



Spectral Properties
of Saddle Point Linear Systems
and Relations to Iterative Solvers
Part III: Nonsymmetric Preconditioners

V. Simoncini

Dipartimento di Matematica, Università di Bologna

valeria@dm.unibo.it

Outline of the 3-hour Presentation

- Schematic presentation of certain algebraic preconditioners
(First day)
- Iterative solvers. Some (hopefully) helpful considerations...
(Yesterday)
- **Spectral analysis of nonsymmetric preconditioners**
(Today)

Why should we go nonsymmetric?

- Good (complex) clustering may be better than just “symmetry”
- More freedom in selecting a preconditioner
- If only few iterations, costs are low

Only for really tough problems

An example. The 3D magnetostatic problem.

(3D) Maxwell equations: $\operatorname{div} \mathbf{B} = 0 \quad \operatorname{curl} \mathbf{H} = \mathbf{J}$

Constitutive law

$$\mathbf{B} = \mu \mathbf{H}$$

\mathbf{B} displacement field, \mathbf{H} magnetic field, μ magn. permeability

Constrained quadratic programming formulation



$$\min \frac{1}{2} \int_{\Omega} \mu^{-1} |\mathbf{B} - \mu \mathbf{H}|^2 dx$$

with $\mathbf{B} \cdot \mathbf{n} = f_B$ on Γ_B and $\operatorname{div} \mathbf{B} = 0$
 $\mathbf{H} \wedge \mathbf{n} = \mathbf{f}_H$ on Γ_H and $\operatorname{curl} \mathbf{H} = \mathbf{J}$

★ *Boundary conditions are enforced*

★ *Constraints: Lagrange multipliers*

Triangular preconditioner

$$\mathcal{M} = \begin{bmatrix} A & B^T \\ B & -C \end{bmatrix} \quad A \text{ spd}, \quad \mathcal{P} = \begin{bmatrix} \tilde{A} & B^T \\ 0 & -\tilde{C} \end{bmatrix}, \quad \begin{array}{l} \tilde{A} \approx A, \\ \tilde{C} \approx BA^{-1}B^T + C \end{array}$$

Spectrum of $\mathcal{M}\mathcal{P}^{-1}$:

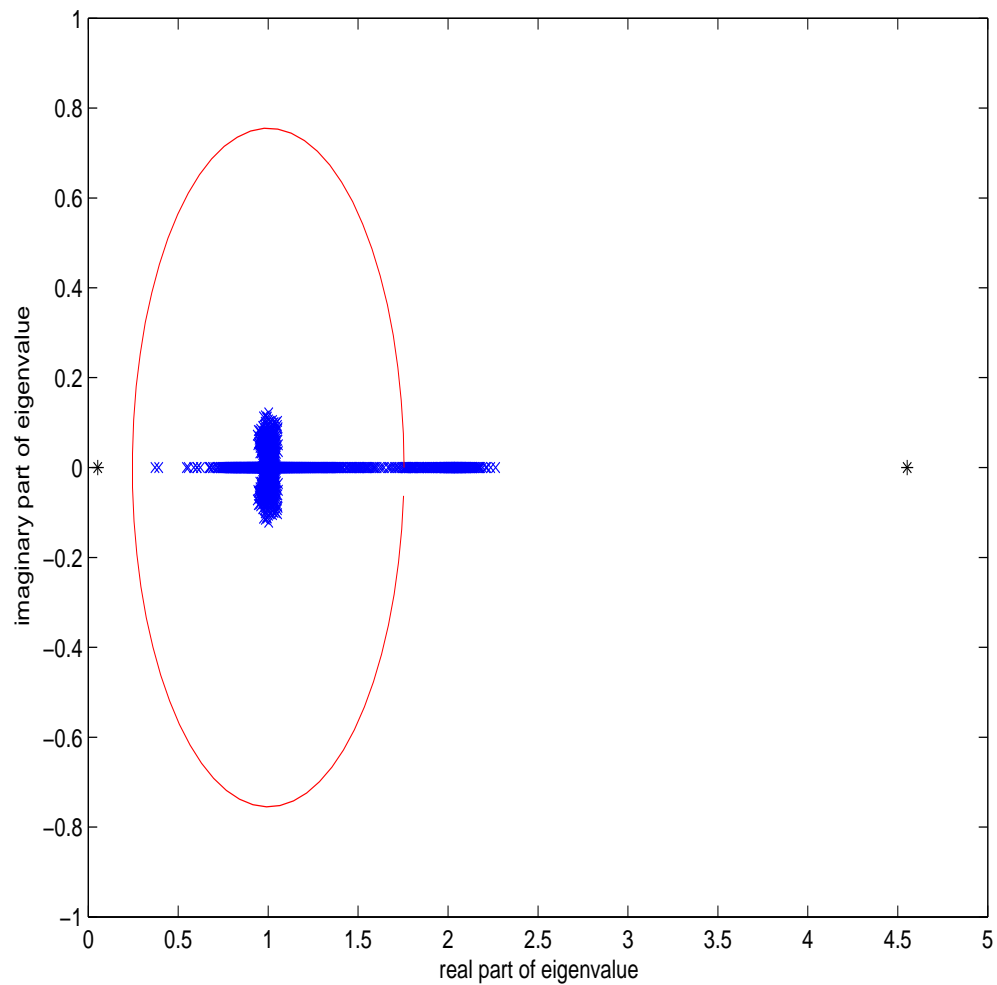
small complex cluster around 1 \cup real interval :

More precisely: $\theta \in \Lambda(\mathcal{M}\mathcal{P}^{-1})$

$$\Im(\theta) \neq 0 \Rightarrow |\theta - 1| \leq \sqrt{1 - \lambda_{\min}(A\tilde{A}^{-1})} \quad (\text{if } 1 - \lambda_{\min}(A\tilde{A}^{-1}) \geq 0)$$

$$\Im(\theta) = 0 \Rightarrow \theta \in [\chi_1, \chi_2] \text{ with } 1 \in [\chi_1, \chi_2]$$

An example. The 3D magnetostatic problem.



size: 2208. $\tilde{A} = \text{cholinc}(A, 10^{-2})$, $\tilde{C} = \text{cholinc}(C, 10^{-2})$

An example. 3D magnetostatic problem.

