

# Nonanticipative functional calculus and controlled rough paths

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## Notations

$D([0, T], \mathbb{R}^d)$  space of cadlag functions (right continuous with left limits).

$C^\alpha([0, T], \mathbb{R}^d)$   $\alpha$ -Holder functions

For a path  $\omega \in D([0, T], \mathbb{R}^d)$ , denote by

- ▶  $\omega(t) \in \mathbb{R}^d$  the value of  $\omega$  at  $t$
- ▶  $\omega_t = \omega(t \wedge \cdot)$ : path stopped at  $t$
- ▶  $\omega_{t-} = \omega \cdot 1_{[0, t[} + \omega(t-) \cdot 1_{[t, T]}$

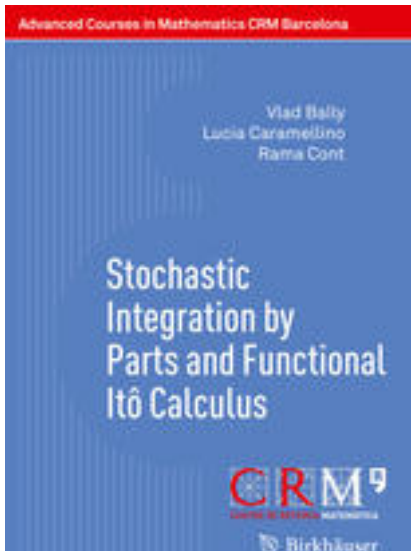
For a process  $X$  we denote

- ▶  $X(t)$  its value and
- ▶  $X_t = X(t \wedge \cdot)$  its path stopped at  $t$ .



- ▶ A Ananova, R Cont (2017) Pathwise integration with respect to paths of finite quadratic variation, *Journal de Mathématiques Pures et appliquées*.
- ▶ A Ananova, R Cont (2017) Functionals of irregular paths as controlled rough paths, WP.
- ▶ R Cont, P Das (2017) On pathwise quadratic variation, WP.
- ▶ R Cont & Yi LU (2016) Weak approximations for martingale representations, *Stochastic Processes and Applications*
- ▶ R Cont & Candia Riga (2015) Pathwise analysis and robustness of hedging strategies for path-dependent derivatives, Working Paper.
- ▶ R Cont *Functional Ito Calculus and Functional Kolmogorov Equations*, (Lectures Notes of the Barcelona Summer School on Stochastic Analysis, July 2012), Springer.
- ▶ R Cont and D Fournié (2010) Change of variable formulas for non-anticipative functional on path space, *Journal of Functional Analysis*, 259, 1043 - 1072.





## A pathwise approach of the Ito formula

Consider a continuous  $\mathbb{R}^d$ -valued process  $X$  and  $f \in C^2(\mathbb{R}^d, \mathbb{R})$ . The main idea in the proof of the Ito formula is to consider a sequence of partitions  $\pi_n = (0 = t_0^n < t_1^n \dots < t_{N(\pi_n)}^n = T)$  of  $[0, T]$  with step size decreasing to zero and expand increments of  $f(X(t))$  along the partition using a 2nd order Taylor expansion:

$$\begin{aligned} f(X(t)) - f(X(0)) &= \sum_{\pi_n} f(X(t_{i+1}^n)) - f(X(t_i^n)) \\ &= \sum_{\pi_n} \nabla f(X(t_i^n)) \cdot (X(t_{i+1}^n) - X(t_i^n)) \\ &\quad + \frac{1}{2} {}^t(X(t_{i+1}^n) - X(t_i^n)) \nabla^2 f(X(t_i^n)) \cdot (X(t_{i+1}^n) - X(t_i^n)) + r(X(t_{i+1}^n), X(t_i^n)) \end{aligned}$$



Summing over  $\pi_n$  we get

$$f(X(t)) - f(X(0)) = S_1(\pi_n, f) + S_2(\pi_n, f) + R(\pi_n, f)$$

- ▶ By uniform continuity of

$$r(x, y) = f(y) - f(x) - \nabla f(x) \cdot (y - x) - 0.5^t (y - x) \nabla^2 f(x) (y - x),$$

$$r(x, y) \leq \varphi(\|x - y\|) \|x - y\|^2$$

with  $\varphi(u) \rightarrow 0$  as  $u \rightarrow 0$  so  $R(\pi_n, f) = \sum_{\pi_n} r(X(t_{i+1}^n), X(t_i^n)) \rightarrow 0$  pointwise if  $\sum_{\pi_n} \|X(t_{i+1}^n) - X(t_i^n)\|^2$  bounded.

- ▶ Under this condition the (left) Riemann sum

$S_1(\pi_n, f) = \sum_{\pi_n} \nabla f(X(t_i^n)) \cdot (X(t_{i+1}^n) - X(t_i^n))$  converges **if and only if** the 'quadratic Riemann sum'

$$S_2(\pi_n, f) = \frac{1}{2} \sum_{\pi_n} {}^t(X(t_{i+1}^n) - X(t_i^n)) \nabla^2 f(X(t_i^n)) \cdot (X(t_{i+1}^n) - X(t_i^n))$$

converges.



## Quadratic Riemann sums

For  $d=1$ : given a path of  $X$ , pointwise convergence of 'quadratic Riemann sums'

$$S_2(\pi_n, f) = \frac{1}{2} \sum_{\pi_n} \nabla^2 f(X(t_i^n)) \cdot (X(t_{i+1}^n) - X(t_i^n))^2$$

along the path for every  $f \in C^2(\mathbb{R}^d, \mathbb{R})$  is exactly equivalent to the weak convergence of the sequence of discrete measures

$$\mu_n = \sum_{t_j \in \pi^n} (X(t_{j+1}^n) - X(t_j^n))^2 \delta_{t_j}$$

where  $\delta_t$  denotes a point mass at  $t$ . This is a joint property of  $X$  and  $(\pi_n)$ .

This motivated Föllmer (1981)'s definition of 'pathwise quadratic variation along a sequence of partitions.



## Definition (Quadratic variation along a sequence of partitions)

Let  $\pi_n = (0 = t_0^n < t_1^n \dots < t_{N(\pi_n)}^n = T)$  be a sequence of partitions of  $[0, T]$  with step  $|\pi_n|$  decreasing to zero. A càdlàg function  $x \in D([0, T], \mathbb{R})$  is said to have finite quadratic variation along the sequence of partitions  $(\pi_n)_{n \geq 1}$  if

(i) the sequence of discrete measures

$$\sum_{t_j \in \pi^n} (x(t_{j+1}^n) - x(t_j^n))^2 \delta_{t_j} \xrightarrow[n \rightarrow \infty]{\Rightarrow} \mu(dt) = d[\omega]_\pi$$

converges weakly;

(ii)  $[x]_\pi^c$  defined by  $[x]_\pi^c(t) = \mu([0, t]) - \sum_{0 < s \leq t} |\Delta x(s)|^2$  is continuous and increasing.

We denote  $Q_\pi([0, T], \mathbb{R})$  the set of functions with the above properties.





