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FOR DYNAMICS OF COMPLEX  
TECHNICAL SYSTEMS  
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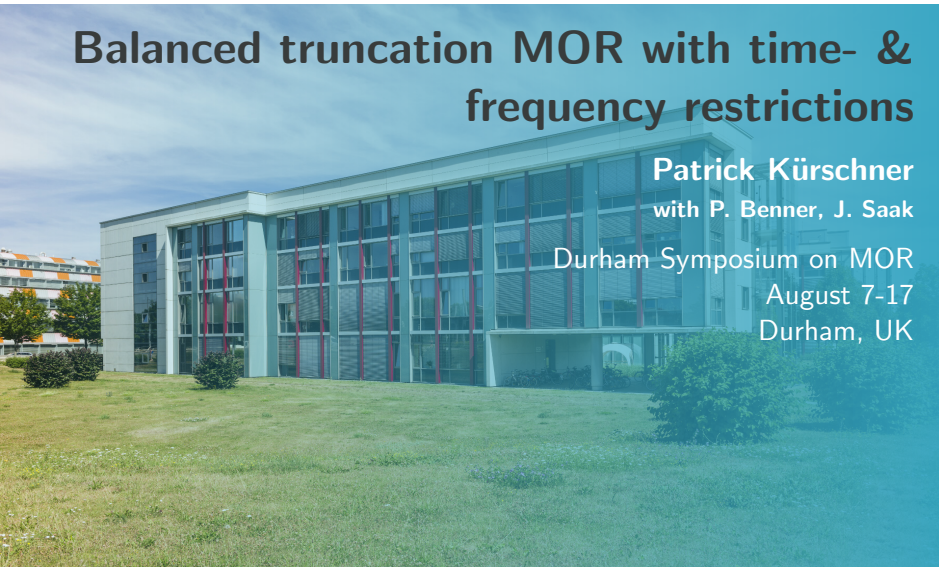


COMPUTATIONAL METHODS IN  
SYSTEMS AND CONTROL THEORY

# Balanced truncation MOR with time- & frequency restrictions

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with P. Benner, J. Saak

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Durham, UK





Linear, time-invariant systems

$$\Sigma: \begin{cases} \dot{x}(t) = Ax(t) + Bu(t), & x(0) = 0, \\ y(t) = Cx(t) \end{cases} \iff \mathbf{G}(s) = C(sI - A)^{-1}B$$

with

- $A \in \mathbb{R}^{n \times n}$ , large, stable ( $\text{Re}(\lambda(A)) < 0$ ),
- $B \in \mathbb{R}^{n \times m}$ ,  $C \in \mathbb{R}^{p \times n}$ ,  $m, p \ll n$ .

**Recall Tatjana Stykel's lectures:**

Balanced truncation (BT) MOR requires (factors of) the *infinite* reachability & observability Gramians  $P_\infty$ ,  $Q_\infty$ , i.e. the solutions of the algebraic Lyapunov equations

$$AP_\infty + P_\infty A^T = -BB^T, \quad A^T Q_\infty + Q_\infty A = -C^T C.$$

Lyapunov equation for reachability Gramian  $AP_\infty + P_\infty A^T = -BB^T$   
 Integral representations w.r.t. time / frequencies:

$$P_\infty = \int_0^\infty e^{At} BB^T e^{A^T t} dt = \frac{1}{2\pi} \int_{-\infty}^\infty (i\omega I - A)^{-1} BB^T (i\omega I - A)^{-H} d\omega$$