A spd, B not full rank, C s.t. $BB^T + C$ is spd

Problem dim.	(its)	E-time (its)	E-time (its)	E-time (its)
	GMRES Block.Tr.	CGstab Block.Tr.	QMRs Block.Tr.	QMRs Block.Diag.
2208	(17)	0.59 (24)	0.46 (18)	0.88 (40)
8622	(30)	5.31 (44)	4.06 (31)	6.85 (64)
22675	(50)	26.08 (84)	18.57 (53)	32.85 (115)

\hat{A} : ICT($A, 10^{-2}, 2$). \hat{C} : ICT($BB^T + C, 10^{-4}, 5$)

tol = 10^{-8}

More to show? An open problem

$$\begin{bmatrix} A & B^T \\ 0 & -C \end{bmatrix} \Rightarrow \mathcal{P} = \begin{bmatrix} \tilde{A} & B^T \\ 0 & -\tilde{C} \end{bmatrix}$$

★ Pretty clear understanding of “perturbed” spectrum

Eigenvectors?

$$\|r_m^{gmres}\| \leq \|r_0\| \kappa(X) \min_{p_m(0)=1} \max_{j=1, \dots, n+m} \|p_m(\lambda_j)\|$$

X eigenvector matrix of $\mathcal{M}\mathcal{P}^{-1}$, $\lambda_j \in \sigma(\mathcal{M}\mathcal{P}^{-1})$

Indefinite (Constraint) Preconditioner

$$\mathcal{M}\mathcal{P}^{-1} \quad \mathcal{P} = \begin{bmatrix} \tilde{A} & B^T \\ B & O \end{bmatrix}, \quad C = O, \quad \tilde{A} = I$$

Remark: $Bx_k = 0$ for all iterates x_k (constraint)

Indefinite (Constraint) Preconditioner

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Remark: $Bx_k = 0$ for all iterates x_k (constraint)

$\Pi = B^T(BB^T)^{-1}B$ orth. projector

$$\mathcal{M}\mathcal{P}^{-1} = \begin{bmatrix} (A - I)(I - \Pi) + \Pi & \star \\ O & I_m \end{bmatrix}$$

$\lambda \neq 0$ eigs of $\mathcal{M}\mathcal{P}^{-1}$: $\lambda \in \mathbb{R}^+$, $\lambda \in \{1\} \cup \sigma(A(I - \Pi) + \Pi)$

$\mathcal{M}\mathcal{P}^{-1}$ has nontrivial Jordan blocks

Canonical Form ($C = O$)

$$\mathcal{P}^{-1}\mathcal{M} = \mathcal{X}^{-1} \begin{bmatrix} \Theta & & \\ & I_m & I_m \\ & & I_m \end{bmatrix} \mathcal{X}$$

with

$$\mathcal{X} = \begin{bmatrix} I & B^T \\ O & (BB^T)^{\frac{1}{2}} \end{bmatrix} \left[\begin{array}{c|c|c} X_0 & B_0^T & (A - I)^{-1}B_0^T \\ \hline B_0X_0 & I_m & O \end{array} \right]$$

where

- $B_0 = (BB^T)^{-\frac{1}{2}}B$ orth. rows
- X_0 eigenvec's of $(A - I)(I - \Pi)$ corresponding to nonzero eigs Θ :

$$(A - I)(I - \Pi)X_0 = X_0\Theta$$

Bound for the GMRES residual

$$\mathcal{J} = \begin{bmatrix} \ominus & & \\ & I_m & I_m \\ & & I_m \end{bmatrix}$$

Then

$$\|r_m\| \leq \|r_0\| \kappa(\mathcal{X}) \min_{p_m(0)=1} \|p_m(\mathcal{J})\|$$