## Characterization in continuous case

### Proposition (C. & Das (2017))

Let  $x \in C^0([0, T], \mathbb{R})$  and define

$$[x]_{\pi_n}(t) = \sum_{t_j \in \pi^n} (\omega(t_{j+1}^n \wedge t) - \omega(t_j^n \wedge t))^2$$

The following properties are equivalent:

1.  $x$  has finite quadratic variation along the sequence of partitions  $(\pi_n)_{n \geq 1}$ .
2. The sequence  $[x]_{\pi_n}$  converges uniformly on  $[0, T]$  to a continuous function  $[x]_{\pi}$ .
3. The sequence  $[x]_{\pi_n}$  converges pointwise on  $[0, T]$  to a continuous function  $[x]_{\pi}$ .



## Definition (Pathwise quadratic variation: multidimensional case)

$x \in Q_\pi([0, T], \mathbb{R}^d)$  if, for all  $1 \leq i, j \leq d$ ,  $x^i, x^i + x^j$  in  $Q_\pi([0, T], \mathbb{R})$ .  
 $[x]_\pi$  is a positive symmetric  $d \times d$  matrix:

$$[x]_\pi(t) = \lim_{n \rightarrow \infty} \sum_{t_i^n \leq t} (x(t_{i+1}^n) - x(t_i^n)) \cdot (x(t_{i+1}^n) - x(t_i^n)) < +\infty,$$

with elements given by

$$\begin{aligned} ([x]_\pi)_{i,j}(t) &= \frac{1}{2} \left( [x^i + x^j]_\pi(t) - [x^i]_\pi(t) - [x^j]_\pi(t) \right) \\ &= [x^i, x^j]_\pi^c(t) + \sum_{0 < s \leq t} \Delta x^i(s) \Delta x^j(s), \quad i, j = 1, \dots, d \end{aligned}$$



## Föllmer's 'pathwise Ito formula'

### Proposition (Föllmer, 1981)

$\forall f \in C^2(\mathbb{R}^d, \mathbb{R}), \forall \omega \in Q_\pi([0, T], \mathbb{R}^d)$ , the non-anticipative Riemann sums along  $\pi$

$$\sum_{\pi_n} \nabla f(\omega(t_i^n)) \cdot (\omega(t_{i+1}^n) - \omega(t_i^n)) \xrightarrow{n \rightarrow \infty} \int_0^T \nabla f(\omega(t)) \cdot d^\pi \omega$$

converge pointwise and

$$\begin{aligned} f(\omega(t)) - f(\omega(0)) &= \int_0^t \nabla f(\omega) \cdot d^\pi \omega + \frac{1}{2} \int_0^t \langle \nabla^2 f(\omega), d[\omega]_\pi^c \rangle \\ &+ \sum_{s \leq t} f(\omega(s)) - f(\omega(s-)) - \nabla f(\omega(s-)) \cdot \Delta \omega(s) \end{aligned}$$



## Dependence on the partition

Consider now two sequences of partitions  $\pi, \tau$  and a continuous path  $\omega \in Q_\pi([0, T], \mathbb{R}^d) \cap Q_\tau([0, T], \mathbb{R}^d)$ .

Since  $\forall f \in C^2(\mathbb{R}^d)$ ,

$$\begin{aligned} f(\omega(t)) - f(\omega(0)) &= \int_0^t \nabla f(\omega) \cdot d^\pi \omega + \frac{1}{2} \int_0^t \langle \nabla^2 f(\omega), d[\omega]_\pi \rangle \\ &= \int_0^t \nabla f(\omega) \cdot d^\tau \omega + \frac{1}{2} \int_0^t \langle \nabla^2 f(\omega), d[\omega]_\tau \rangle \end{aligned} \quad (1)$$

the pathwise integrals are equal if and only if  $[\omega]_\pi = [\omega]_\tau$ .

But the pathwise quadratic variation **does** depend on the sequence of partition...



## Quadratic variation along a sequence of partitions

This notion of 'pathwise quadratic variation along a sequence of partitions' depends on the chosen sequence of partitions:

### Proposition ((Friedman))

*Let  $\omega \in C^0([0, T], \mathbb{R}^d)$ . There exists a sequence of partitions  $(\pi_n)$  such that  $[\omega]_{\pi} = 0$ .*

Proof: We construct recursively partitions  $\pi_n$  such that

$$|\pi_n| \leq \frac{1}{n} \quad \text{and} \quad \sum_{\pi_n} |\omega(t_{k+1}^n) - \omega(t_k^n)|^2 \leq \frac{1}{n}.$$

Assume we have constructed  $\pi_n$  with this property. Adding to  $\pi_n$  the points  $k/(n+1)$ ,  $k = 1..n$  we obtain a partition  $\sigma_n = (s_i^n, i = 0..M_n)$  with  $|\sigma_n| \leq 1/(n+1)$ .



For  $i = 0..(M_n - 1)$ , we further refine  $[s_i^n, s_{i+1}^n]$  as follows. Let  $J(i)$  be an integer with

$$J(i) \geq (n+1)M_n |\omega(s_{i+1}^n) - \omega(s_i^n)|^2,$$

$$\tau_{i,k+1}^n = \inf \left\{ t \geq \tau_{i,k}^n, \quad \omega(t) = \omega(s_i^n) + \frac{k(\omega(s_{i+1}^n) - \omega(s_i^n))}{J(i)} \right\}.$$

Then points  $(\tau_{i,k}^n, k = 1..J(i))$  defines a partition of  $[s_i^n, s_{i+1}^n]$  with

$$|\tau_{i,k+1}^n - \tau_{i,k}^n| \leq \frac{1}{n+1} \quad \text{and} \quad |\omega(\tau_{i,k+1}^n) - \omega(\tau_{i,k}^n)| = \frac{|\omega(s_{i+1}^n) - \omega(s_i^n)|}{J(i)}$$

$$\text{so} \quad \sum_{k=1}^{J(i)} |\omega(\tau_{i,k+1}^n) - \omega(\tau_{i,k}^n)|^2 \leq J(i) \frac{|\omega(s_{i+1}^n) - \omega(s_i^n)|^2}{J(i)^2} = \frac{1}{(n+1)M_n}.$$

Sorting  $(\tau_{i,k}^n, i = 0..M_n, k = 1..J(i))$  gives  $\pi_{n+1} = (t_j^{n+1})$  such that

$$|\pi_{n+1}| \leq \frac{1}{n+1}, \quad \sum_{\pi_{n+1}} |\omega(t_{i+1}^n) - \omega(t_i^n)|^2 \leq \frac{1}{n+1}.$$



## Definition (Well-balanced sequence of partitions)

Let  $\pi_n = \inf_{i=0..N(\pi_n)-1} |t_{i+1}^n - t_i^n|$ .

