

Chapter 7

Overview of the inverse scattering method

7.1 Initial value problems

So far, we have seen methods to construct particular solutions.

Question: can we find a *general* solution to these p.d.e.s?

In more detail: given a wave equation and ‘enough’ initial data at $t = 0$, find $u(x, t)$ at all later times $t > 0$. For there to be a unique solution, sufficient initial data must be given.

- If p.d.e. is 1st order in time, (eg KdV) must specify $u(x, 0)$
- If 2nd order (eg sine-Gordon), need $u(x, 0)$ and $u_t(x, 0)$
- etc.

[why? because we can use the p.d.e. to solve for higher t derivatives. Eg for KdV, if I tell you $u(x, 0)$, you can use the p.d.e. to find out what $u_t(x, 0)$ must be – it’s not independent data.]

But given that information, can we construct $u(x, t)$ for all $t > 0$? (analytically if possible). So far, the answer is no, unless the initial condition happens to be a snapshot of one of the special solutions seen before.

Eg in KdV, what if

(a) $u(x, 0) = 2 \operatorname{sech}^2(x)$

(b) $u(x, 0) = 2.1 \operatorname{sech}^2(x)$

(c) $u(x, 0) = 6 \operatorname{sech}^2(x)$?

Case (a) is a snapshot of a one-soliton solution at $t = 0$, so, assuming the uniqueness of solutions, the answer to (a) at all later times is

$$u(x, t > 0) = 2 \operatorname{sech}^2(x - 4t).$$

But what about (b) and (c)?

It turns out that

(b) \rightarrow { 2 solitons, 1 very small, both moving right, + some junk moving left }

(c) \rightarrow { 2 solitons, both moving right, and that's all }

[so in fact, the initial condition for (c) is a snapshot of a “pure” 2-soliton solution]

Inverse scattering will allow us to understand situations like (b), and give a much more complete understanding of when things like (a) and (c) occur. In fact (as you might remember seeing “experimentally” at the start of last term) whenever the height is $N(N + 1)$, $N = 1, 2, 3, \dots$ we are in a situation like (a) or (c)... but why?

Inverse scattering gives analytic insight into this question.

How might this go?

7.2 Linear initial value problems

For a linear wave equation, the general solution is a linear transformation of the initial data.

Examples

1. The heat equation

$$u_t + u_{xx} = 0, \quad -\infty < x < \infty, t > 0. \quad (7.1)$$

Given $u(x, 0) \equiv u_0(x)$ (the initial data), $u(x, t)$ is

$$u(x, t) = \int_{-\infty}^{+\infty} \frac{1}{\sqrt{4\pi t}} e^{-(x-x')^2/(4t)} u_0(x') dx' \quad (7.2)$$

and this is a linear transform of $u_0(x)$ (it's actually a "Green's function" solution).

2. The Klein-Gordon equation

$$u_{tt} - u_{xx} + u = 0 \quad (7.3)$$

This is second-order in t , so we need to specify $u(x, 0)$ and $u_t(x, 0)$:

$$u(x, 0) = \alpha(x), \quad u_t(x, 0) = \beta(x). \quad (7.4)$$

With luck, { (7.3) + (7.4) } is a "good" initial value problem.

It can be solved using a Fourier transform, which is like the Fourier series seen in AMV, but for functions on a infinite line.

Given $u(x, t)$, set

$$\begin{aligned} \hat{u}(k, t) &= \int_{-\infty}^{+\infty} dx e^{-ikx} u(x, t) \\ u(x, t) &= \frac{1}{2\pi} \int_{-\infty}^{+\infty} dk e^{+ikx} \hat{u}(k, t) \end{aligned} \quad (7.5)$$

where the second equation shows how to get u back from \hat{u} .

Working with $\hat{u}(k, t)$ instead of $u(x, t)$ is a good move, because (7.3) for u implies

$$\hat{u}_{tt} + (k^2 + 1)\hat{u} = 0 \quad (7.6)$$

for \hat{u} , and this equation is easier to solve – there are only t derivatives, so it can be treated as an *ordinary* differential equation rather than a partial one.

Solving (7.6),

$$\hat{u}(k, t) = A(k) e^{i\omega t} + B(k) e^{-i\omega t} \quad (7.7)$$

where $\omega^2 = k^2 + 1$, and A and B can be fixed by matching with the initial condition at $t = 0$:

$$\begin{aligned} \hat{u}(k, 0) &= A(k) + B(k) = \hat{\alpha}(k) \\ \hat{u}_t(k, 0) &= i\omega(A(k) - B(k)) = \hat{\beta}(k). \end{aligned} \quad (7.8)$$

Solving for A and B and simplifying the resulting expression for $\hat{u}(k, t)$,

$$\hat{u}(k, t) = \hat{\alpha}(k) \cos \omega t + \frac{1}{\omega} \hat{\beta}(k) \sin \omega t. \tag{7.9}$$

Finally, a reverse Fourier transform allows $u(x, t)$ to be found:

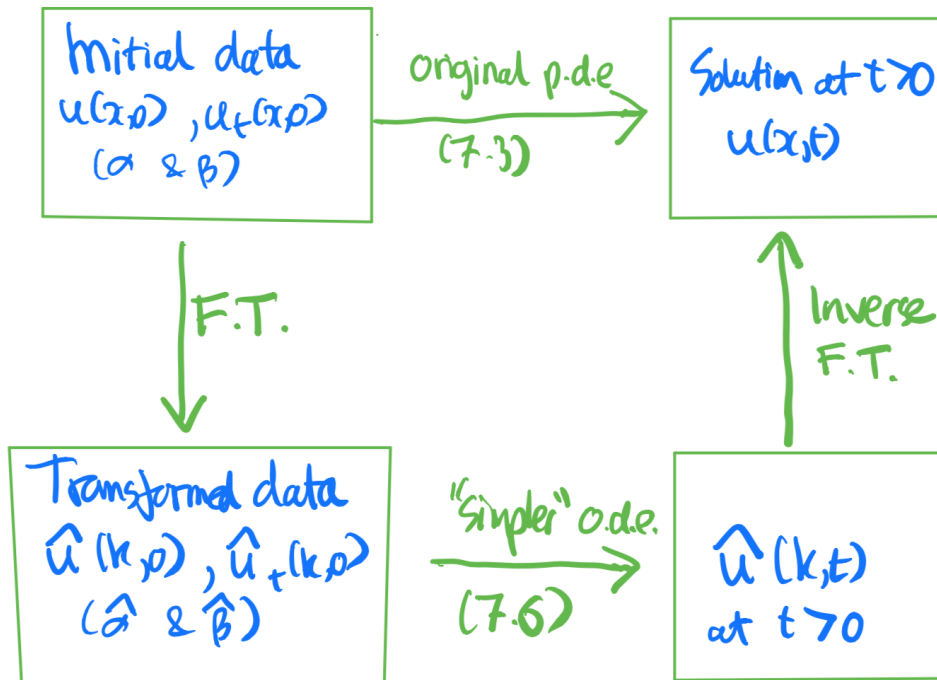
$$\begin{aligned} u(x, t) &= \frac{1}{2\pi} \int_{-\infty}^{+\infty} \hat{u}(k, t) e^{ikx} dk \\ &= \dots \\ &= \frac{1}{2\pi} \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} e^{ik(x-x')} \left(u(x', 0) \cos \omega t + \frac{1}{\omega} u_t(x', 0) \sin \omega t \right) dx' dk \end{aligned} \tag{7.10}$$

with $\omega = \sqrt{k^2 + 1}$.

Again, this is a *linear* function of $u(x, 0)$ and $u_t(x, 0)$, the initial data [this won't be true for KdV].

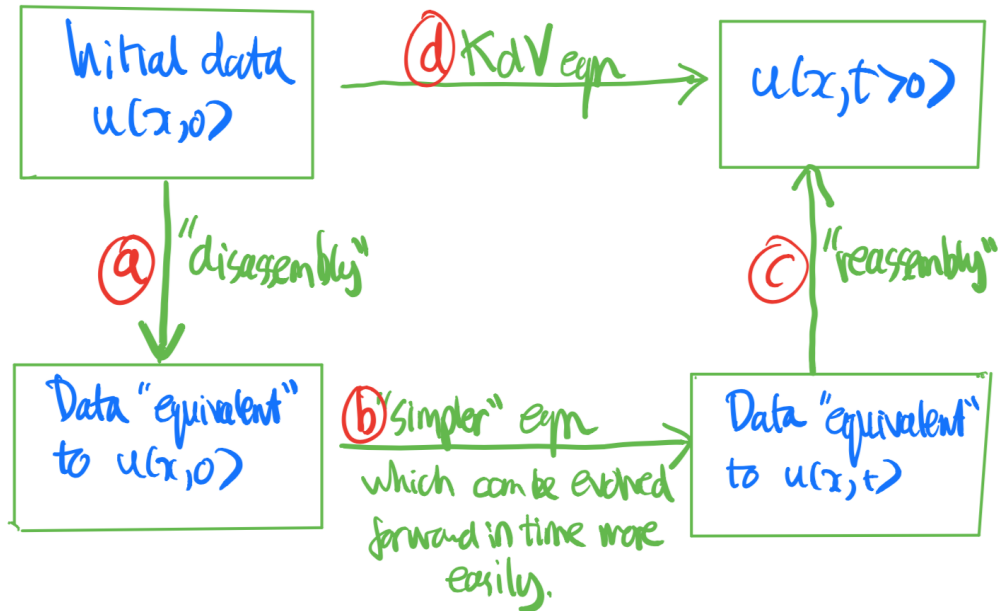
Key feature: the data for each value of k evolved separately, in a simple way, in the “transformed” equation (7.6) [something like this *will* be true for KdV].

Summarising, the general picture for Klein-Gordon is:



This will turn out to be the correct “big idea” for KdV also, but in a much more subtle way since KdV is nonlinear.

Map of the general strategy for KdV:



Instead of doing step (d) directly, we will go the roundabout route of (a) \rightarrow (b) \rightarrow (c).

This will be a long story, so it will be good to keep this “roadmap” in mind as we go, starting with step (a).