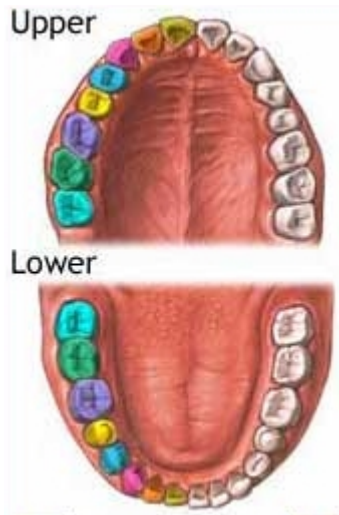
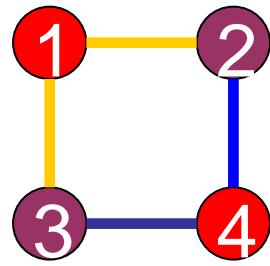
Fret's head: Length and breadth of head of first and second son:



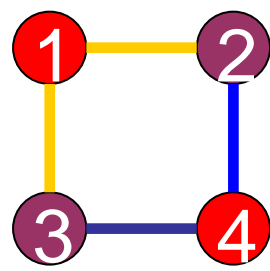
Complete symmetry between first and second son

- Both RCON and RCOR
- RCOP-model (defined by permutations)
- Studied by Helene Neufeld (poster session)

Symmetry models in nature

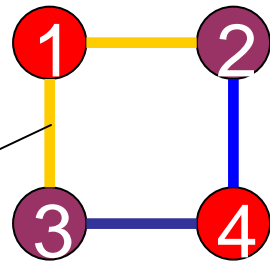
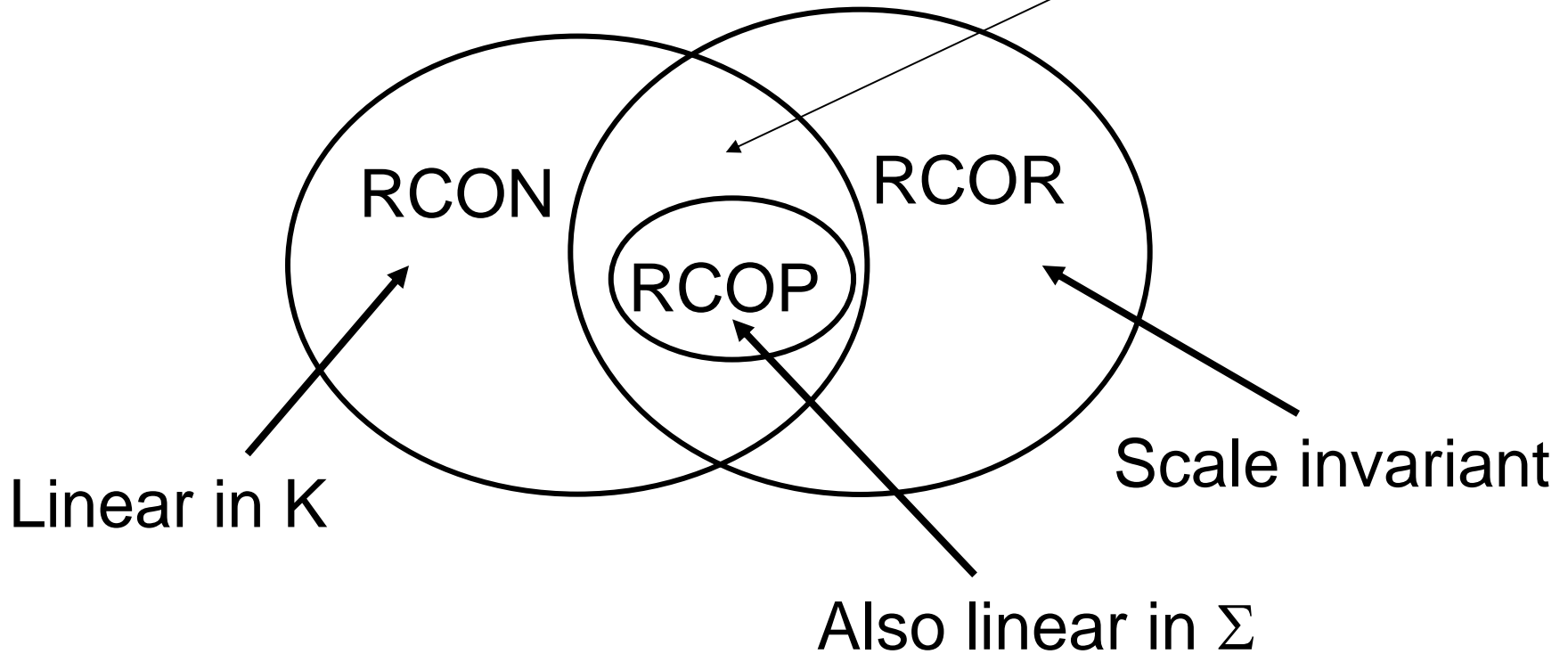


Further...