The sequence of partitions  $(\pi_n)_{n \geq 1}$  well-balanced if

$$\exists c > 0, \quad \forall n \geq 1, \quad \frac{|\pi_n|}{\pi_n} \leq c. \quad (2)$$

## Theorem (R.C. & P. Das, 2016)

Let  $\alpha > 0$ ,  $f \in C^\alpha([0, T], \mathbb{R}^d)$  and  $\tau = (\tau^n)_{n \geq 1}$  and  $\sigma = (\sigma^n)_{n \geq 1}$  two well-balanced partition sequences such that

$$f \in Q_\tau([0, T], \mathbb{R}^d) \cap Q_\sigma([0, T], \mathbb{R}^d) \quad \text{and} \quad [f]_\sigma > 0, \quad [f]_\tau > 0.$$

Then:  $\forall t \in [0, T], \quad [f]_\sigma(t) = [f]_\tau(t)$



## Non-anticipative Functionals

Denote  $\omega_t = \omega(t \wedge \cdot)$  the *past* i.e. the path stopped at  $t$ .

### Definition (Non-anticipative Functionals)

A *causal*, or *non-anticipative functional* is a functional  $F : [0, T] \times D([0, T], \mathbb{R}^d) \mapsto \mathbb{R}$  whose value only depends on the past:

$$\forall \omega \in \Omega, \quad \forall t \in [0, T], \quad F(t, \omega) = F(t, \omega_t). \quad (3)$$

Causal functional = map on the space  $\Lambda_T^d$  of stopped paths, defined as the quotient space:

$$\Lambda_T^d := ([0, T] \times D([0, T], \mathbb{R}^d)) / \sim$$

where  $(t, x) \sim (t', x') \Leftrightarrow t = t', x_t = x'_t$ .  $\Lambda_T^d$  is equipped with a metric

$$d_\infty((t, x), (t', x')) = \sup_{u \in [0, T]} |x(u \wedge t) - x'(u \wedge t')| + |t - t'|.$$





## Functionals of piecewise constant paths

A piecewise-constant path  $\omega = \sum_{k=1}^n x_k 1_{[t_k, t_{k+1}[}$  is obtained by

- ▶ “horizontal stretchings” from  $t_k$  to  $t_{k+1}$ , followed by
- ▶ addition of a jump at each discontinuity point:

$$\omega_{t_{k+1}} = \omega_{t_k} + (x_{k+1} - x_k) 1_{t_{k+1}}$$

Key idea: The evolution of a non-anticipative functional along  $\omega$  may be decomposed into its variations with respect to two types of operations:

- ▶ “horizontal extension” of the path from  $t_k$  to  $t_{k+1}$

$$F(t_{k+1}, \omega_{t_k}) - F(t_k, \omega_{t_k})$$

- ▶ ‘vertical step’ at partition points: addition of a jump at  $t_{k+1}$

$$F(t_{k+1}, \omega_{t_{k+1}}) - F(t_{k+1}, \omega_{t_k})$$

If one can control the behavior of  $F$  under these two types of path perturbations, then one can follow/reconstitute  $F(t, \omega)$ .



## Definition (Horizontal and vertical derivatives)

A non-anticipative functional  $F$  is said to be:

- ▶ horizontally differentiable at  $(t, \omega) \in \Lambda_T^d$  if the finite limit exists

$$DF(t, \omega) := \lim_{h \rightarrow 0^+} \frac{F(t+h, \omega_t) - F(t, \omega_t)}{h}.$$

- ▶ vertically differentiable at  $(t, \omega) \in \Lambda_T^d$  if the map

$$\mathbb{R}^d \rightarrow \mathbb{R}, e \mapsto F(t, \omega(t \wedge \cdot) + e1_{[t, T]})$$

is differentiable at 0; its gradient at 0 is denoted by  $\nabla_\omega F(t, \omega)$ .

Note that  $DF(t, \omega)$  is **not** the partial derivative in  $t$ :

$$DF(t, \omega) \neq \partial_t F(t, \omega) = \lim_{h \rightarrow 0} \frac{F(t+h, \omega) - F(t, \omega)}{h}.$$



## Smooth functionals

### Definition ( $\mathbb{C}_b^{1,2}(\Lambda_T^d)$ functionals)

We denote by  $\mathbb{C}_b^{1,2}(\Lambda_T^d)$  the set of non-anticipative functionals  $F \in \mathbb{C}_i^{0,0}(\Lambda_T^d)$ , such that

- ▶  $F$  is horizontally differentiable with  $\mathcal{D}F$  continuous at fixed times,
- ▶  $F$  is twice vertically differentiable with  $\nabla_\omega^j F \in \mathbb{C}_i^{0,0}(\Lambda_T^d)$  for  $j = 1, 2$ ;
- ▶  $\mathcal{D}F, \nabla_\omega F, \nabla_\omega^2 F \in \mathbb{B}(\Lambda_T^d)$ .



## Examples of smooth functionals

### Example (Cylindrical functionals)

For  $g \in C^0(\mathbb{R}^{d \times n})$ ,  $h \in C^k(\mathbb{R}^d)$  with  $h(0) = 0$ . Then

$$F(t, \omega) = h(\omega(t) - \omega(t_n-)) \mathbf{1}_{t \geq t_n} g(\omega(t_1-), \omega(t_2-), \dots, \omega(t_n-))$$

is in  $\mathbb{C}_b^{1,k}$  and

$$\mathcal{D}_t F(\omega) = 0, \quad \text{and} \quad \forall j = 1..k,$$

$$\nabla_{\omega}^j F(t, \omega) = h^{(j)}(\omega(t) - \omega(t_n-)) \mathbf{1}_{t \geq t_n} g(\omega(t_1-), \omega(t_2-), \dots, \omega(t_n-))$$

$\mathbb{S}(\Lambda_T, \pi_n) :=$  space of simple predictable cylindrical functionals piecewise constant along  $\pi_n$ ,  $\mathbb{S}(\Lambda_T, \pi) := \cup_{n>1} \mathbb{S}(\Lambda_T, \pi_n)$



## Examples of smooth functionals

### Example (Integral functionals)

For  $g \in C_0(\mathbb{R}^d)$ ,  $Y(t) = \int_0^t g(X(u))\rho(u)du = F(t, X_t)$  where

$$F(t, \omega) = \int_0^t g(\omega(u))\rho(u)du \quad (4)$$

$F \in \mathbb{C}_b^{1,\infty}$ , with:

$$\mathcal{D}_t F(\omega) = g(\omega(t))\rho(t) \quad \nabla_\omega^j F(t, \omega) = 0 \quad (5)$$



## Conditional expectations as smooth functionals

Let  $\sigma \in \mathbb{C}^{0,0}(\mathcal{W}_T)$  be such that

$$X(t) = X(0) \exp \left( \int_0^t \sigma(u) dW(u) - \frac{1}{2} \int_0^t \sigma^2(u) \cdot du \right) \quad (*)$$

is a martingale, i.e.  $E(X(T)) = 1$  and denote by  $\mathbb{Q}^\sigma$  the law of (\*).