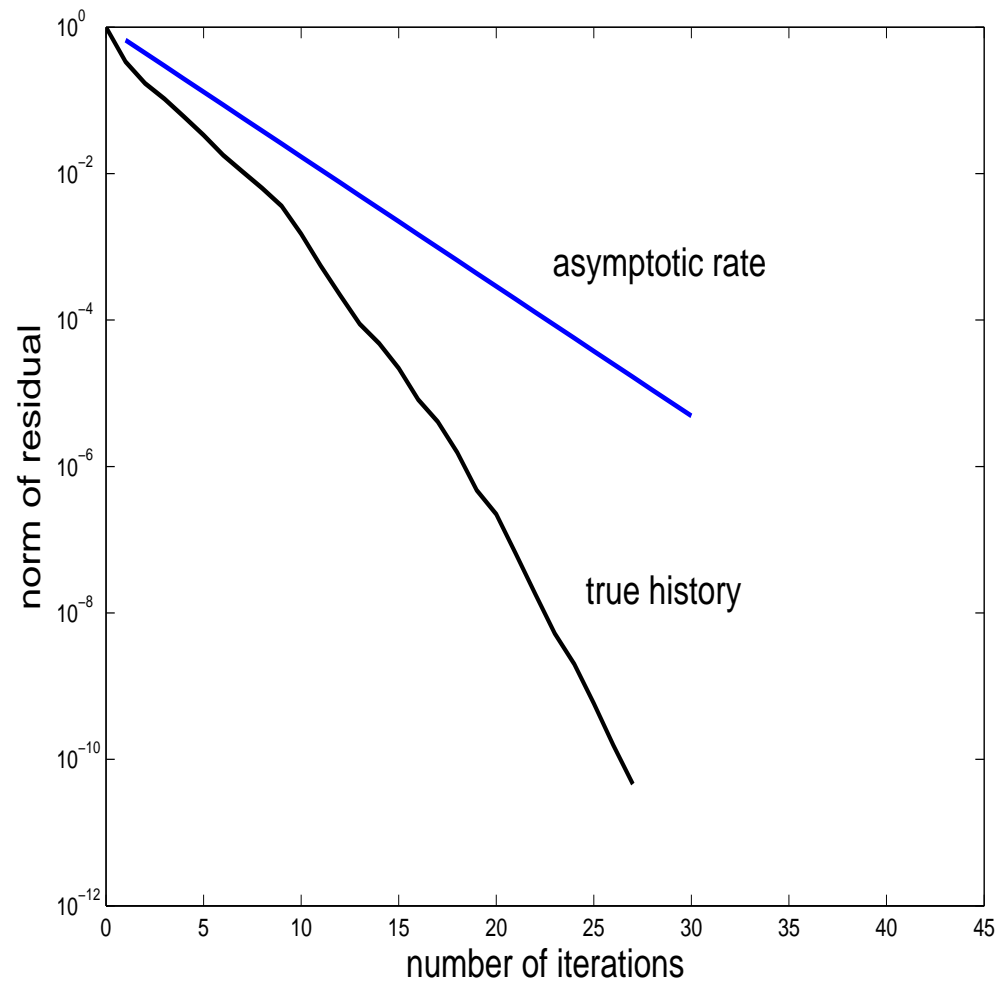
If 1 is inside the spectral interval,

$$\min_{p_m(0)=1} \|p_m(\mathcal{J})\| \approx \min_{p_m(0)=1} \max_{j=1, \dots, n+m} |p_m(\lambda_j)| \leq 2 \left(\frac{\sqrt{\kappa} - 1}{\sqrt{\kappa} + 1} \right)^m$$

$$\text{with } \kappa = \frac{\lambda_{\max}}{\lambda_{\min}}$$

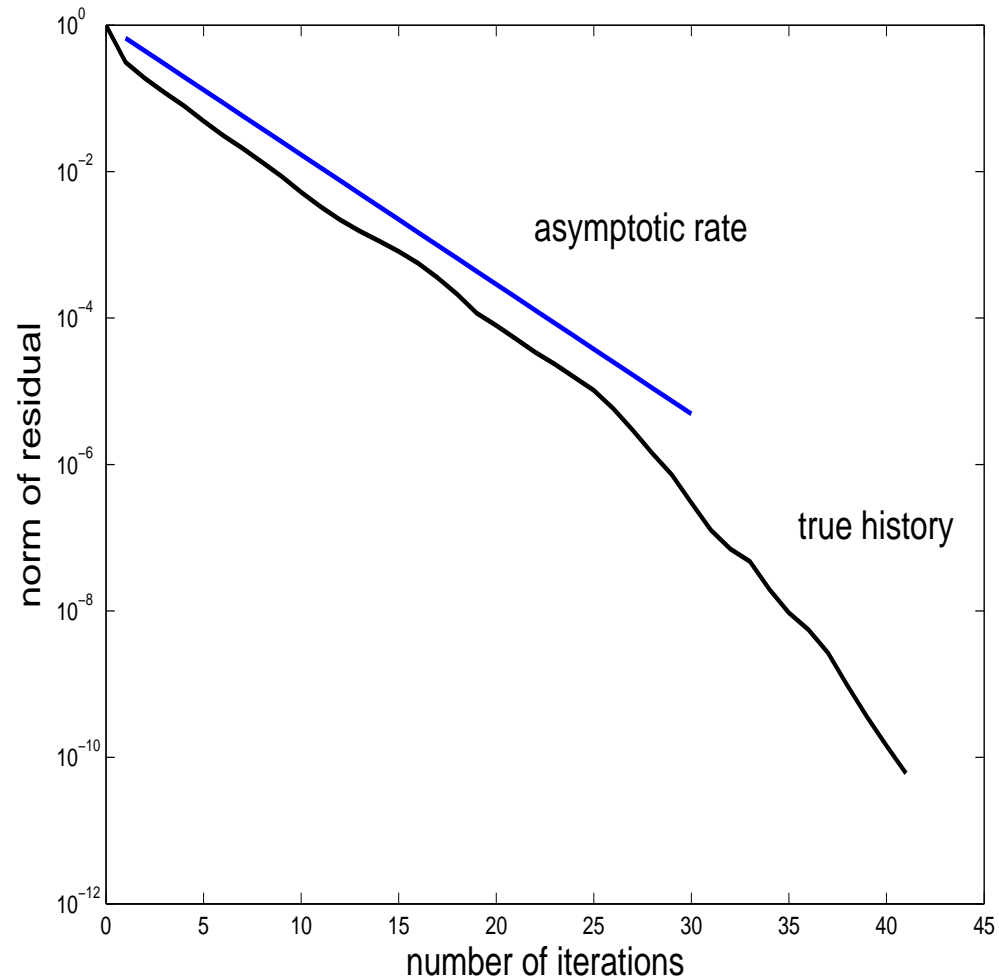
CG bound for the spectrum

Stokes problem with mixed b.c. on the unit square



$$\kappa(\mathcal{X}) = 9.4 \cdot 10^3$$

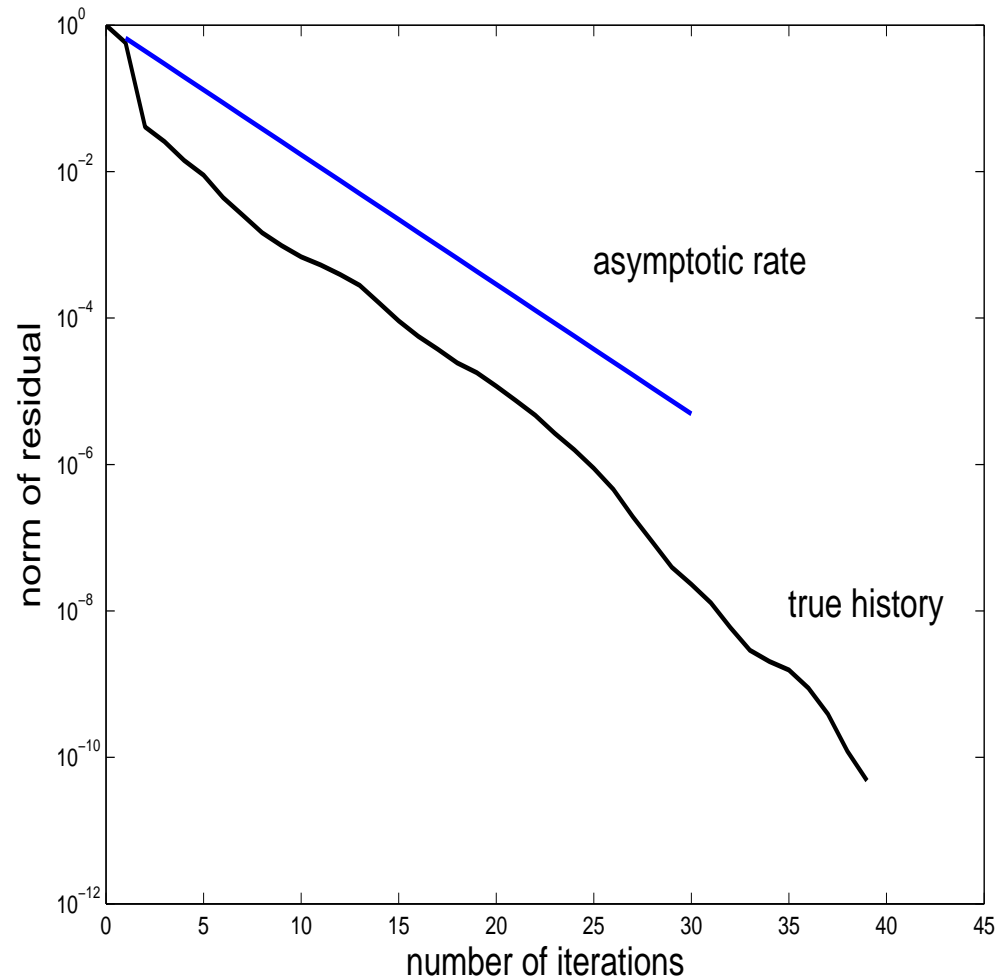
Stokes problem with mixed b.c. on the unit square