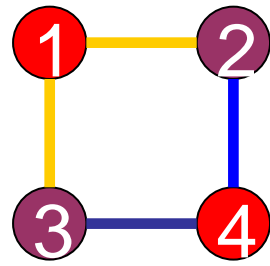


A bigger picture...

Relationships between models



Specification of RCON / RCOR models



- **Generators of model**

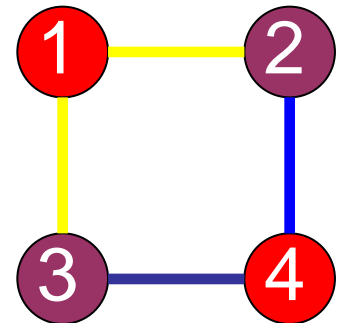
- Edge colour classes:

$$EC = \{\{1,2\}\{1,3\}\} \{\{2,4\}\{3,4\}\}$$

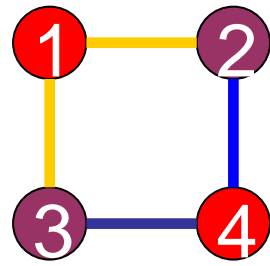
- Vertex colour classes:

$$VC = \{1,4\}\{2,3\}$$

- **(EC,VC) specifies RCON/RCOR model**



RCON Estimation - Sufficient statistics



For EdgeCC $s=\{\{1,2\}\{1,3\}\}$

$$T^s = \begin{bmatrix} 0 & 1 & 1 & 0 \\ 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

For vertexCC $s=\{1,4\}$

$$T^s = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Let $W \sim \text{Wishart}(f, \Sigma)$

RCON regular exponential family;
linear in K :

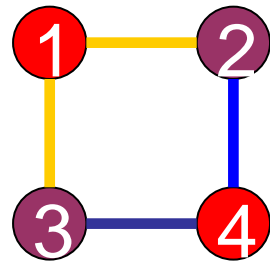
Then

$$\begin{aligned} 2 \log L &= f \log |K| - \text{tr}(KW) \\ &= f \log |K| - \sum_s \theta_s \text{tr}(T^s W) \end{aligned}$$

So $\{t^s = \text{tr}(T^s W)\}$ is a set of
sufficient statistics

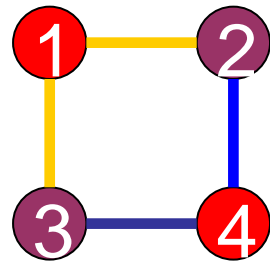
Equated with expectations
 $\{t^s\} = \{f \text{tr}(T^s \Sigma)\}$

Estimation in RCON models - Modified Newton



- Use convergent (!) algorithm of Jensen, Johansen and Lauritzen (1991):
- Maximize $1/L$ (instead of $\log L$) cyclically over one parameter at the time by Newton iteration.
- In exponential families we have
 - $\exp(t(y)\theta - \psi(\theta))$
 - $I^* = 1/L = \exp(-t(y)\theta + \psi(\theta))$

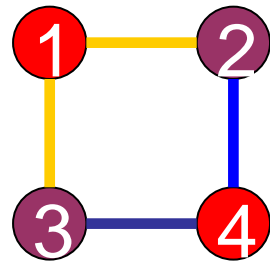
Modified Newton



- Let $\Delta = E(t(\mathbf{y})) - t(\mathbf{y})$.
- Then
 - $(l^*)' = \exp(-t(\mathbf{y})\theta + \psi(\theta))\Delta$
 - $(l^*)'' = \exp(-t(\mathbf{y})\theta + \psi(\theta))[\text{Var}(t(\mathbf{y})) + \Delta^2]$
- **Newton step becomes:**
- $\theta \leftarrow \theta - (l^*)' / (l^*)'' = \theta - \Delta / (\text{Var}(t(\mathbf{y})) + \Delta^2)$

- **For RCON models**
 - $E(T^s W) = f \text{tr}(T^s \Sigma)$
 - $\text{Var}(T^s W) = f \text{tr}(T^s \Sigma T^s \Sigma)$

Estimation – RCOR - short version



RCOR model is generally not a linear exponential family

$$\log L = f/2 \log |C_\rho| + f \log |A_\eta| - \text{tr}(A_\eta C_\rho A_\eta W)/2$$

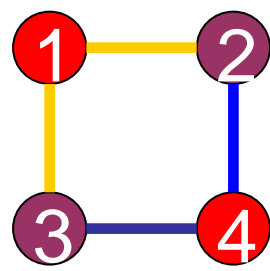
Linear exponential family for fixed η ; likelihood equations quadratic for fixed ρ .

