## Riemannian Geometry IV

Solutions, set 9.

**Exercise 21.** (a) We have with the notation of Exercise 20:  $f(x_1) = \cos x_1$ ,  $g(x_1) = \sin x_1$ , so  $(f'(x_1))^2 + (g'(x_1))^2 = 1$ . This implies that

$$\Gamma_{11}^{1} = \frac{1}{2}g^{11} (g_{11,1} + g_{11,1} - g_{11,1}) = \frac{f'(x_1)f''(x_1) + g'(x_1)g''(x_1)}{(f'(x_1))^2 + (g'(x_1))^2} = 0,$$

$$\Gamma_{11}^{2} = \frac{1}{2}g^{22} (g_{12,1} + g_{12,1} - g_{11,2}) = 0,$$

$$\Gamma_{12}^{1} = \frac{1}{2}g^{11} (g_{11,2} + g_{12,1} - g_{12,1}) = 0 = \Gamma_{21}^{1},$$

$$\Gamma_{12}^{2} = \frac{1}{2}g^{22} (g_{12,2} + g_{22,1} - g_{12,2}) = \frac{f'(x_1)}{f(x_1)} = -\tan x_1 = \Gamma_{21}^{2},$$

$$\Gamma_{22}^{1} = \frac{1}{2}g^{11} (g_{12,2} + g_{12,2} - g_{22,1}) = \frac{-f(x_1)f'(x_1)}{(f'(x_1))^2 + (g'(x_1))^2} = \sin x_1 \cos x_1,$$

$$\Gamma_{22}^{2} = \frac{1}{2}g^{22} (g_{22,2} + g_{22,2} - g_{22,2}) = 0.$$

(b) We are interested in the parallel vector field X along the equator, parametrized by  $c: (-\pi, \pi) \to S^2$ ,  $c(t) = \varphi^{-1}(0, \pi + t)$  with initial condition  $X(0) = \frac{\partial}{\partial x_1}|_{c(0)}$ . This implies that

$$\varphi \circ c_1(t) =: (c_{11}(t), c_{12}(t)) = (0, \pi + t),$$

hence

$$(c'_{11}(t), c'_{12}(t)) = (0, 1).$$

The solution reduces to the ordinary differential equation

$$\begin{pmatrix} a_1' \\ a_2' \end{pmatrix} = - \begin{pmatrix} \Gamma_{12}^1 & \Gamma_{22}^1 \\ \Gamma_{12}^2 & \Gamma_{22}^2 \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix}, \qquad \begin{pmatrix} a_1(0) \\ a_2(0) \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}.$$

Note that for  $x_1 = 0$  we have

$$-\begin{pmatrix} \Gamma_{12}^1 & \Gamma_{22}^1 \\ \Gamma_{12}^2 & \Gamma_{22}^2 \end{pmatrix} = \begin{pmatrix} 0 & -\sin x_1 \cos x_1 \\ \tan x_1 & 0 \end{pmatrix} = 0.$$

So the differential equations are simply  $a_1 \equiv 0 \equiv a_2$  which, together with  $a_1(0) = 1, a_2(0) = 0$  implies that

$$\begin{pmatrix} a_1(t) \\ a_2(t) \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}.$$

So we end up with  $X(t) = \frac{\partial}{\partial x_1}|_{c(t)}$ .

(c) From

$$A^2 = \begin{pmatrix} -ab & 0\\ 0 & -ab \end{pmatrix}$$

we conclude that

$$A^{2k} = (-1)^k \begin{pmatrix} (ab)^k & 0 \\ 0 & (ab)^k \end{pmatrix},$$

$$A^{2k+1} = (-1)^k \begin{pmatrix} 0 & -a(ab)^k \\ b(ab)^k & 0 \end{pmatrix},$$

SO

$$\text{Exp}(tA) = \sum_{k=0}^{\infty} (-1)^k \frac{t^{2k}}{(2k)!} \begin{pmatrix} (\sqrt{ab})^{2k} & 0\\ 0 & (\sqrt{ab})^{2k} \end{pmatrix} \\
 + \sum_{k=0}^{\infty} (-1)^k \frac{t^{2k+1}}{(2k+1)!} \begin{pmatrix} 9 & -\sqrt{\frac{a}{b}}(\sqrt{ab})^{2k+1}\\ \sqrt{\frac{b}{a}}(\sqrt{ab})^{2k+1} & 0 \end{pmatrix} \\
 = \begin{pmatrix} \cos(\sqrt{ab}t) & -\sqrt{\frac{a}{b}}\sin(\sqrt{ab}t)\\ \sqrt{\frac{b}{a}}\sin(\sqrt{ab}t) & \cos(\sqrt{ab}t) \end{pmatrix}.$$

(d) We have  $\varphi \circ c_2(t) = (\pi/4, \pi+t) = (c_{21}(t), c_{22}(t))$  and  $Y(0) = \frac{\partial}{\partial x_1}|_{c_2(0)}$ . This translates into the ordinary differential equation

$$\begin{pmatrix} a_1' \\ a_2' \end{pmatrix} = \begin{pmatrix} 0 & -\frac{1}{2} \\ 1 & 0 \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix}, \qquad \begin{pmatrix} a_1(0) \\ a_2(0) \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}.$$

Using (c), we conclude that

So the parallel vector field Y along  $c_2$  is given by

$$Y(t) = \cos\left(\frac{t}{\sqrt{2}}\right) \frac{\partial}{\partial x_1} \Big|_{c_2(t)} + \sin\left(\frac{t}{\sqrt{2}}\right) \sqrt{2} \frac{\partial}{\partial x_2} \Big|_{c_2(t)}.$$

Note that  $\frac{\partial}{\partial x_1}|_{c_2(t)}$  and  $\sqrt{2}\frac{\partial}{\partial x_2}|_{c_2(t)}$  form an orthonormal basis of  $T_{c_2(t)}S^2$ , so Y(t) is a rotating vector field along the parallel  $c_2$ , similarly to the calculations for the hyperbolic plane (see Example 27).