Random right-hand side (first block)

$$\kappa(\mathcal{X}) = 9.4 \cdot 10^3$$

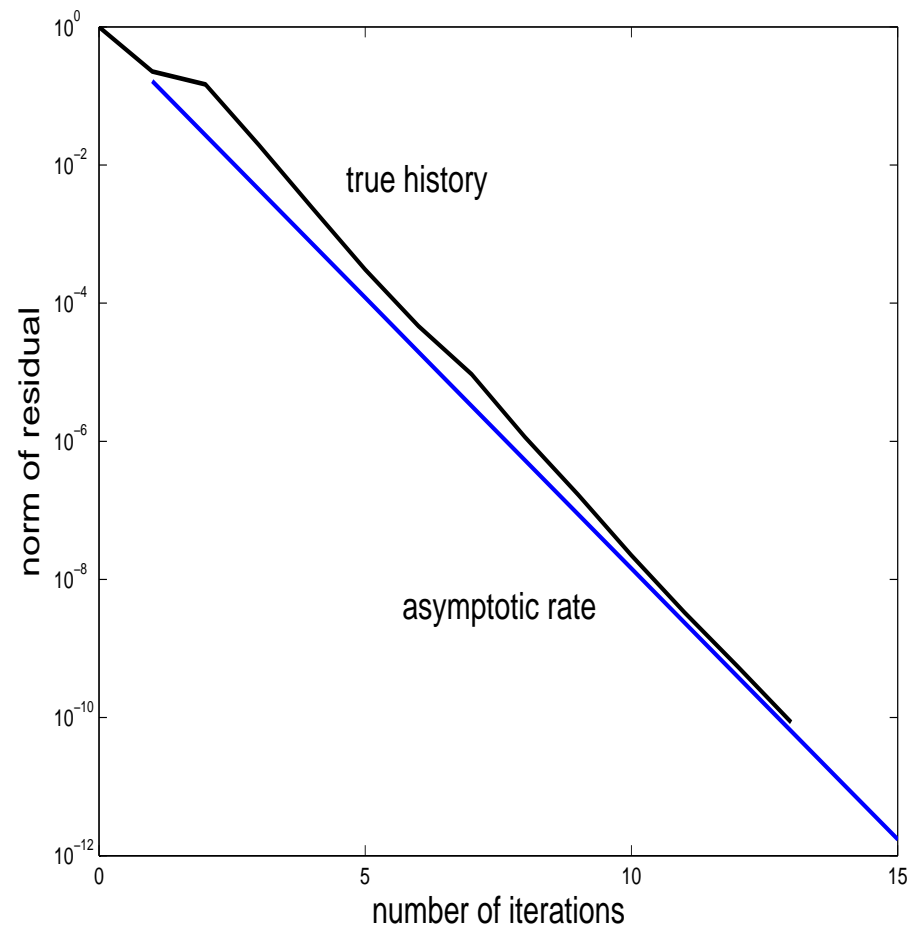
Stokes problem with mixed b.c. on the unit square



Random right-hand side (both blocks)

$$\kappa(\mathcal{X}) = 9.4 \cdot 10^3$$

The example from magnetostatic



$$\kappa(\mathcal{X}) = 2.6 \cdot 10^9$$

Dimension reduction

$$\begin{bmatrix} A & B^T \\ B & -C \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} f \\ 0 \end{bmatrix}$$

In this case, GMRES on $\mathcal{M}\mathcal{P}^{-1}$ satisfies:

$$\|r_m^{gmres}\| = \min_{p_m(0)=1} \|p_m((A - I)\Pi + \Pi)f\|$$

where $\Pi = B^T(BB^T + C)^{-1}B$

From this,

$$\|r_m^{gmres}\| \leq \|r_0\| \zeta \left(\frac{\sqrt{\kappa} - 1}{\sqrt{\kappa} + 1} \right)^m$$

$$\kappa = \lambda_{\max}/\lambda_{\min}$$

ζ depends on $\|A\|, \|(A - I)^{-1}\|$

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★ Nonsym Lanczos-type methods reduce to PCG