Existence/uniqueness of MLE not clear. But unique maximum in ρ for fixed η and unique maximum in η for fixed ρ .

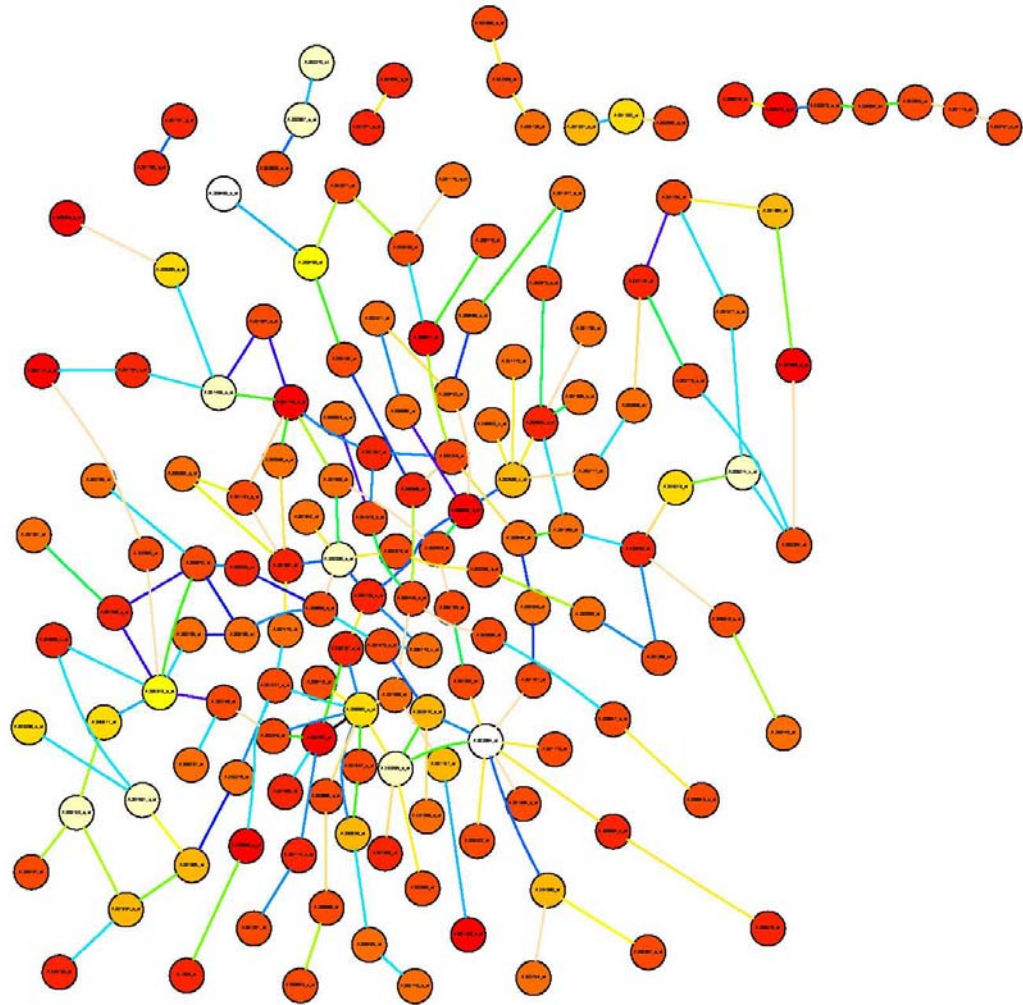
Suggests alternating algorithm

1. For given η , estimate ρ using modified Newton as for RCON
2. For given ρ , estimate η by solving system of 2nd degree equations (cyclically)

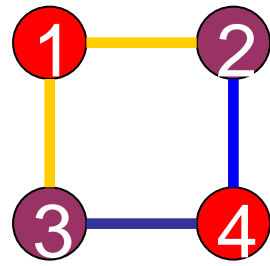
Larger model: Breast cancer genes



- 58 cases, 150 genes
- 7 VCC, 10 ECC: 17 parameters
- Fitting with gRc: 0.3 sec
- 380 parms
- Fitting with gRc: 1.1 sec
- Model selection is a big issue...



Summing up



- SH +Lauritzen: Graphical Gaussian models with edge and vertex symmetries. (*RSSB, To appear*)
- SH + Lauritzen (2007). Inference in graphical Gaussian models with edge and vertex symmetries with the gRc package for R (*J. Stat. Soft*)
- gRc package in R ('c' for colour) on CRAN