### Proposition (Cont & Riga 2015)

Let  $h : (D([0, T], \mathbb{R}), \|\cdot\|_\infty) \mapsto \mathbb{R}$  be  $\mathbb{Q}^\sigma$ -integrable and Lipschitz. Assume that for  $(t, \omega) \in \mathcal{W}_T$ , the map

$$g^h(\cdot; t, \omega) : e \in \mathbb{R}^d \rightarrow g^h(e) = h(\omega + e1_{[t, T]}), \quad (6)$$

is twice differentiable at 0, with derivatives bounded uniformly in  $(t, \omega) \in \mathcal{W}_T$  in a neighborhood of 0. Then, there exists  $F \in \mathbb{C}_b^{0,2}(\mathcal{W}_T)$  such that  $F(t, X_t) = E^{\mathbb{Q}^\sigma} [H | \mathcal{F}_t^X]$   $\mathbb{Q}^\sigma$ -a.s.



## Weak Euler schemes as smooth functionals

Let  $\sigma : (\Lambda_T, d_\infty) \rightarrow \mathbb{R}^{d \times d}$  be a Lipschitz map. Then

$${}_n X(t_{j+1}, \omega) = {}_n X(t_j, \omega) + \sigma(t_j, {}_n X_{t_j}(\omega)) \cdot (\omega(t_{j+1}-) - \omega(t_j-)). \quad (7)$$

defines a non-anticipative functional  ${}_n X$  which approximates

$$X(t) = X(0) + \int_0^t \sigma(u, X_u) dW(u) \quad (8)$$

For a Lipschitz functional  $g : (D([0, T], \mathbb{R}^d), \|\cdot\|_\infty) \rightarrow \mathbb{R}$ , consider the 'weak Euler approximation' of  $\mathbb{E} [g(X_T) | \mathcal{F}_t^W]$ :

$$F_n(t, \omega) = \mathbb{E} [g({}_n X_T(W_T)) | \mathcal{F}_t^W] (\omega). \quad (9)$$

**(R Cont- Yi Lu, SPA 2016):**  $F_n \in \mathbb{C}_b^{1, \infty}(\mathcal{W}_T)$ .



## Controlled Hölder rough paths

### Definition (Controlled rough path (Gubinelli 2004))

Let  $X \in C^\alpha([0, T], V)$ .  $Y \in C^\alpha([0, T], W)$  is a controlled rough path controlled by  $X$  if there exists  $Y' \in C^\alpha([0, T], \mathcal{L}(V, W))$  such that

$$R(s, t) = Y(t) - Y(s) - Y'_s \cdot (X(t) - X(s)), \quad T \geq t \geq s \geq 0$$

satisfies  $\|R\|_\nu < \infty$ . for some  $\nu > \alpha$ .

$X$  is called the *control* or *reference path*.

$R(s, t)$  can be thought of as the remainder in a first order Taylor expansion.

Any  $Y'$  satisfying this property is called a 'Gubinelli derivative' for  $Y$ .





## Regular functionals as controlled rough paths

If  $F \in \mathcal{R}(\Lambda_T^d)$ ,  $\omega \in C^\nu([0, T], \mathbb{R}^d)$  then  $t \mapsto (F(t, \omega), \nabla_\omega F(t, \omega))$  is a rough path controlled by  $\omega$  in the sense of Gubinelli (2004):

### Proposition

Let  $\omega \in C^\nu([0, T], \mathbb{R}^d)$  for some  $\nu \in (1/3, 1/2]$  and  $F \in \mathbb{C}_b^{1,2}(\Lambda_T^d, \mathbb{R}^n)$  with  $\nabla_\omega F \in \mathbb{C}_b^{1,1}(\Lambda_T^d, \mathbb{R}^{n \times d})$  and  $F \in \text{Lip}(\Lambda_T^d, \|\cdot\|_\infty)$ . Define

$$R_{s,t}^F(\omega) := F(s, \omega_s) - F(t, \omega_t) - \nabla_\omega F(t, \omega_t)(\omega(s) - \omega(t)). \quad (10)$$

Then there exists a constant  $C_{F,T,\omega}$ , increasing in  $T$  and  $\|\omega\|_\nu$ , such that

$$|R_{s,t}^F(\omega)| \leq C_{F,T,\omega} |s - t|^{2\nu(1+\nu)}$$



## Controlled rough paths as regular functionals

Conversely, a **family** of controlled rough paths indexed by the reference path is none other than a .. vertically differentiable functional, whose 'Gubinelli derivative' is none other than the Dupire/ vertical derivative:

### Proposition (Ananova & Cont, 2017)

*Let  $F \in \mathbb{C}^{0,0}(\mathcal{W}_T^d, \mathbb{R})$ ,  $G \in \mathbb{C}^{0,0}(\mathcal{W}_T^d, \mathbb{R}^d)$  be non-anticipative functionals. Assume that for any  $\omega \in C^\nu([0, T])$ ,  $\nu \in (0, 1)$  the pair  $(F(\cdot, \omega), G(\cdot, \omega))$  is a controlled rough path with respect to  $\omega$  s.t.  $\exists C_{F,T,\omega} > 0$*

$$|F(s, \omega_s) - F(t, \omega_t) - G(t, \omega_t)(\omega(s) - \omega(t))| \leq C|s - t| + C|s - t|^{\nu(1+\nu)},$$

*where the constants depend only on  $T, F$  and  $\|\omega\|_\nu$ . Then  $F \in \mathbb{C}^{0,1}(\mathcal{W}_T^d, \mathbb{R})$  and  $\nabla_\omega F(t, \omega) = G(t, \omega)$ .*



## Chain rule for functionals

### Proposition

Let  $G \in \mathbb{C}_b^{1,1}(\Lambda_T^d)$  and  $F \in \mathbb{C}_b^{1,1}(\Lambda_T^1)$  be non anticipative functionals and  $H(\omega, t) := F(G(t, \omega), t)$ . Then  $H \in C_b^{1,1}(\Lambda_T^d)$  and

$$\mathcal{D}H(t, \omega_t) = \mathcal{D}F(t, G(t, \omega_t)) + \nabla F(t, G(t, \omega_t))\mathcal{D}G(t, \omega_t),$$

$$\nabla H(t, \omega_t) = \nabla F(t, G(t, \omega_t))\nabla G(t, \omega_t).$$

Moreover, if  $G, F \in C_b^{1,2}$  then  $H \in C_b^{1,2}$  and

$$\begin{aligned} \nabla^2 H(t, \omega_t) &= \nabla F(t, G(t, \omega_t))\nabla G(t, \omega_t) {}^t\nabla G(t, \omega_t) \\ &\quad + \nabla F(t, G(t, \omega_t))\nabla^2 G(t, \omega_t) \end{aligned} \quad (11)$$



This result implies the stability of the concept controlled rough paths under smooth functionals:

## Proposition (Change of variable formula for controlled rough paths)

Let  $(X, X') \in \mathcal{D}_\omega^{2\nu}([0, T], \mathbb{R}^d)$  be a controlled rough path with control  $\omega \in C^\nu([0, T], \mathbb{R}^d)$ . Then for any  $F \in \mathbb{C}_b^{1,1}(\Lambda_T^1)$ ,

$$(F(t, X), \nabla_\omega F(t, X) \cdot X') \in \mathcal{D}_X^{2\nu}([0, T], \mathbb{R}^d)$$

is a controlled rough path with control  $X$ .

Similar transformation rules exist in the theory of controlled rough paths ( see Friz-Hairer Ch .4) but here the derivation is much simpler.