**Here:** *time- / frequency-limited* Gramians & BT [GAWRONSKI/JUANG '90]

$$P_{T_f} := \int_0^{T_f} e^{At} BB^T e^{A^T t} dt, \quad T_f < \infty,$$

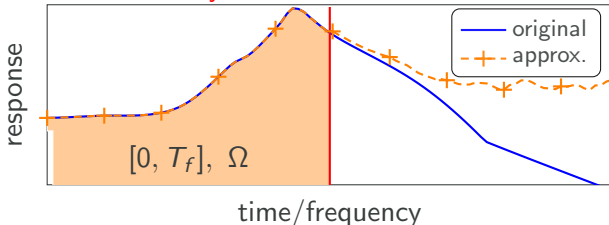
$$P_\Omega := \frac{1}{2\pi} \int_\Omega (i\omega I - A)^{-1} BB^T (i\omega I - A)^{-H} d\omega, \quad \Omega = -\Omega \subset \mathbb{R}$$

completely analogue for observability Gramians



## Why bother with time/frequency-limited BT?

- Compared to normal BT, we want **higher accuracies** ( $\mathbf{G}(i\omega) \approx \mathbf{G}_r(i\omega)$ ,  $y(t) \approx y_r(t)$ ) in **given**  $\Omega$ ,  $[0, T_f]$  with reduced system of the **order  $r$** ,
- or, **comparable accuracies** in  $\Omega$ ,  $[0, T_f]$  with **smaller reduced system**,
- **but allow arbitrary inaccuracies elsewhere:**



- **Also of interest:** extra / reduced computational effort coming from restrictions.



## Lyapunov equations of restricted Gramians

[GAWRONSKI/JUANG '90, PETERSSON/LÖFBERG '14]

Time-limited reachability Gramian for  $[0, T_f]$ ,  $T_f < \infty$ :

$$AP_{T_f} + P_{T_f}A^T = -BB^T + f(A)BB^Tf(A)^T, \quad f(A) = e^{AT_f}.$$

Frequency-limited reachability Gramian

for  $\Omega := [-\omega_2, -\omega_1] \cup [\omega_1, \omega_2]$ ,  $0 \leq \omega_1 < \omega_2 < \infty$ :

$$AP_{\Omega} + P_{\Omega}A^T = -f(A)BB^T - BB^Tf(A)^T,$$
$$f(A) = \operatorname{Re}\left(\frac{i}{\pi} \log\left((A + i\omega_1 I)^{-1}(A + i\omega_2 I)\right)\right).$$

completely analog for observability Gramians  $Q_{\infty} \rightsquigarrow Q_{T_f}, Q_{\Omega}$ .



## Time-limited Balanced Truncation (TLBT)

1. Get  $f(A)B$ ,  $Cf(A)$ ,  $f(A) = e^{AT_f}$ .
2. Compute Cholesky factors of the Gramians  
 $P_{T_f} = Z_{T_f}^T Z_{T_f}$ ,  $Q_{T_f} = Y_{T_f} Y_{T_f}^T$  s.t.  
$$\mathbf{A}P_{T_f} + P_{T_f}\mathbf{A}^T + \mathbf{B}\mathbf{B}^T - f(\mathbf{A})\mathbf{B}\mathbf{B}^T f(\mathbf{A})^T = \mathbf{0},$$
$$\mathbf{A}^T Q_{T_f} + Q_{T_f}\mathbf{A} + \mathbf{C}^T \mathbf{C} - f(\mathbf{A})^T \mathbf{C}^T \mathbf{C} f(\mathbf{A}) = \mathbf{0}.$$
3. SVD:  $Y_{T_f}^T Z_{T_f} = [U_1 \ U_2] \begin{bmatrix} S_1 & \\ & S_2 \end{bmatrix} \begin{bmatrix} R_1^T \\ R_2^T \end{bmatrix}$
4. Define  $W := Y_{T_f} R_1 S_1^{-1/2}$ ,  $V := Z_{T_f} U_1 S_1^{-1/2}$ .
5.  $\Sigma_r$  : ( $A_r := W^T A V$ ,  $B_r := W^T B$ ,  $C_r := C V$ ).