A feasible preconditioner

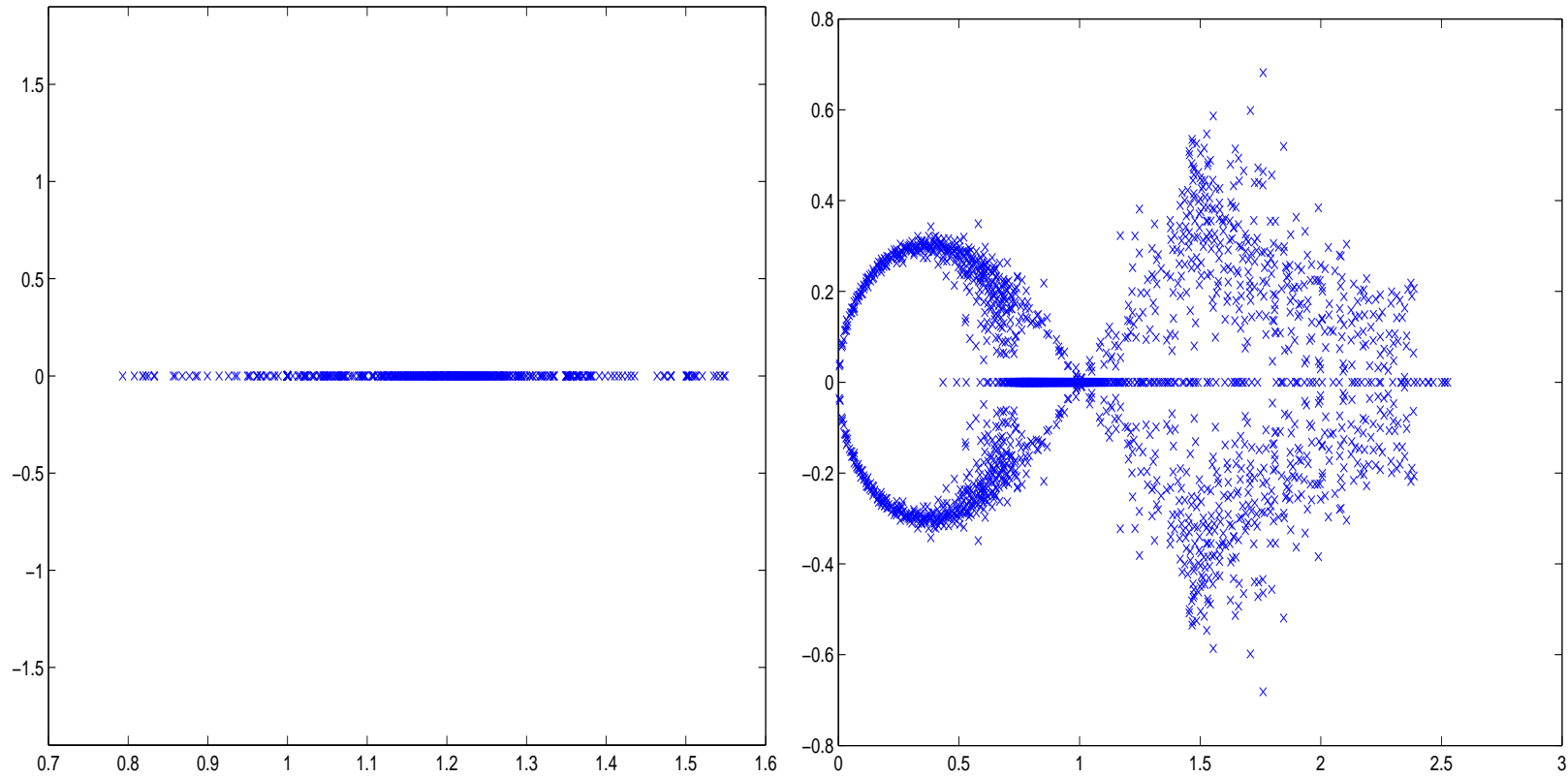
$$\mathcal{P} = \begin{bmatrix} I & B^T \\ B & -C \end{bmatrix}$$

$$\mathcal{P} = \begin{bmatrix} I & O \\ B & I \end{bmatrix} \begin{bmatrix} I & O \\ O & -(\mathbf{B}\mathbf{B}^T + \mathbf{C}) \end{bmatrix} \begin{bmatrix} I & B^T \\ O & I \end{bmatrix}$$

Replace $BB^T + C$ with a cheaper approximation S

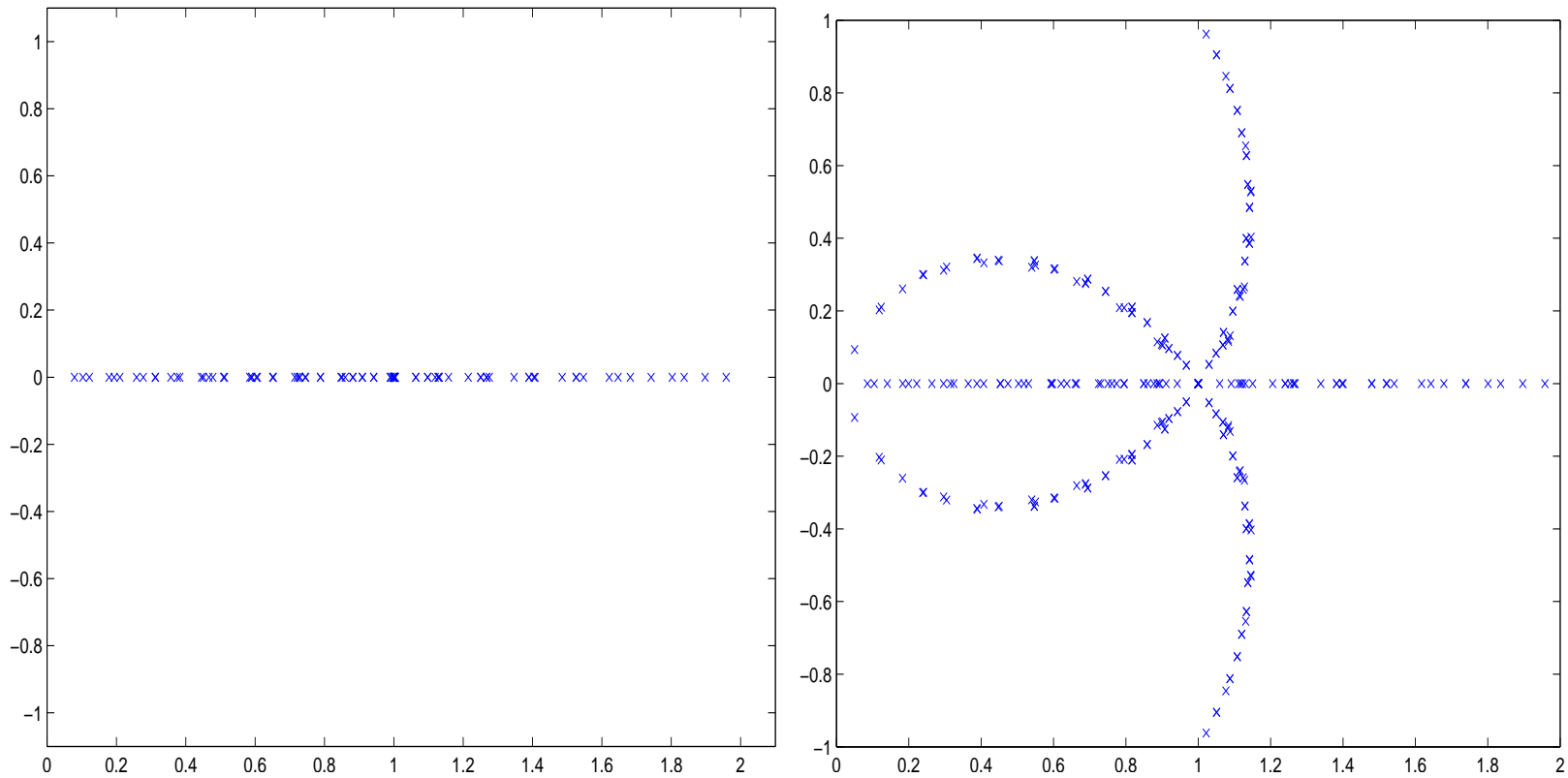
Question: How much does S affect the preconditioner ?