The concept of controlled rough path does not come with a natural approximation theory. Our representation yields such an approximation theory.

Let  $(X, X') \in \mathcal{D}_\omega^{2\nu}([0, T], \mathbb{R}^d)$  be a controlled rough path with control  $\omega \in C^\nu([0, T], \mathbb{R}^d)$  and  $F \in \mathbb{C}_b^{1,1}(\Lambda_T^1)$  a functional such that  $(X, X') = (F(\cdot, \omega), \nabla_\omega F(\cdot, \omega))$ .

Then if  $X_n = F_n(\cdot, \omega)$  is a sequence of (piecewise) smooth approximations of  $X$  then a natural approximation for  $(X, X')$  is  $(X_n, \nabla_\omega F_n(\cdot, \omega))$

Example (C.-Lu, 2016): numerical approximations of martingale representations.



## Theorem (Change of variable formula (Cont- Fournié ,2010))

Let  $\omega \in Q^\pi ([0, T], \mathbb{R}^d)$  such that  $\sup_{t \in [0, T] \setminus \pi^n} |\Delta\omega(t)| \rightarrow 0$  and denote  $\omega^n := \sum_{i=0}^{m(n)-1} \omega(t_{i+1}^n -) \mathbf{1}_{[t_i^n, t_{i+1}^n)} + \omega(T) \mathbf{1}_{\{T\}}$ . Then for any  $F \in \mathbb{C}_b^{1,2}(\Lambda_T^d)$ , the limit

$$\int_0^T \nabla_\omega F(t, \omega_{t-}) \cdot d^\pi \omega = \lim_{n \rightarrow \infty} \sum_{i=0}^{m(n)-1} \nabla_\omega F(t_i^n, \omega_{t_i^n-}^{n, \Delta\omega(t_i^n)}) (\omega(t_{i+1}^n) - \omega(t_i^n))$$

exists, and

$$\begin{aligned} F(T, \omega) &= F(0, \omega) + \int_0^T \nabla_\omega F(t, \omega_{t-}) \cdot d^\pi \omega + \int_0^T \mathcal{D}F(t, \omega_{t-}) dt \\ &+ \int_0^T \frac{1}{2} \text{tr} (\nabla_\omega^2 F(t, \omega_{t-}) d[\omega]_\pi^c(t)) + \sum_{s \in [0, T]} (F(s, \omega_s) - F(s, \omega_{s-}) - \nabla_\omega F(s, \omega_{s-}) \cdot \Delta\omega(s)). \end{aligned}$$

(ChV)



## Functional Ito formula

Applied to a semimartingale, these results lead to a functional extension of the Ito formula:

**Theorem (Functional Ito formula (Dupire 09, C.& Fournié 2009))**

Let  $X$  be a continuous semimartingale and  $F \in \mathbb{C}_{loc}^{1,2}([0, T[)$ . For any  $t \in [0, T[$ ,

$$F(t, X_t) - F_0(X_0) = \int_0^t \mathcal{D}_u F(X_u) du + \int_0^t \nabla_\omega F_u(X_u) \cdot dX(u) + \int_0^t \frac{1}{2} \text{tr}({}^t \nabla_\omega^2 F_u(X_u) d[X](u)) \quad \text{a.s.}$$

In particular,  $Y(t) = F(t, X_t)$  is a semimartingale.

## Brownian martingales as harmonic functionals

### Theorem (R.C. & D Fournié 2010)

Let  $\mathbb{P}$  be the Wiener measure on the canonical space,  
 $H : (D([0, T], \mathbb{R}^d), \|\cdot\|_\infty) \mapsto \mathbb{R}$  a  $\mathbb{P}$ -integrable functional. If there exists  
 $F \in \mathbb{C}_{loc}^{1,2}(\mathcal{W}_T)$  such that

$$M(t) = F(t, W.) = E^{\mathbb{P}}[H(W.) | \mathcal{F}_t^W] \quad \mathbb{P} - a.s.$$

then

$$\forall (t, \omega) \in \mathcal{W}_T, \quad \mathcal{D}F(t, \omega) + \frac{1}{2} \text{tr}(\nabla_\omega^2 F)(t, \omega) = 0$$

and

$$M(t) = F(t, W.) = M(0) + \int_0^t \nabla_\omega F(s, W) dW(s).$$





These result allows to construct  $\int_0^\cdot \nabla_\omega F$  as a pointwise limit of non-anticipative 'Riemann sums':

$$\int_0^T \nabla_\omega F(t, \omega_{t-}) \cdot d^\pi \omega = \lim_{n \rightarrow \infty} \sum_{i=0}^{m(n)-1} \nabla_\omega F(t_i^n, \omega_{t_i^n-}^{n, \Delta\omega(t_i^n)}) (\omega(t_{i+1}^n) - \omega(t_i^n))$$

## Remark

$$F \in \mathcal{R}(\Lambda_T^d), \omega \in C^{\frac{1}{2}-}([0, T], \mathbb{R}^d) \Rightarrow \nabla_\omega F(t, \omega) \in C^{\frac{1}{2}-}([0, T], \mathbb{R}^d).$$

*The pathwise integral is a strict extension of the Young integral.*

Does this integral verify any continuity/ stability property?

Does it share any of the other 'nice' properties of the Ito integral?



## Assumptions on $F$

### Assumption (Lipschitz continuity of $F$ )

$F \in Lip(\Lambda_T^d, \|\cdot\|_\infty)$ :  $\exists K > 0, \quad \forall \omega, \omega' \in D([0, T], \mathbb{R}^d),$

$$|F(t, \omega) - F(t, \omega')| \leq K \|\omega_t - \omega'_t\|_\infty$$

### Assumption (Regularity of $F$ )

$F \in \mathbb{C}^{1,2}(\Lambda_T)$  and  $\nabla_\omega F \in \mathbb{C}_b^{1,1}(\Lambda_T^d).$



Denote  $C^{\frac{1}{2}-}([0, T], \mathbb{R}^d) = \bigcap_{\nu < 1/2} C^{\nu}([0, T], \mathbb{R}^d)$

## Theorem (Pathwise Isometry formula, A. Ananova, R. C. 2016)

*Under the above assumptions on  $F \in \mathbb{C}^{1,2}(\Lambda_T)$ , for any path  $\omega \in Q_{\pi}([0, T], \mathbb{R}) \cap C^{1/2-}([0, T], \mathbb{R}^d)$  and any sequence of partitions  $\pi = (\pi_n)_{n \geq 1}$  satisfying  $\text{osc}(F(\cdot, \omega), \pi_n) \rightarrow_{n \rightarrow +\infty} 0$  we have*

$$[F(t, \omega)]^{\pi}(t) = \left[ \int_0^{\cdot} \nabla_{\omega} F(s, \omega) \cdot d^{\pi} \omega \right]^{\pi}(t) = \int_0^t \langle {}^t \nabla_{\omega} F(s, \omega) \cdot \nabla_{\omega} F(s, \omega), d[\omega]^{\pi}(s) \rangle.$$

(Isometry)



As a consequence:

## Proposition

*Let  $\omega \in Q_\pi([0, T], \mathbb{R}^d) \cap C^{1/2-}([0, T], \mathbb{R}^d)$  such that  $\frac{d[\omega]}{dt} := a(t) > 0$  is right-continuous. Then the path  $t \mapsto F(t, \omega)$  has a zero quadratic variation along the partition  $\pi$  if and only if  $\nabla_\omega F(t, \omega) = 0, \forall t \in [0, T]$ .*



## Proof of the pathwise isometry formula

For simplicity set  $d = 1$ . Let

$$\mathcal{R}_{s,t}^{F,\omega} := F(s, \omega) - F(t, \omega) - \nabla_{\omega} F(t, \omega)(\omega(s) - \omega(t)).$$

First we prove that

$$|\mathcal{R}_{s,t}^{F,\omega}| \lesssim_{F,T,\|\omega\|_{\nu}} |s - t|^{\nu(1+\nu)}, \quad \forall \nu < \frac{1}{2}. \quad (*)$$

For that, we will use the following formula for  $\mathcal{R}_{s,t}^{F,\lambda}$  for Lipschitz continuous paths  $\lambda$ :

$$\begin{aligned} \mathcal{R}_{t,s}^{F,\lambda} &= \int_t^s \mathcal{D}F(u, \lambda) du + \int_t^s \mathcal{D}\nabla_{\omega}^i F(r, \lambda)(\lambda^i(s) - \lambda^i(r)) dr \\ &\quad + \int_t^s \nabla_{\omega}^{ij} F(r, \lambda) \dot{\lambda}^j(r)(\lambda^i(s) - \lambda^i(r)) dr. \end{aligned} \quad (12)$$



(12) follows from the following result

## Lemma (R. C. 2012)

Assume  $G \in C_b^{1,1}(\Lambda_T)$  and  $\lambda$  is a continuous path with finite variation on  $[t, s]$ , then

$$G(s, \lambda) - G(t, \lambda) = \int_t^s \mathcal{D}G(u, \lambda) du + \int_t^s \nabla_\omega G(u, \lambda) d\lambda(u),$$

where the second integration is in the Riemann-Stieltjes sense.



Thanks to (12), Lipschitz property of  $F$  and since  $\omega \in C^\nu$ ,  $\forall \nu < \frac{1}{2}$ , we can construct a Lipschitz continuous approximation  $\omega^N$  to  $\omega$  such that

$$|\mathcal{R}_{t,s}^{F,\omega^N}| \lesssim |s-t| + N^{1-\nu}|s-t|^{2\nu}, \text{ and } |\mathcal{R}_{t,s}^{F,\omega^N} - \mathcal{R}_{t,s}^{F,\omega}| \lesssim N^{-\nu}|s-t|^\nu.$$

Thus

$$|\mathcal{R}_{t,s}^{F,\omega}| \lesssim |s-t| + N^{1-\nu}|s-t|^{2\nu} + N^{-\nu}|s-t|^\nu.$$

We conclude the proof of (\*) by choosing  $N \approx |s-t|^{-\nu}$ .



For the proof of the Theorem, note that from the assumptions on the partitions  $\pi_n$ , we have

$$M_n := \max_i \left| \mathcal{R}_{t_i^n, t_{i+1}^n}^{F, \omega} \right| \rightarrow 0.$$

Next we choose  $\nu$  close to  $\frac{1}{2}$  so that  $\nu^2 + \nu > \frac{1}{2}$ , then from (\*)

$$\sum_i \left| \mathcal{R}_{t_i^n, t_{i+1}^n}^{F, \omega} \right|^2 \leq CM_n^{2-\frac{1}{\nu^2+\nu}} \sum_i |t_{i+1}^n - t_i^n| \leq CTM_n^{2-\frac{1}{\nu^2+\nu}} \rightarrow 0.$$





Thus, since

$$\begin{aligned} & \left| (F(t_{i+1}^n, \omega) - F(t_i^n, \omega_{t_i^n}))^2 - \nabla_{\omega} F(t_i^n, \omega)^2 (\omega(t_{i+1}^n) - \omega(t_i^n))^2 \right| \\ & \leq |\mathcal{R}_{t_i^n, t_{i+1}^n}^{F, \omega}|^2 + C_F |\mathcal{R}_{t_i^n, t_{i+1}^n}^{F, \omega}| |\omega_{t_i^n, t_{i+1}^n}|, \end{aligned}$$

using the triangle and Cauchy-Schwarz inequalities, we get

$$\begin{aligned} & \left| \sum_i (F(t_{i+1}^n, \omega) - F(t_i^n, \omega_{t_i^n}))^2 - \sum_i \nabla_{\omega} F(t_i^n, \omega)^2 (\omega(t_{i+1}^n) - \omega(t_i^n))^2 \right| \\ & \leq \sum_i |\mathcal{R}_{t_i^n, t_{i+1}^n}^{F, \omega}|^2 + C_F \sqrt{\sum_i |\mathcal{R}_{t_i^n, t_{i+1}^n}^{F, \omega}|^2} \sqrt{\sum_i |\omega_{t_i^n, t_{i+1}^n}|^2} \rightarrow 0. \end{aligned}$$



The result of the Theorem now follows from the fact

$$\sum_i \nabla_\omega F(t_i^n, \omega)^2 (\omega(t_{i+1}^n) - \omega(t_i^n))^2 \rightarrow \int_0^T \nabla_\omega F(s, \omega)^2 d[\omega]^\pi(s)$$

which is a consequence of the weak convergence of

$$\sum_{t_i \in \pi^n} (\omega(t_{i+1}^n) - \omega(t_i^n))^2 \delta_{t_j} \rightharpoonup d[\omega]^\pi$$

and the strong convergence of

$$\sum_{t_i^n \leq t} \nabla_\omega F(t_i^n, \omega)^2 \mathbf{1}_{[t_i^n, t_{i+1}^n)} \rightarrow \nabla_\omega F(t, \omega)^2.$$



## Relation with Ito isometry

Let  $\mathbb{P}$  be a martingale measure on  $C^0([0, T], \mathbb{R})$  under which the canonical process  $X$  is a square integrable martingale. Then the integral  $\int_0^t \nabla_\omega F(t, \omega) \cdot d\pi_\omega$  is a version of the Ito integral  $\int_0^t \nabla_\omega F(t, X) dX$  and integrating the pathwise isometry formula with respect to  $\mathbb{P}$  yields the well-known Ito isometry formula :

$$E \left( \left[ \int_0^\cdot \nabla_\omega F(t, X) dX \right] (t) \right) = E \left( \int_0^t |\nabla_\omega F(t, X)|^2 d[X] \right).$$

So our pathwise isometry formula uncovers a pathwise relation which underlies the Ito isometry property.