Time-limited Balanced Truncation (TLBT) with low-rank factors

1. Get  $f(A)B$ ,  $Cf(A)$ ,  $f(A) = e^{AT_f}$ .
2. Compute **low-rank** factors of the Gramians  
 $P_{T_f} \approx Z_{T_f} Z_{T_f}^T$ ,  $Q_{T_f} \approx Y_{T_f} Y_{T_f}^T$  s.t.  
$$\mathbf{A}P_{T_f} + P_{T_f}\mathbf{A}^T + \mathbf{B}\mathbf{B}^T - \mathbf{f}(\mathbf{A})\mathbf{B}\mathbf{B}^T\mathbf{f}(\mathbf{A})^T = \mathbf{0},$$
$$\mathbf{A}^T\mathbf{Q}_{T_f} + \mathbf{Q}_{T_f}\mathbf{A} + \mathbf{C}^T\mathbf{C} - \mathbf{f}(\mathbf{A})^T\mathbf{C}^T\mathbf{C}\mathbf{f}(\mathbf{A}) = \mathbf{0}.$$
3. SVD:  $Y_{T_f}^T Z_{T_f} = [U_1 \ U_2] \begin{bmatrix} S_1 & \\ & S_2 \end{bmatrix} \begin{bmatrix} R_1^T \\ R_2^T \end{bmatrix}$
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Numerical methods for computing low-rank factors:

Low-rank ADI, Rational Krylov subspace methods,

[E.G., PENZL '98, LI/WHITE '02, DRUSKIN/SIMONCINI '11]

Frequency-limited Balanced Truncation (FLBT) with low-rank factors

1. Get  $f(A)B$ ,  $Cf(A)$ ,  $f(A) = \operatorname{Re}\left(\frac{i}{\pi} \log\left((A + i\omega_1 I)^{-1}(A + i\omega_2 I)\right)\right)$ .

2. Compute **low-rank** factors of the Gramians

$$P_\Omega \approx Z_\Omega Z_\Omega^T, \quad Q_\Omega \approx Y_\Omega Y_\Omega^T \text{ s.t.}$$

$$\mathbf{A}P_\Omega + P_\Omega\mathbf{A}^T + \mathbf{f}(A)\mathbf{B}\mathbf{B}^T - \mathbf{B}\mathbf{B}^T\mathbf{f}(A)^T = \mathbf{0},$$

$$\mathbf{A}^TQ_\Omega + Q_\Omega\mathbf{A} + \mathbf{f}(A)^TC^TC - C^TC\mathbf{f}(A) = \mathbf{0}.$$

3. SVD:  $Y_\Omega^T Z_\Omega = [U_1 \ U_2] \begin{bmatrix} S_1 & \\ & S_2 \end{bmatrix} \begin{bmatrix} R_1^T \\ R_2^T \end{bmatrix}$

4. Define  $W := Y_\Omega R_1 S_1^{-1/2}$ ,  $V := Z_\Omega U_1 S_1^{-1/2}$ .

5.  $\Sigma_r$  : ( $A_r := W^T A V$ ,  $B_r := W^T B$ ,  $C_r := C V$ ).

Numerical methods for computing low-rank factors:

Low-rank ADI, Rational Krylov subspace methods,

[E.G., PENZL '98, LI/WHITE '02, DRUSKIN/SIMONCINI '11]



Consider reachability Gramians  $P, P_\Omega, P_{T_f}$ .

For low-rank approximation, a rapid decay of the singular values is required.

[E.G., ANTOULAS/SORENSEN/ZHOU '02, GRASEDYCK '04]

Lyapunov equations for infinite, time-/frequency-limited Gramians:

$$AP + PA^T = \begin{cases} -BB^T & \text{(BT)} \\ -BB^T + f(A)BB^T f(A)^T & \text{(TLBT)} \\ -f(A)BB^T - BBf(A)^T & \text{(FLBT)} \end{cases}$$

$\Rightarrow \text{rank}(\text{rhs}_{\text{BT}}) = 2m = 2 \cdot \text{rank}(\text{rhs}_{\text{FLBT, TLBT}}) = m$

**Expectation:** slower singular value decay  $\Rightarrow$  larger low-rank factors required for  $P_{T,\Omega}, Q_{T,\Omega}$  compared  $P_\infty, Q_\infty$ .