**Exercise 22.** Assume first that there are global vector fields  $\tilde{X}, \tilde{Y}: M \to TM$  with  $\tilde{X}(c(t)) = X(t)$  and  $\tilde{Y}(c(t)) = Y(t)$  for all  $t \in [a, b]$ . Since the Levi-Civita connection is Riemannian, we conclude that

$$\frac{d}{dt}\Big|_{t}\langle X,Y\rangle = \frac{d}{dt}\Big|_{t}\left(\langle \tilde{X},\tilde{Y}\rangle \circ c\right) = c'(t)\left(\langle \tilde{X},\tilde{Y}\rangle\right) 
= \langle \nabla_{c'(t)}\tilde{X},Y(t)\rangle + \langle X(t),\nabla_{c'(t)}\tilde{Y}\rangle = \langle \frac{D}{dt}X(t),Y(t)\rangle + \langle X(t),\frac{D}{dt}Y(t)\rangle = 0,$$

since the vector fields X, Y are parallel along c. But this implies that  $t \mapsto \langle X(t), Y(t) \rangle$  is a constant function, i.e. the parallel transport  $P_c : T_{c(a)}M \to T_{c(b)}M$  is an isometry, since

$$\langle P_c X(a), P_c Y(a) \rangle = \langle X(b), Y(b) \rangle = \langle X(a), Y(a) \rangle.$$

Now assume that X, Y don't have global extensions. Assume that there is a coordinate chart  $\varphi: (x_1, \ldots, x_n): U \to V$  with  $c([a, b]) \subset U$ . Then we can write

$$X(t) = \sum a_j(t) \frac{\partial}{\partial x_j} \Big|_{c(t)}, \quad Y(t) = \sum b_j(t) \frac{\partial}{\partial x_j} \Big|_{c(t)},$$

and we have

$$\frac{d}{dt}\langle X, Y \rangle = \frac{d}{dt} \left( \sum_{j,k} a_j b_k \left( \langle \frac{\partial}{\partial x_j}, \frac{\partial}{\partial x_k} \rangle \circ c \right) \right).$$

As previously, the Riemannian property of the Levi-Civita connection yields

$$\frac{d}{dt}\left(\langle \frac{\partial}{\partial x_{i}}, \frac{\partial}{\partial x_{k}}\rangle \circ c\right) = \langle \nabla_{c'(t)} \frac{\partial}{\partial x_{i}}, \frac{\partial}{\partial x_{k}}\Big|_{c(t)}\rangle + \langle \frac{\partial}{\partial x_{i}}\Big|_{c(t)}, \nabla_{c'(t)} \frac{\partial}{\partial x_{k}}\rangle.$$

This implies that

$$\frac{d}{dt}\langle X,Y\rangle = \sum_{i,k} (a'_j b_k + a_j b'_k) \langle \frac{\partial}{\partial x_j}, \frac{\partial}{\partial x_k} \rangle \circ c + 
a_j b_k \left( \langle \nabla_{c'(t)} \frac{\partial}{\partial x_j}, \frac{\partial}{\partial x_k} \Big|_{c(t)} \rangle + \langle \frac{\partial}{\partial x_j} \Big|_{c(t)}, \nabla_{c'(t)} \frac{\partial}{\partial x_k} \rangle \right) 
= \langle \sum_j a'_j(t) \frac{\partial}{\partial x_j} \Big|_{c(t)} + a_j(t) \nabla_{c'(t)} \frac{\partial}{\partial x_j}, \sum_k b_k(t) \frac{\partial}{\partial x_k} \Big|_{c(t)} \rangle + 
\langle \sum_j a_j(t) \frac{\partial}{\partial x_j} \Big|_{c(t)}, \sum_k b'_k(t) \frac{\partial}{\partial x_k} \Big|_{c(t)} + b_k(t) \nabla_{c'(t)} \frac{\partial}{\partial x_k} \rangle 
= \langle \sum_j \frac{D}{dt} \left( a_j \frac{\partial}{\partial x_j} \circ c \right), Y \rangle + \langle X, \sum_k \frac{D}{dt} \left( a_k \frac{\partial}{\partial x_k} \circ c \right) 
= \langle \frac{D}{dt} X, Y \rangle + \langle X, \frac{D}{dt} Y \rangle = 0.$$

Finally, if we need k coordinate charts  $U_1, \ldots, U_k$  to cover c([a, b]), i.e., if we have

$$c([a,b]) \subset \bigcup_{j=1}^k U_j$$

with a partition  $a < t_1 < t_2 \cdots < t_{k-1} < b$  such that  $c(a), c(t_1) \in U_1, c(t_1), c(t_2) \in U_2, \ldots c(t_{k-1}), c(b) \in U_k$ , so we conclude with the previous argument that  $\frac{d}{dt}\langle X, Y \rangle$  is constant on the segments  $[a, t_1], [t_1, t_2], \ldots, [t_{k-1}, b]$ , and therefore, constant on all of [a, b].