

# Geometry III/IV

**Time and place:** Fr 13:00, 15:00 CG60

**Course webpage:** <http://www.maths.dur.ac.uk/users/anna.felikson/Geometry/>

**Instructor:** Anna Felikson  
e-mail: [anna.felikson@durham.ac.uk](mailto:anna.felikson@durham.ac.uk)

Office: CM235; Phone: 334-4158  
Office hours: Mon 12:00-13:00

## Spherical geometry – outline

### 1. Distance and geodesics.

- $d(A, B) = R\angle AOB$  (for a sphere of radius  $R$  centred at  $O$ ).
- Geodesics are great circles.

### 2. Polar correspondence.

- Equator  $\rightarrow$  union of two poles; any pole  $\rightarrow$  corresponding equator.
- If  $A \in l$  then  $Pol(l) \in Pol(A)$  (where  $A$  is a point and  $l$  is a line).
- Polar triangle:  $A'B'C'$  is polar for  $ABC$  if  $A'$  is polar to the line  $\overline{BC}$  containing the side  $BC$  (chosen so that  $\overline{BC}$  does not separate  $A$  from  $A'$ ) and similar properties hold for  $B'$  and  $C'$ .
- Bipolar theorem: if  $A'B'C' = Pol(ABC)$  then  $Pol(A'B'C') = ABC$ .
- Angles and sidelengths of polar triangles:  
 $(\alpha', \beta', \gamma') = (\pi - a, \pi - b, \pi - c)$ ,  $(a', b', c') = (\pi - \alpha, \pi - \beta, \pi - \gamma)$ .

### 3. Spherical triangles.

- Four theorems of congruence of spherical triangles: ASA, SAS, SSS, AAA.
- Area of a spherical triangle:  $S_{ABC} = (\alpha + \beta + \gamma - \pi)R^2$   
where  $R$  is the radius of the sphere.  
In particular,  $\alpha + \beta + \gamma > \pi$ .
- Sine and cosine theorems:
  - sine theorem  $\frac{\sin a}{\sin \alpha} = \frac{\sin b}{\sin \beta} = \frac{\sin c}{\sin \gamma}$
  - cosine thm:  $\cos a = \cos b \cos c + \sin b \sin c \cos \alpha$
  - second cosine thm:  $\cos \alpha = -\cos \beta \cos \gamma + \sin \beta \sin \gamma \cos a$

### 4. Isometries of the sphere:

- Any isometry of the sphere is uniquely determined by images of three points.
- Isometries act transitively on the sphere.
- Isometry group of the sphere is generated by reflections.
- Any isometry is a product of at most three reflections.
- Any orientation preserving isometry is a rotation (a product of two reflections).
- Any orientation reversing isometry is either a reflection or a product of three reflections.