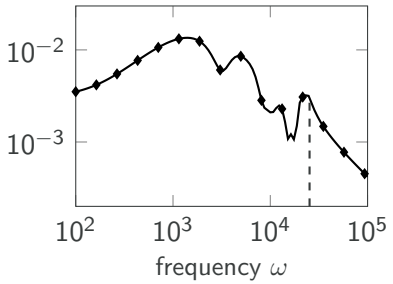
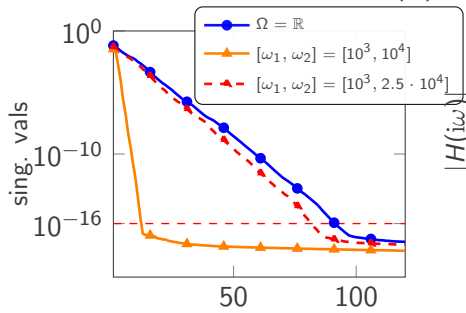
**That's not what happens!**



# Singular Value Decay of $P_\Omega$

$$AP_\Omega + P_\Omega A^T + f(A)BB^T + BB^T f(A)^T = 0,$$

$$f(A) = \text{Re}\left(\frac{i}{\pi} \log\left((A + i\omega_1 I)^{-1}(A + i\omega_2 I)\right)\right)$$



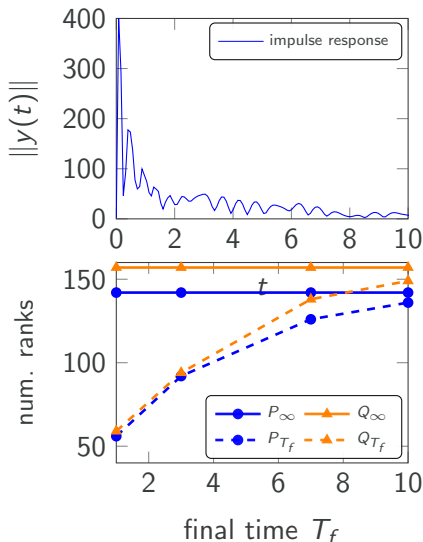
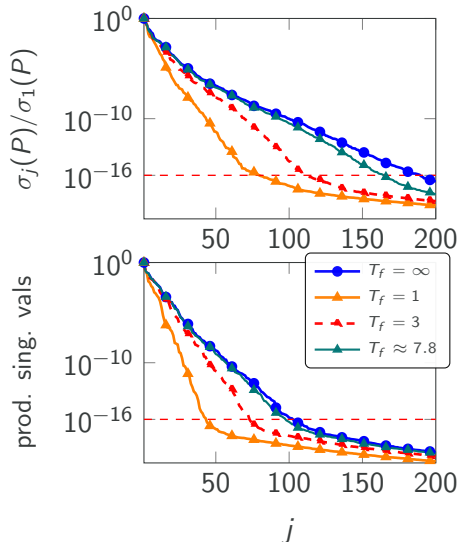
## Singular values of frequency-limited Gramians

[BENNER/K./SAAK '16]

If  $|\omega_2 - \omega_1| < \rho(A)$ , and  $\omega_1, \omega_2 \not\approx |\lambda(A)|$  with large  $\left| \frac{\text{Im}(\lambda(A))}{\text{Re}(\lambda(A))} \right|$ ,  
 then  $\sigma_i(P_\Omega) < \sigma_i(P_\infty)$ .



$$AP_{T_f} + P_{T_f}A^T + BB^T - f(A)BB^Tf(A)^T = 0, f(A) = e^{AT_f}$$



**Observation:** The higher  $T_f$ , the slower the singular value decay of  $P_{T_f}$  (and of  $Q_{T_f}$ ,  $\sqrt{\lambda(P_{T_f}Q_{T_f})}$ )

↪ the smaller the differences to  $P_\infty$ ,  $Q_\infty$ .