## Theorem (Properties of the pathwise integral (R.C. 2012))

1. *Quadratic covariation formula: for  $\phi, \psi \in \mathbb{V}(\Lambda_T^d)$ , the limit*

$$[I_\omega(\phi), I_\omega(\psi)]_\pi(T) :=$$

$$\lim_{n \rightarrow \infty} \sum_{\pi_n} (I_\omega(\phi)(t_{k+1}^n) - I_\omega(\phi)(t_k^n)) (I_\omega(\psi)(t_{k+1}^n) - I_\omega(\psi)(t_k^n))$$

exists and  $[I_\omega(\phi), I_\omega(\psi)]_\pi(T) = \int_0^T \langle \psi^t \phi(t, \omega_{t-}), d[\omega] \rangle .$

2. *Associativity: Let  $\phi \in \mathbb{V}(\Lambda_T^d)$ ,  $\psi \in \mathbb{V}(\Lambda_T^1)$  and  $x \in D([0, T], \mathbb{R})$  defined by  $x(t) = \int_0^t \phi(u, \omega_{u-}) . d^\pi \omega$ . Then*

$$\int_0^T \psi(t, x_{t-}) . d^\pi x = \int_0^T \psi(t, (\int_0^\cdot \phi(u, \omega_{u-}) . d^\pi \omega)) \phi(t, \omega_{t-}) d^\pi \omega .$$



## Regular functionals

### Assumption (Horizontal local Lipschitz property)

A functional  $G: \Lambda_T^d \rightarrow \mathbb{R}$  is said to satisfy horizontal local Lipschitz property, if:  $\forall \omega \in D([0, T], \mathbb{R}^d), \exists C > 0, \eta > 0, \forall h \geq 0, \forall t \leq T - h,$

$$\|\omega_t - \omega'_t\|_\infty < \eta, \Rightarrow |G(t+h, \omega'_t) - G(t, \omega'_t)| \leq Ch.$$

### Definition (Regular Functionals)

$\mathcal{R}(\Lambda_T^d) =$  set of functionals  $F \in \mathbb{C}^{1,2}(\Lambda_T^d, \cdot)$  with  $\nabla_\omega^k F, \in \mathbb{C}_b^{1,1}(\Lambda_T^d), k = \overline{1, 2}, F, DF, \nabla^3 F \in Lip(\Lambda_T^d, \|\cdot\|_\infty)$  and  $\nabla_\omega^3 F$  horizontally locally Lipschitz.

Example: cylindrical non-anticipative functionals are regular.



## Uniqueness and pathwise nature of integral

### Proposition (Föllmer integral as a limit of Riemann sums)

Let  $F \in \mathcal{R}(\Lambda_T^d)$  and  $\omega \in Q_\pi([0, T], \mathbb{R}^d) \cap C^{1/2-}([0, T], \mathbb{R}^d)$ . Then

$$\int_0^T \nabla_\omega F(u, \omega) d^\pi \omega = \lim_{n \rightarrow +\infty} \sum_{i=0}^{m(n)-1} \nabla_\omega F(t_i^n, \omega) \cdot (\omega(t_{i+1}^n) - \omega(t_i^n)).$$

In particular, if  $\nabla F(t, \omega) = \nabla G(t, \omega)$  for  $F, G \in \mathcal{R}(\Lambda_T^d)$  then

$$\forall t \in [0, T], \quad \int_0^t \nabla_\omega F(u, \omega) d^\pi \omega = \int_0^t \nabla_\omega G(u, \omega) d^\pi \omega.$$



## Lemma

*Under the assumptions of the previous result, for consecutive endpoints  $t < s \in \pi^n$ , we have*

$$F(s, \omega_s) - F(t, \omega_t) = \int_t^s \mathcal{D}_t F(u, \omega_u) du + \nabla_\omega F(t, \omega_t) (\omega(s) - \omega(t)) \\ + \frac{1}{2} \langle \nabla_\omega^2 F(t, \omega_t), (\omega(s) - \omega(t)) \otimes (\omega(s) - \omega(t)) \rangle + O(|s - t|^{3\nu^2 + \nu}).$$



## The pathwise integral as a continuous map

### Definition ( $a$ -harmonic functionals)

Let  $a: [0, T] \rightarrow S_+^d$  be a continuous function taking values in positive-definite symmetric matrices.  $F \in \mathcal{H}_a(\Lambda_T)$  if

$$\forall (t, \omega) \in \Lambda_T, \quad \mathcal{D}F(t, \omega_t) + \frac{1}{2} \langle \nabla_\omega^2 F(t, \omega_t), a(t) \rangle = 0.$$

Let  $\bar{\omega} \in Q_\pi([0, T], \mathbb{R}^d) \cap C^p([0, T], \mathbb{R}^d)$ ,  $d[\bar{\omega}]_\pi/dt = a$ . Then

$$\forall F \in \mathcal{H}_a(\Lambda_T), \quad F(t, \bar{\omega}) = F(0, \bar{\omega}) + \int_0^t \nabla_\omega F(u, \bar{\omega}) \cdot d^\pi \bar{\omega}.$$

so by the isometry formula

$$[F(\cdot, \bar{\omega})]_\pi(t) = \int_0^t \nabla_\omega F(u, \bar{\omega}) \cdot a(u) \nabla_\omega F(u, \bar{\omega}) du = \|\nabla_\omega F(\cdot, \bar{\omega})\|_{L^2([0, T], a)}^2 < \infty.$$





## Continuity of the pathwise integral

Let  $\bar{\omega} \in Q_\pi([0, T], \mathbb{R}^d) \cap C^{1/2-}([0, T], \mathbb{R}^d)$ ,  $d[\bar{\omega}]_\pi/dt = a > 0$ .

$$\mathcal{H}_a(\bar{\omega}) := \{ F(\cdot, \bar{\omega}) \mid F \in \mathcal{H}_a(\Lambda_T) \} \subset Q_\pi([0, T], \mathbb{R}),$$

$$\mathbb{V}_a(\bar{\omega}) := \{ \nabla_\omega F(\cdot, \bar{\omega}) \mid F \in \mathcal{H}_a(\Lambda_T) \} \subset L^2([0, T], a).$$

### Proposition (Pathwise integral as an injective isometry)

*The pathwise integral*

$$I_{\bar{\omega}}(\phi) = \lim_{n \rightarrow \infty} \sum_{\pi_n} \phi(t_k^n) \cdot (\bar{\omega}(t_{k+1}^n) - \bar{\omega}(t_k^n))$$

*defines an injective isometry*

$$I_{\bar{\omega}} : (\mathbb{V}_a(\bar{\omega}), \|\cdot\|_{L^2([0, T], a)}) \rightarrow (\mathcal{H}_a(\bar{\omega}), \|\cdot\|_\pi)$$



## A pathwise 'Doob-Meyer' decomposition

Given  $\bar{\omega} \in Q_\pi([0, T], \mathbb{R}^d) \cap C^{\frac{1}{2}-}([0, T], \mathbb{R}^d)$  with strictly increasing quadratic variation along  $\pi$ :

$$\bar{\omega} \in Q_\pi([0, T], \mathbb{R}^d) \cap C^{1/2-}([0, T], \mathbb{R}^d) \quad \text{with} \quad \frac{d[\bar{\omega}]_\pi}{dt} > 0 \quad dt - a.e. \quad (13)$$

and consider the set of regular transformations of  $\bar{\omega}$ :

$$\mathcal{R}(\bar{\omega}) := \{ F(\cdot, \bar{\omega}) \mid F \in \mathcal{R}(\Lambda_T) \} \subset Q_\pi([0, T], \mathbb{R}).$$

