

# Riemannian Geometry

## Hints 3-4

1. (a) Consider the function  $F(A) = A^\top A - I$  and compute its differential using the chain rule.  
More precisely, you may want to use that the differential  $Df(x)$  of a smooth function  $f : \mathbf{R}^m \rightarrow \mathbf{R}^n$  satisfies  $Df(u)(v) = \lim_{t \rightarrow 0} \frac{f(u+tv) - f(u)}{t}$ .
- (b) We need to check that the inverse element  $A^{-1}$  and the product  $AB$  are smooth functions (of elements of  $A$  and elements of  $A$  and  $B$  respectively) for all  $A, B \in SO(n, \mathbf{R})$ .
- (c) (\*) For a curve  $A(T)$  with  $A(0) = I$  compute  $DF(A) |_{t=0}$  (where  $F(A) = A^\top A - I$ ).
2. To get good coordinates on  $M \times N$  use the product atlas (see HW 1).
3. (a) Applying the definition  $[X, Y]f = X(Y(f)) - Y(X(f)) = \dots$  you will get a long expression in partials. Since  $\frac{\partial^2 f}{\partial x_i \partial x_j} = \frac{\partial^2 f}{\partial x_j \partial x_i}$ , second derivatives will cancel and you will be left with  $\varphi(x, y, z) \frac{\partial}{\partial x} + \psi(x, y, z) \frac{\partial}{\partial y} + \eta(x, y, z) \frac{\partial}{\partial z}$ .
- (b) You need to check that the vectors  $X$  and  $Y$  at the point  $p \in S^2$  are orthogonal to the vector pointing to the point  $p$ .
4. (\*) A direct computation...
5. (a) Consider  $S^3$  as a unit sphere inside  $\mathbf{R}^4$ . One example of the required vector field is  $(-y, x, -w, z) \in T_{(x,y,z,w)} \mathbf{R}^4$ .
- (b) Easy to obtain from (a).