Rough explanation:  $P_{T_f} = P_\infty - \Delta(T_f)$ ,  $\Delta(t) := e^{At} P_\infty e^{A^T t} \succeq 0$   
 the difference  $\Delta(t)$  and the impulse-to-state map

$$x_\delta(t) = e^{At} B \mathbf{v} \quad (u(t) = \mathbf{v} \delta(t)).$$

decay at a similar speed

[K.' 17].

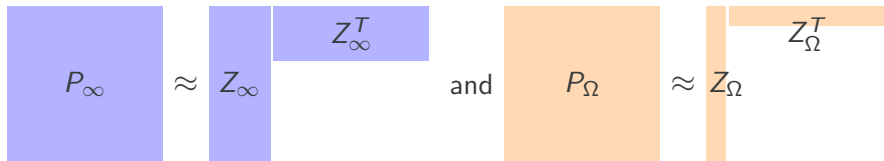
↪ TLBT might be only worthwhile for

- small final times  $T_f$ , s.t.,  $x_\delta(t)$ ,  $y_\delta(t)$  haven't reached stationary phase,
- and/or weakly damped systems.

Under some conditions on  $\Omega$ ,  $T_f$ , the restricted Gramians often exhibit

- faster singular value decay
- $\rightsquigarrow$  smaller numerical rank than the infinite ones

$\Rightarrow \exists$  low-rank approximations



with  $\text{rank}(Z_\infty) = k \geq \ell = \text{rank}(Z_\Omega)$ ,  $(k, \ell \ll n)$

s.t.  $\|P_\infty - Z_\infty Z_\infty^T\| \approx \|P_\Omega - Z_\Omega Z_\Omega^T\|$ .



Before starting with the low-rank Gramian factors, we need  $B_f = f(A)B!$   
 Galerkin projection for  $B_f := f(A) \times B$  onto  $\text{range}(V_k) \subset \mathbb{R}^n$ :

$$B_f \approx V_k f(\underbrace{V_k^T A V_k}_{=: H_k \in \mathbb{R}^{k \times k}}) V_k^T B, \quad V_k \in \mathbb{R}^{n \times k}, \quad V_k^T V_k = I_k, \quad k \ll n.$$

**Here:** use of rational Krylov subspace  $\text{range}(V_k) = \mathcal{RK}_k$ ,

$$\mathcal{RK}_k = \text{span} \left\{ B, (A - \xi_2 I)^{-1} B, \dots, \prod_{i=1}^k (A - \xi_i I)^{-1} B \right\},$$

shifts/poles  $\xi \in \mathbb{C}$  generated adaptively  $\xi_{k+1} = \text{argmax}_{s \in \mathcal{S}_k} |r_k(s)|^{-1}$ ,

- TLBT  $f = e^{zT_f}$ ,  $\mathcal{S}_k = \partial \text{conv}[\Lambda(H_k)]$  or  $[\lambda_{\min}, \lambda_{\max}]$

[DRUSKIN/LIEBERMAN/ZASLAVSKY '10, DRUSKIN/SIMONCINI '11, GÜTTEL '13]

- FLBT  $f = \text{Re} \left( \frac{i}{\pi} \log \frac{z+i\omega_2}{z+i\omega_1} \right)$ ,  $\mathcal{S}_k = i[\omega_1, \omega_2]$  [BENNER/K./SAAK '16]



**Big advantage of using  $\mathcal{RK}$  approximation: we can reuse this subspace for computing the low-rank Gramian approximation!**