### Proposition (Rough-smooth decomposition of paths)

*Any path  $\omega \in \mathcal{R}(\bar{\omega})$  has a unique decomposition*

$$\omega(t) = \omega(0) + \int_0^t \phi \cdot d^\pi \bar{\omega} + s(t)$$

*where  $\phi \in \mathbb{V}_a(\bar{\omega})$  and  $[s]_\pi = 0$ .*



- ▶ This result may be viewed as a pathwise analogue of the well-known decomposition of a continuous semimartingale as the sum of a local martingale and a process with finite variation.
- ▶ Similar results were obtained using rough path techniques Hairer-Pillai (2013) using a uniform Hölder roughness condition on the path and by Hu & Tindel (2013) for fractional Brownian motion.
- ▶ Our setting is closer to the original semimartingale decomposition: the components are distinguished based on (pathwise) quadratic variation.



As in Cass-Litterer-Hairer-Tindel (2012) and Hairer-Pillai (2013), we obtain a '**Norris Lemma**' for this decomposition under a roughness condition on the reference path  $\bar{\omega}$ :

## Theorem (Stability of rough-smooth decomposition)

Let  $\bar{\omega} \in C^{1/2-}([0, T]) \cap Q_{\pi}^{++}([0, T], \mathbb{R}^d)$  such that  
 $\exists \theta < 1, L_{\theta}(\bar{\omega}) > 0 \forall t \in [0, T], \epsilon \in (0, T/2], \nu \in \mathbb{R}^d,$

$$\exists s \in [0, T], \quad |t - s| \leq \epsilon \text{ and } |\nu \cdot (\bar{\omega}(s) - \bar{\omega}(t))| > L_{\theta}(\bar{\omega})\epsilon^{\theta}.$$

There exists  $p, q > 0$  such that for any  $\omega \in \mathcal{R}(\bar{\omega})$  with rough-smooth decomposition

$$\omega(t) = \omega(0) + \int_0^t \phi_{\omega} \cdot d^{\pi} \bar{\omega} + s_{\omega}(t), \quad \phi \in \mathbb{V}_a(\bar{\omega}), \quad [s]_{\pi} = 0.$$

$$\text{we have} \quad \|\phi_{\omega}\|_{\infty} + \|s_{\omega}\|_{\infty} \leq CM^p \|\omega\|_{\infty}^q.$$

where  $M(\omega) := 1 + L_{\theta}(\bar{\omega})^{-1} + \|\phi'\|_{\nu} + \|R^{\phi}\|_{2\nu} + \|\bar{\omega}\|_{\nu} + \|d[\bar{\omega}]/dt\|_{\infty} + \|s\|_{\nu}.$



$Q_\pi([0, T], \mathbb{R})$  is not a vector space and, given two paths  $(\omega_1, \omega_2) \in Q_\pi([0, T], \mathbb{R})$  the quadratic covariation along  $\pi$  cannot be defined in general.

By contrast, the space

$$\mathcal{R}(\bar{\omega}) := \{ F(\cdot, \bar{\omega}) \mid F \in \mathcal{R}(\Lambda_T) \} \subset Q_\pi([0, T], \mathbb{R}).$$

is a vector space of paths with finite quadratic variation along  $\pi$ . Moreover, for any pair of elements  $(\omega_1, \omega_2) \in \mathcal{U}(\bar{\omega})^2$ , the quadratic covariation along  $\pi$  is well defined; if  $\omega_i = \int_0^\cdot \phi_i \cdot d^\pi \bar{\omega} + s_i$  is the rough-smooth decomposition of  $\omega_i$  the quadratic covariation is given by

$$[\omega_1, \omega_2]_\pi(t) = \int_0^t \langle \phi_1^t \phi_2, d[\bar{\omega}] \rangle.$$

This bilinear form on  $\mathcal{R}(\bar{\omega})$  allows to define a weak pathwise functional derivative (R.C.-Yi Lu, 2017) and extend the formulas above to a larger class of functionals.



## A regularity structure on path space

Let  $X \in C^{1/2-} \cap Q_\pi([0, T], \mathbb{R}^d)$  with  $[X]_\pi$  strictly increasing.

Define  $A = \{-\frac{1}{2}, 0, \frac{1}{2}, 1\}$ ,

$$T_0 = \langle 1 \rangle, T_{1/2-} = \langle X^1, \dots, X^d \rangle, T_{-1/2} = \langle d^\pi X^1, \dots, d^\pi X^d \rangle$$

$$T_{0-} = \langle d[X]^{i,j}, i, j = 1..d \rangle$$

The bijective regular functionals  $G \in \mathcal{R}(\mathcal{W}_T)$  with  $\nabla_\omega F \in GL(d, \mathbb{R})$  then define a group of transformations which acts on

$$\mathcal{R}(X) = \{F(\cdot, X), F \in \mathcal{R}(\mathcal{W}_T)\} \subset Q_\pi([0, T], \mathbb{R}^d)$$

Expansion at  $(t, \omega)$  :

$T_{(t,x)} F(s, \cdot) = F(t, x) + (s-t)DF + \nabla_\omega F(t, x) \cdot (y-x) + 1/2 \langle \nabla_\omega^2 F(t, x) \cdot (y-x) \otimes (y-x) \rangle$  The functional chain rule then allows to transpose a functional expansion  $T_y F$  at any  $y = Y(X) \in \mathcal{R}(X)$  to an expansion  $T_z F = \Gamma_{y,z}(T_y)F$  at  $z = Z(X) \in \mathcal{R}(X)$ .



## A regularity structure on path space

The group of transformations  $G = \{\Gamma_{y,z}\}$  then allows to define a *regularity structure* (Hairer 2014) on the space of regular functionals of an irregular path  $X$ :

### Proposition (C. 2017)

*Let  $X \in C^{1/2-}([0, T]) \cap Q_\pi([0, T], \mathbb{R}^d)$  with  $[X]_\pi$  strictly increasing.  $(T, A_X, \Gamma)$  defines a regularity structure over the space of paths  $\mathcal{R}(X)$ . A realization of this regularity structure is given by the  $L^2$  closure of regular functionals of  $X$  and their  $(1, 2)$ -jets given by the horizontal and (1st, 2nd) vertical derivatives.*

In addition to this regularity structure, we also have an additional structure on  $\mathcal{R}(X)$  given by the quadratic form  $[\cdot]_\pi$ .



## Summary

Non-anticipative functional calculus for paths with finite quadratic variation which gives a

- ▶ Global formulation and calculus for controlled rough paths.
- ▶ Pathwise analog of the Ito isometry: pathwise integral with respect to paths of finite quadratic variation which satisfies a pathwise isometry property
- ▶ Pathwise analog of the semimartingale decomposition for functionals of an irregular path with strictly increasing quadratic variation
- ▶ Regularity structure for functionals defined on typical sample paths of semimartingales.





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