

Feedback 17-18

For all questions:

As usually: please, please support your solutions with **diagrams!!!**.

• Question 17.4:

- Most solutions of the question started with something like “let’s use the classification of isometries” - which is the best strategy here. However, later many students fall into different traps:
 - One should remember there are orientation-preserving isometries **and** orientation-reversing ones;
 - There are two types of “translations” in \mathbb{H}^2 : the **parabolic** and the **hyperbolic** ones!
 - All orientation-preserving isometries in \mathbb{H}^2 have a fixed point in \mathbb{H}^2 **or** on the absolute. But only the elliptic one have fixed points inside \mathbb{H}^2 . (Fixed points on the boundary do not help to conclude f is identity, as distances are only defined for two points lying inside \mathbb{H}^2).

• Question 17.5:

- While computing in the hyperboloid model, remember
 - to use the pseudo-scalar product $(\mathbf{u}, \mathbf{v}) = u_1v_1 + u_2v_2 - u_3v_3$.
 - to square (u, v) in the numerator of $Q = \frac{(\mathbf{u}, \mathbf{v})^2}{(\mathbf{u}, \mathbf{u})(\mathbf{v}, \mathbf{v})}$
 - Also, remember that when computing in the vector model, it is not necessary to have $\langle a, a \rangle = 1$ (as soon as you do not forget about the denominator in Q). So, you can use the vector which is more convenient for computations (i.e. for example $(1, 1, 0)$ rather than something with $\sqrt{2}$).
- Remember, if l_1 and l_2 are two intersecting lines forming an angle θ then the composition of reflections in these lines is a rotation by the angle **2θ** !

• Question 18.2:

- When working with circles, horocycles or equidistant curves, remember:

they are not straight lines!

In particular, congruence of triangles applies to triangles formed of straight lines, the same holds for any statements about sum of angles.