## Rational Krylov method for restricted Gramians

[BENNER/K./SAAK '16]

1. Approximation  $\tilde{B}_f \approx B_f := f(A)B$  by (block) rational Krylov method.  
 $H_k = V_k^T (AV_k)$ ,  $V_k^T V_k = I_k$  ( $\text{range}(V_k) = \mathcal{RK}_k(A, B, \xi)$ ).
2. Galerkin for (time-lim.) Lyapunov equation:  
 $H_k \hat{P}_{T_f} + \hat{P}_{T_f} H_k^T - (V_k^T \tilde{B}_f)(\tilde{B}_f^T V_k) + (V_k^T B)(B^T V_k) = 0$ .  
 $\Rightarrow P_{T_f} \approx \tilde{P}_{T_f} := V_k \hat{P}_{T_f} V_k^T$ .
3. Continue (**rarely required**) rational Krylov method until, e.g.,  
 $\|A\tilde{P}_{T_f} + \tilde{P}_{T_f}A^T - \tilde{B}_f\tilde{B}_f^T + BB^T\| < \text{tol}$ .



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$\Rightarrow$  numerical effort of Gramian approximation and, hence, executing time / frequency-limited BT  
(almost entirely) shifted to approximation of  $f(A)B$ !





# BT vs. freq.-limited BT

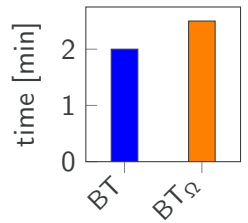
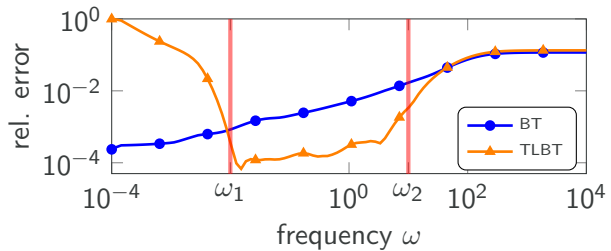
- computation of low-rank factors of Gramians  $P_\infty, Q_\infty, P_\Omega, Q_\Omega$  by rational Krylov subspace method.

[DRUSKIN/SIMONCINI '11, BENNER/K./SAAK '16]

- stopping criterion  $\|\text{Lyap. residual}\| \leq 10^{-8} \|\text{rhs}\|$ .

- accuracy assessment via relative transfer function error  $\frac{\|\mathbf{G}(i\omega) - \mathbf{G}_r(i\omega)\|}{\|\mathbf{G}(i\omega)\|}$

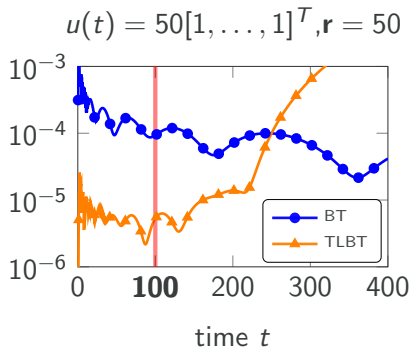
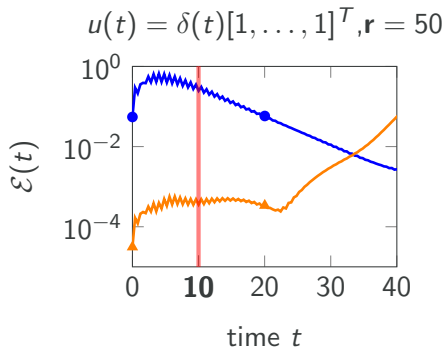
**Example** rail<sup>a</sup>:  $m = 7, p = 6$  reduction from  $n = 79,841$  to order  $r = 50$