Spectrum of perturbed matrix. 2D Magnetostatic problem



$$(C = 0), \|BB^T - S\|_\infty \approx 0.5\|BB^T\|_\infty \quad \tilde{A} = I, S = \text{diag}(BB^T)$$

Spectrum of perturbed matrix. Stokes problem



$$\|BB^T - S\|_\infty \approx 0.5\|BB^T\|_\infty \quad \tilde{A} = \text{diag}(A), \quad S = \text{diag}(B\tilde{A}^{-1}B^T)$$

Eigenvalue bounds

$$C = 0, A \text{ spd. } S \approx BB^T$$

$$\text{Let } G = B(2I - A)B^T S^{-1} \quad (\text{scale } A \text{ so that } G \geq 0)$$

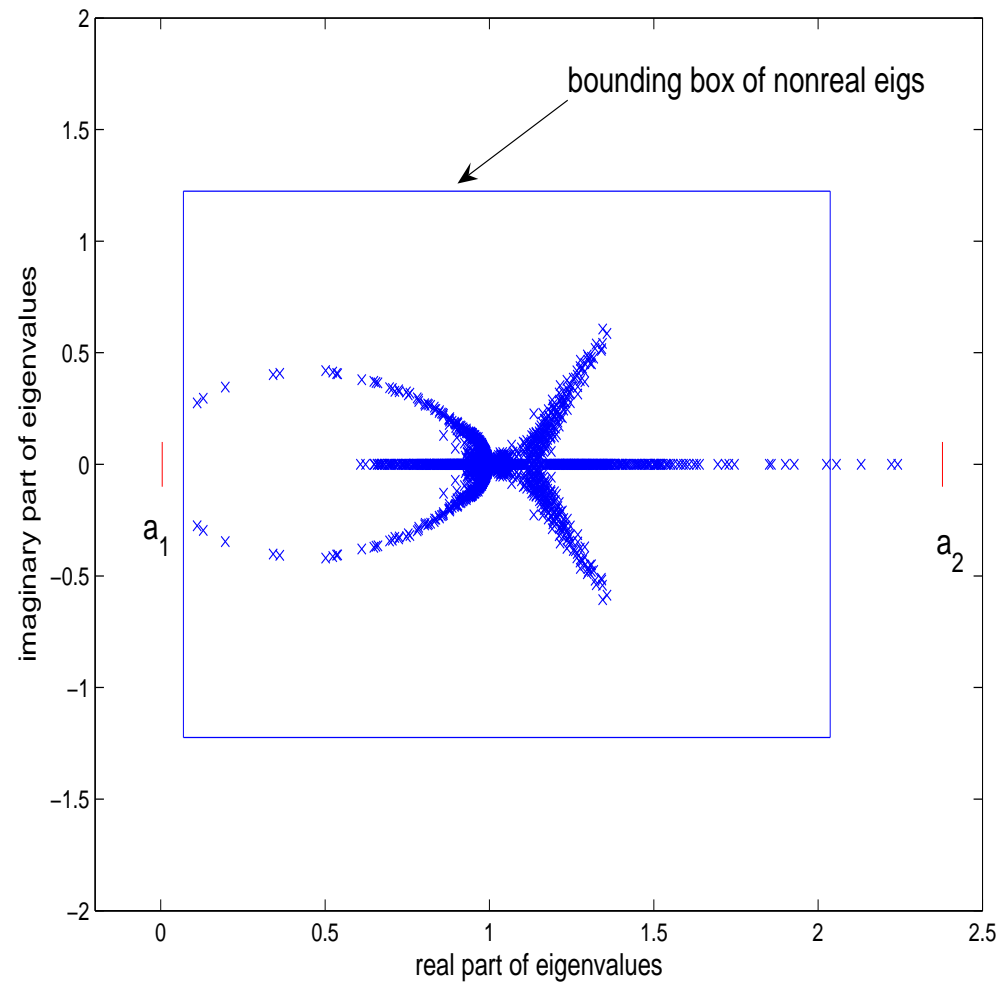
★ If $\Im(\lambda) \neq 0$ then

$$\begin{aligned} \frac{1}{2}(\lambda_{\min}(A) + \lambda_{\min}(G)) &\leq \Re(\lambda) \leq \frac{1}{2}(\lambda_{\max}(A) + \lambda_{\max}(G)) \\ |\Im(\lambda)| &\leq \sigma_{\max}((I - A)B^T (BB^T)^{-\frac{1}{2}}). \end{aligned}$$

★ If $\Im(\lambda) = 0$ then

$$\min\{\lambda_{\min}(A), \lambda_{\min}(G)\} \leq \lambda \leq \max\{\lambda_{\max}(A), \lambda_{\max}(G)\}$$

Spectral bounds



$$S = \text{cholinc}(BB^T, 10^{-2})$$

A class of indefinite preconditioners

$$\mathcal{P} = \begin{bmatrix} I & O \\ B\hat{A}^{-1} & I \end{bmatrix} \begin{bmatrix} \hat{A} & O \\ O & -S \end{bmatrix} \begin{bmatrix} I & \hat{A}^{-1}B^T \\ O & I \end{bmatrix}$$

where $\hat{A} \approx A$, $S \approx B\hat{A}^{-1}B^T$

A class of indefinite preconditioners

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where $\hat{A} \approx A$, $S \approx B\hat{A}^{-1}B^T$

