

This result motivates the following definition:

**Definition 3.1.8.** A transformation  $\varphi(\epsilon)$  is a *symmetry* if, to first order in  $\epsilon$ , there exists some function  $F(\mathbf{q}, t)$  such that the change in the Lagrangian is a total time derivative of  $F(\mathbf{q}, t)$ :

$$L \rightarrow L' = L(\phi(q_1, \epsilon), \dots, \phi(q_N, \epsilon)) = L + \epsilon \frac{dF(q_1, \dots, q_N, t)}{dt} + \mathcal{O}(\epsilon^2).$$

*Remark 3.1.9.* I emphasize that  $F(\mathbf{q}, t)$  is only defined up to a constant: if some  $F(\mathbf{q}, t)$  exists such that

$$L' = L + \epsilon \frac{dF(\mathbf{q}, t)}{dt} + \mathcal{O}(\epsilon^2)$$

any other  $F'(\mathbf{q}, t) = F(\mathbf{q}, t) + c$  with  $c$  is a constant will also satisfy the same equation. The specific choice of  $c$  is arbitrary, and any choice will lead to correct results. In what follows I will simply pick a convenient representative  $F(\mathbf{q}, t)$  — for instance  $F(\mathbf{q}, t) = 0$  whenever this is possible.

**Example 3.1.10.** Whenever we have an ignorable coordinate  $q_i$ , the symmetry associated to shifting it by constants,  $q_i \rightarrow q_i + c_i$ , is clearly a symmetry, since by definition the coordinate does not appear in the Lagrangian, and  $\dot{q}_i$  stays invariant. So in this case  $F$  can be chosen to be 0.

As an example, consider the example of the rotating spring discussed in example 2.3.3. In polar coordinates  $(r, \theta)$ , we have

$$L = \frac{1}{2}m(\dot{r}^2 + r^2\dot{\theta}^2) - \frac{1}{2}\kappa r^2.$$

In this case the  $\theta$  coordinate is ignorable, so the associated shift  $\theta \rightarrow \theta + \epsilon$  is a symmetry. The generators of the symmetry are

$$a_r = 0 \quad ; \quad a_\theta = 1 \quad ; \quad \dot{a}_r = 0 \quad ; \quad \dot{a}_\theta = 0.$$

**Example 3.1.11.** Let us study the same system as in the previous example, but now in Cartesian coordinates. We have

$$L = \frac{1}{2}m(\dot{x}^2 + \dot{y}^2) - \frac{1}{2}\kappa(x^2 + y^2).$$

The transformation  $\theta \rightarrow \theta + \epsilon$  is a rotation around the origin. Whenever  $\epsilon \ll 1$ , we have

$$\begin{aligned} x &\rightarrow x' = x - \epsilon y + \mathcal{O}(\epsilon^2) \\ y &\rightarrow y' = y + \epsilon x + \mathcal{O}(\epsilon^2). \end{aligned}$$

as we argued in example 3.1.6. And accordingly, for the time derivatives we have

$$\begin{aligned} \dot{x} &\rightarrow \dot{x}' = \dot{x} - \dot{y}\epsilon + \mathcal{O}(\epsilon^2) \\ \dot{y} &\rightarrow \dot{y}' = \dot{y} + \dot{x}\epsilon + \mathcal{O}(\epsilon^2). \end{aligned}$$

Note that this transformations imply that

$$x^2 + y^2 \rightarrow x'^2 + y'^2 = (x + \epsilon y)^2 + (y - \epsilon x)^2 = x^2 + y^2 + \mathcal{O}(\epsilon^2)$$

and similarly that

$$\dot{x}^2 + \dot{y}^2 \rightarrow \dot{x}'^2 + \dot{y}'^2 = \dot{x}^2 + \dot{y}^2 + \mathcal{O}(\epsilon^2)$$

The action of the symmetry on the Lagrangian is then, to first order in  $\epsilon$ :

$$L \rightarrow L' = L(x', y', \dot{x}', \dot{y}') = L + \mathcal{O}(\epsilon^2)$$

so we also see in this coordinate system that the rotation is a symmetry.

Note that this argument generalizes straightforwardly for any Lagrangian of the form

$$L = \frac{1}{2}m(\dot{x}^2 + \dot{y}^2) - V(x^2 + y^2)$$

with  $V(r)$  an analytic function of  $r$ , since in this case

$$V(x^2 + y^2 + \mathcal{O}(\epsilon^2)) = V(x^2 + y^2) + \mathcal{O}(\epsilon^2).$$

**Example 3.1.12.** Consider a system with Lagrangian

$$L = \frac{m}{2}(\dot{x}^2 + \dot{y}^2) - y\dot{x} - \frac{1}{2}x^2,$$

and a transformation generated by

$$\begin{aligned} x &\rightarrow x' = x, \\ y &\rightarrow y' = y + \epsilon. \end{aligned}$$

Then  $\dot{x}' = \dot{x}$  and  $\dot{y}' = \dot{y}$  and

$$\delta L = L(x', y', \dot{x}', \dot{y}') - L(x, y, \dot{x}, \dot{y}) = -y'\dot{x}' + y\dot{x} = -\epsilon\dot{x}.$$

So this is also a symmetry, this time with  $F = -x$ .

### Note 3.1.13

It is important to notice that the definition of *symmetry* above does not involve the equations of motion: the Lagrangian must stay invariant (up to a total derivative) **without** using the equations of motion. That is, the Lagrangian must be invariant also for those paths in configuration space that do not extremize  $S$ .