<sup>a</sup>Oberwolfach MOR Benchmark collection



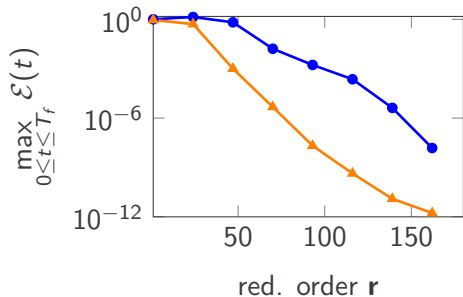
- **Example** rail with  $n = 79,841$ ,
- point wise relative output error  $\mathcal{E}(t) := \frac{\|y(t) - y_r(t)\|}{\|y(t)\|}$ ,
- computing times: BT 65 sec., TLBT 130 sec.



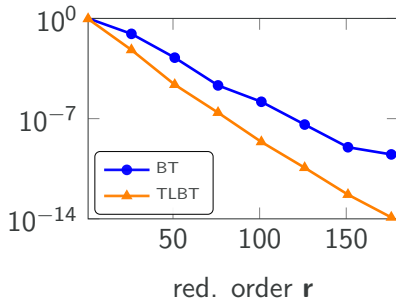


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$$u(t) = \delta(t)[1, \dots, 1]^T$$



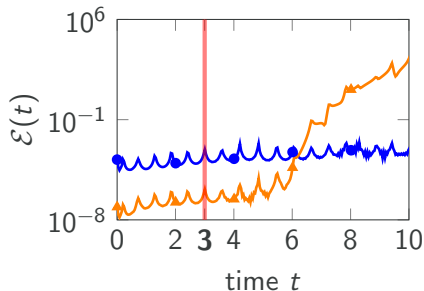
$$u(t) = 50[1, \dots, 1]^T$$



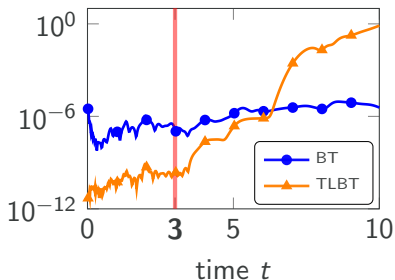


- **Example**  $\text{bips}^a$ , index-1 descriptor system with  $n = 21128$  and  $\hat{n} = 3078$  dynamic states,  $m = p = 4$ ,
- computing times: BT 12.5 sec., TLBT 28.5 sec.

$$u(t) = \delta(t)[1, \dots, 1]^T, r = 30$$



$$u(t) = \sin(t)[1, \dots, 1]^T, r = 100$$

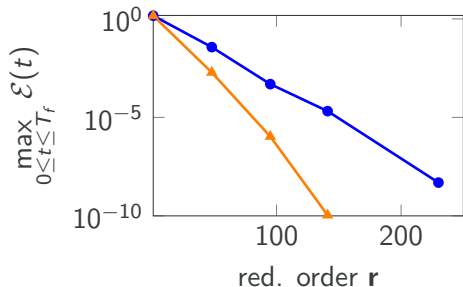


<sup>a</sup>Available from <https://sites.google.com/site/rommes/software>

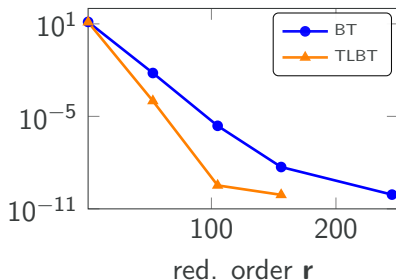


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$$u(t) = \delta(t)[1, \dots, 1]^T$$



$$u(t) = \sin(t)[1, \dots, 1]^T$$



<sup>a</sup>Available from <https://sites.google.com/site/rommes/software>



Originally, [GAWRONSKI/JUANG '90] also proposed TLBT for time-intervals  $\mathcal{T} := [T_s, T_f]$  with  $0 < T_s < T_f < \infty$ .