Two alternatives:

★ Use \mathcal{P} with nonsymmetric solver

A class of indefinite preconditioners

$$\mathcal{P} = \begin{bmatrix} I & O \\ B\hat{A}^{-1} & I \end{bmatrix} \begin{bmatrix} \hat{A} & O \\ O & -S \end{bmatrix} \begin{bmatrix} I & \hat{A}^{-1}B^T \\ O & I \end{bmatrix}$$

where $\hat{A} \approx A$, $S \approx B\hat{A}^{-1}B^T$

Two alternatives:

- ★ Use \mathcal{P} with nonsymmetric solver
- ★ Enforce constraints on \hat{A} , S to derive H -symmetric CG:

$\mathcal{P}^{-1}\mathcal{M}$ is H -symmetric with

$$H = \begin{bmatrix} \hat{A} - A & O \\ O & B\hat{A}^{-1}B^T - S \end{bmatrix} > 0$$

Class of indefinite preconditioners. Stokes problem.

Preconditioner: $\hat{A} : \text{cholinc}(A, 10^{-2})$ $S : \text{cholinc}(B\hat{A}^{-1}B^T, 10^{-2})$

Preconditioner forcing *H*-symmetry: $\tilde{A} = \hat{A} + \tau I$, s.t. $\lambda_{\min}(\tilde{A} - A) \approx 2.74$

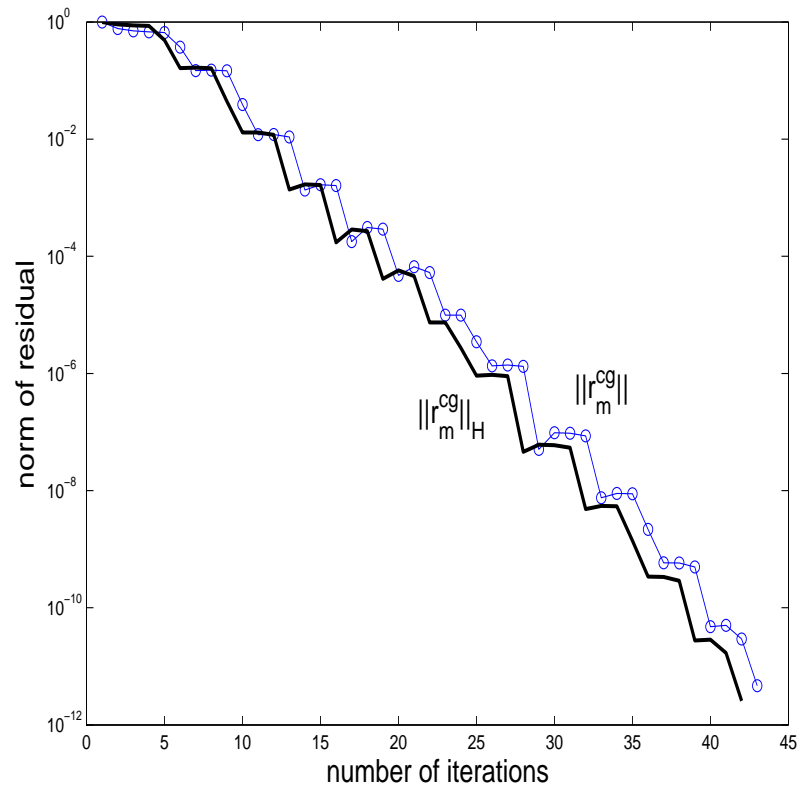
$\hat{S} : \text{from } \text{cholinc}(B\tilde{A}^{-1}B, 10^{-2}) \text{ scaled s.t. } \lambda_{\min}(B\tilde{A}^{-1}B^T - \hat{S}) \approx 0.07$

Class of indefinite preconditioners. Stokes problem.

Preconditioner: $\hat{A} : \text{cholinc}(A, 10^{-2})$ $S : \text{cholinc}(B\hat{A}^{-1}B^T, 10^{-2})$

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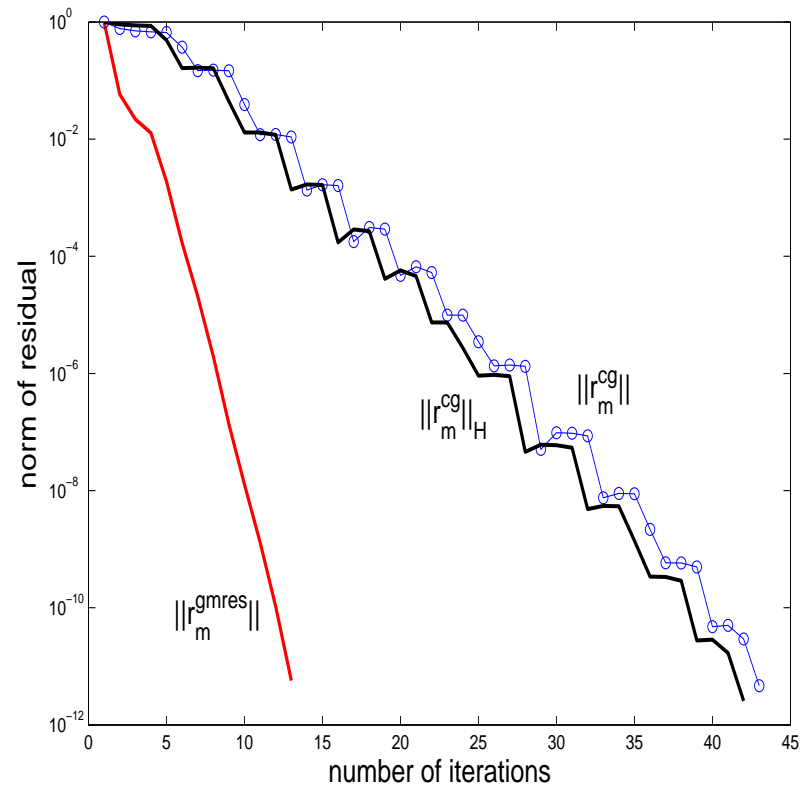


Class of indefinite preconditioners. Stokes problem.