Gramian: 
$$P_{\mathcal{T}} := \int_{T_s}^{T_f} e^{At} B B^T e^{A^T t} dt$$

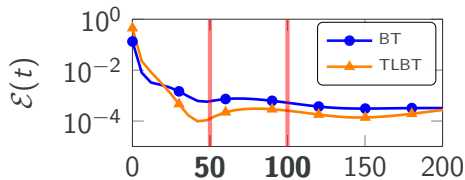
Lyapunov equations:

$$A P_{\mathcal{T}} + P_{\mathcal{T}} A^T + e^{A T_s} B B^T e^{A^T T_s} - e^{A T_f} B B^T e^{A^T T_f} = 0.$$

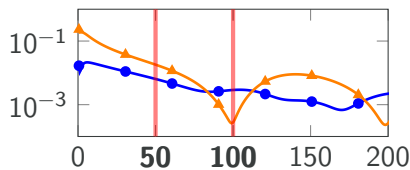
$\rightsquigarrow$  no problem for low-rank factor computation!

However, TLBT in  $[T_s, T_f]$  delivers **only** accurate reduced systems for the impulse input!


$$u(t) = \delta(t)$$



$$u(t) \sim \sin(\pi t/100)^2$$

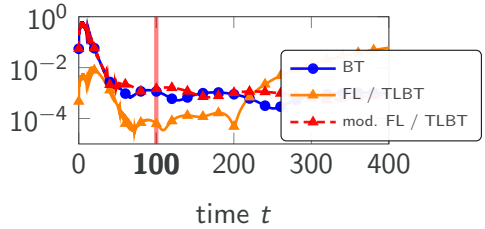
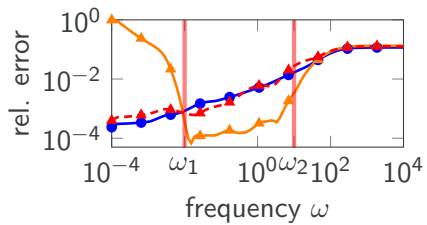




 **Bad news:**  
 | Time- / frequency limited BT are in general not stability preserving!

Modified TLBT / FLBT by [GUGERCIN/ANTOULAS '04] are, but

- sacrifices high accuracy of TLBT, FLBT in the relevant regions,
- numerically more expensive.



⇒ **our recommendation:** if stability preservation is crucial, stick to unrestricted BT!



Time-limited Gramians  $P_{T_f}$ ,  $Q_{T_f}$  still exist for unstable systems, provided  $\Lambda(A) \cap \Lambda(-A) = \emptyset$ .

Moreover, they still solve the time-limited Lyapunov equations. [K '17]

**Idea:**

Use (low-rank factors of) time-limited Gramians as basis for BT of unstable systems. [ANTOULAS '05]

Efficient computation of low-rank factors by the same algorithms.

Might be only practicable for trajectories  $x(t)$ ,  $y(t)$  that do not drastically blow up in  $[0, T_f]$ .



- Faster singular value decay of frequency- / time-limited Gramians.
- Rational Krylov subspace methods enable the approximation of  $f(A)B$  and Gramians in a single algorithm (subspace recycling).
- Frequency- / time-limited BT now applicable for large-scale systems (almost) with the same ease as standard BT.
  - higher accuracy in  $\Omega / [0, T_f]$  compared to standard BT,
  - comparable numerical effort.

## Further research:

- Alternative (better?) methods for  $e^{At}$ ,
- Discrete-time systems. (✓) [GAWRONSKI/JUANG '90, PETERSSON '13]
- Descriptor systems.



Thank you for your attention!

### Some literature



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W. GAWRONSKI AND J. JUANG, *Model reduction in limited time and frequency intervals*, *Int. J. Syst. Sci.* 21(2), pp. 349–376, 1990.



D. PETERSSON, *A Nonlinear Optimization Approach to H2-Optimal Modeling and Control*, PhD thesis, Linköping University, 2013.