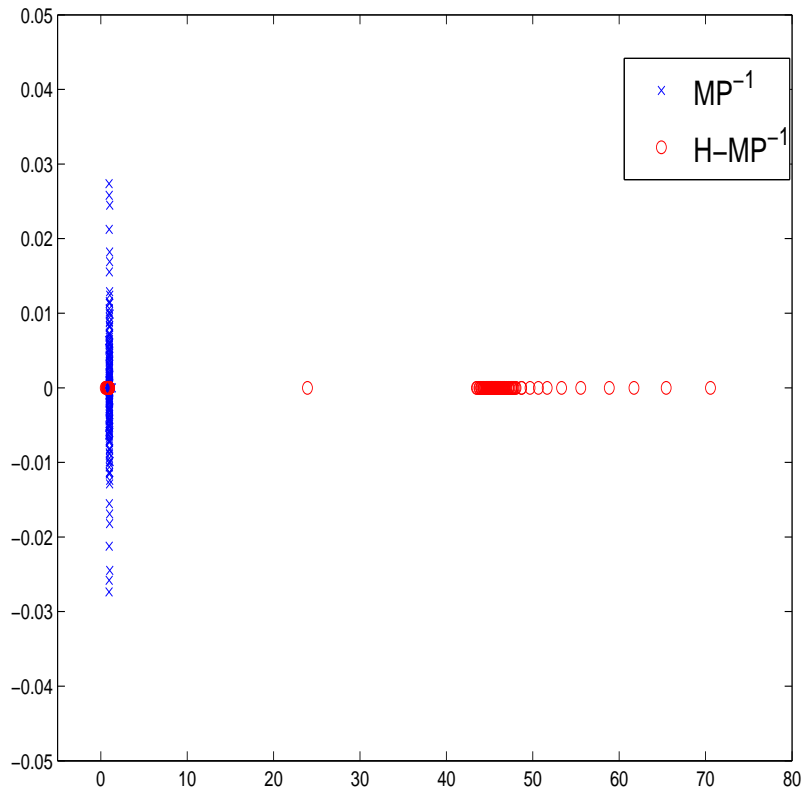
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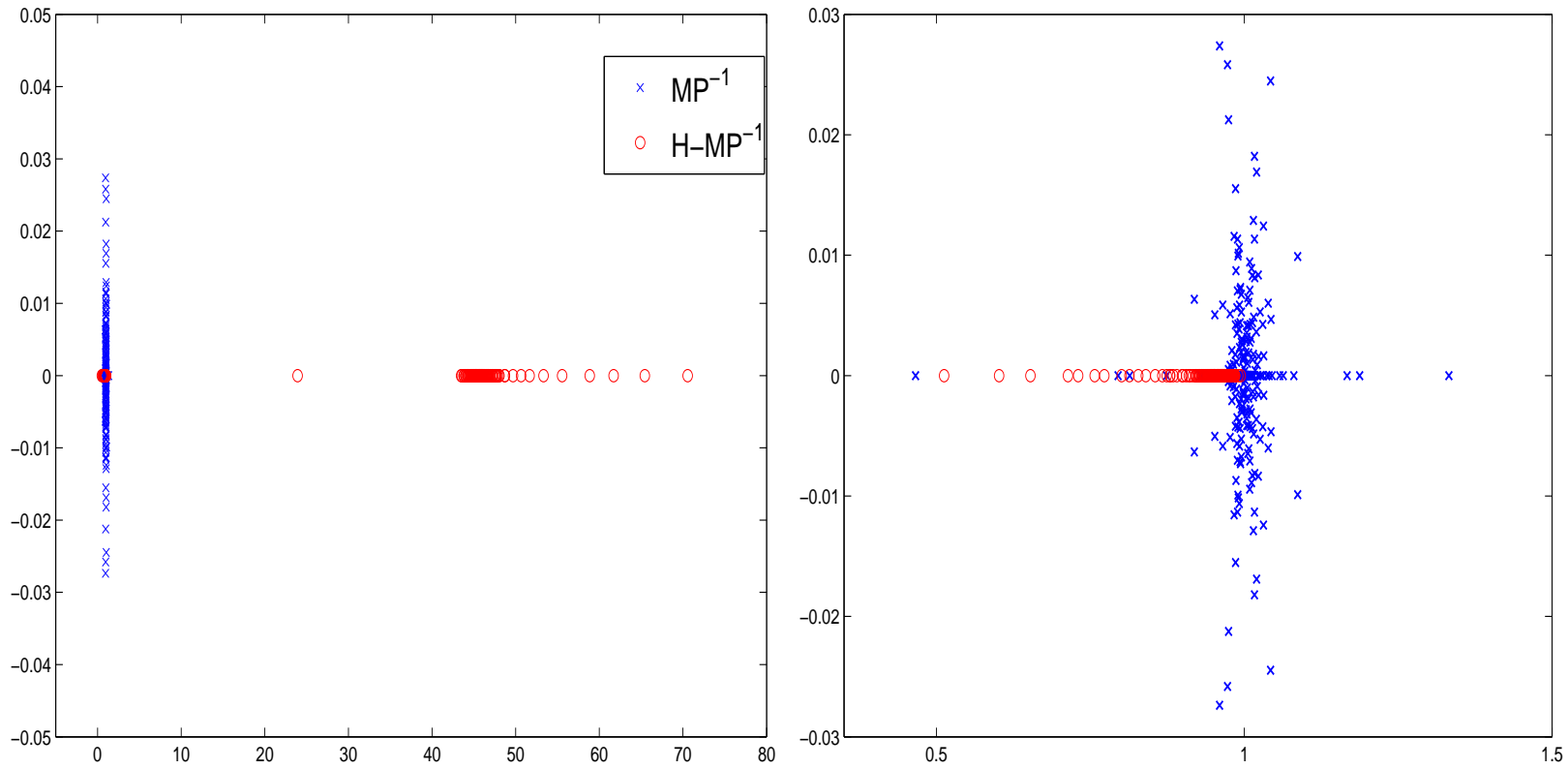
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Class of indefinite preconditioners. Spectra.



Class of indefinite preconditioners. Spectra.



Conclusions

- Use H -symmetric solvers when problem knowledge (with moderation)
- More confidence with nonsymmetric solvers
- More theoretical work needed for nonsymmetric preconditioners (and solvers)