

## Riemannian Geometry IV, Solution 3 (Week 3)

**3.1.** Let  $M$  be a differentiable manifold,  $U_1, U_2 \subset M$  open and  $\varphi = (x_1, \dots, x_n) : U_1 \rightarrow V_1 \subset \mathbb{R}^n$ ,  $\psi = (y_1, \dots, y_n) : U_2 \rightarrow V_2 \subset \mathbb{R}^n$  are two coordinate charts. Show for  $p \in U_1 \cap U_2$ :

$$\frac{\partial}{\partial x_i} \Big|_p = \sum_{j=1}^n \frac{\partial(y_j \circ \varphi^{-1})}{\partial x_i}(\varphi(p)) \cdot \frac{\partial}{\partial y_j} \Big|_p,$$

where  $y_j \circ \varphi^{-1} : V_1 \rightarrow \mathbb{R}$  and  $\frac{\partial(y_j \circ \varphi^{-1})}{\partial x_i}$  is the classical partial derivative in the coordinate direction  $x_i$  of  $\mathbb{R}^n$ .

**Hint:** Write  $f \circ \varphi^{-1}$  as  $f \circ \psi^{-1} \circ \psi \circ \varphi^{-1}$  and apply the chain rule.

*Solution:*

We need to check that for each function  $f \in C^\infty(M, p)$  the derivation  $\frac{\partial}{\partial x_i} \Big|_p$  acts in the same way as the derivation  $\sum_{j=1}^n \frac{\partial y_j}{\partial x_i} \frac{\partial}{\partial y_j} \Big|_p$ .

We have

$$\frac{\partial}{\partial x_i} \Big|_p (f) = \frac{\partial(f \circ \varphi^{-1})}{\partial x_i}(\varphi(p)) = \frac{\partial}{\partial x_i} (f \circ \psi^{-1} \circ \psi \circ \varphi^{-1})(\varphi(p)).$$

The latter expression above is the partial derivative in coordinate direction  $x_i$  of the composition of the two functions  $\psi \circ \varphi^{-1} : V_1 \subset \mathbb{R}^n \rightarrow V_2 \subset \mathbb{R}^n$  and  $f \circ \psi^{-1} : V_2 \subset \mathbb{R}^n \rightarrow \mathbb{R}$ . The chain rule tells us that

$$\frac{\partial}{\partial x_i} (f \circ \psi^{-1} \circ \psi \circ \varphi^{-1})(\varphi(p)) = \sum_{j=1}^n \frac{\partial(f \circ \psi^{-1})}{\partial y_j}(\psi(p)) \cdot \frac{\partial(y_j \circ \varphi^{-1})}{\partial x_i}(\varphi(p)).$$

Here  $\frac{\partial}{\partial y_j}$  denotes the partial derivative in the  $j$ -th coordinate direction of  $V_2 \subset \mathbb{R}^n$ , and  $y_j$  in the expression  $y_j \circ \varphi^{-1}$  denotes the  $j$ -th component function of the map  $\psi$ . So we finally end up with

$$\frac{\partial}{\partial x_i} \Big|_p (f) = \sum_{j=1}^n \frac{\partial(y_j \circ \varphi^{-1})}{\partial x_i}(\varphi(p)) \cdot \frac{\partial}{\partial y_j} \Big|_p (f).$$

**3.2.** (★) Let  $S^2 = \{x \in \mathbb{R}^3 \mid \|x\| = 1\}$  be the standard two-dimensional sphere, let  $\mathbb{R}P^2$  be the real projective plane and  $\pi : S^2 \rightarrow \mathbb{R}P^2$  be the canonical projection identifying opposite points of the sphere. Let

$$c : (-\varepsilon, \varepsilon) \rightarrow S^2, \quad c(t) = (\cos t \cos(2t), \cos t \sin(2t), \sin t)$$

and

$$f : \mathbb{R}P^2 \rightarrow \mathbb{R}, \quad f(\mathbb{R}(z_1, z_2, z_3)) = \frac{(z_1 + z_2 + z_3)^2}{z_1^2 + z_2^2 + z_3^2}.$$

- (a) Let  $\gamma = \pi \circ c$ . Calculate  $\gamma'(0)(f)$ .
- (b) Let  $(\varphi, U)$  be the following coordinate chart of  $\mathbb{R}P^2$ :  
 $U = \{\mathbb{R}(z_1, z_2, z_3) \mid z_1 \neq 0\} \subset \mathbb{R}P^2$  and

$$\varphi : U \rightarrow \mathbb{R}^2, \quad \varphi(\mathbb{R}(z_1, z_2, z_3)) = \left( \frac{z_2}{z_1}, \frac{z_3}{z_1} \right).$$

Let  $\varphi = (x_1, x_2)$ . Express  $\gamma'(t)$  in the form

$$\alpha_1(t) \frac{\partial}{\partial x_1} \Big|_{\gamma(t)} + \alpha_2(t) \frac{\partial}{\partial x_2} \Big|_{\gamma(t)}.$$

*Solution:*

We have  $\gamma(t) = \mathbb{R} \cdot (\cos t \cos(2t), \cos t \sin(2t), \sin t)$ .

- (a) Since

$$(\cos t \cos(2t))^2 + (\cos t \sin(2t))^2 + (\sin t)^2 = 1,$$

we obtain

$$\gamma'(0)(f) = (f \circ \gamma)'(0) = \frac{d}{dt} \Big|_{t=0} (\cos t \cos(2t) + \cos t \sin(2t) + \sin t)^2 = 2 \cdot 3 = 6.$$

- (b) Let  $(\gamma_1(t), \gamma_2(t)) = \varphi \circ \gamma(t)$ . Then

$$\gamma_1(t) = \tan(2t) \quad \text{and} \quad \gamma_2(t) = \frac{\tan t}{\cos(2t)}.$$

This implies that

$$\begin{aligned} \gamma'(t) &= \gamma'_1(t) \frac{\partial}{\partial x_1} \Big|_{\gamma(t)} + \gamma'_2(t) \frac{\partial}{\partial x_2} \Big|_{\gamma(t)} = \\ &= 2(1 + \tan^2(2t)) \frac{\partial}{\partial x_1} \Big|_{\gamma(t)} + \frac{(1 + \tan^2 t) \cos(2t) + 2 \tan t \sin(2t)}{\cos^2(2t)} \frac{\partial}{\partial x_2} \Big|_{\gamma(t)}. \end{aligned}$$

**3.3.** The 3-sphere  $S^3$  sits inside 2-dimensional complex space as

$$S^3 = \{(w, z) \in \mathbb{C}^2 : |w|^2 + |z|^2 = 1\}$$

- (a) Writing  $w = a + ib$  and  $z = c + id$  we can identify the tangent space to  $\mathbb{C}^2 = \mathbb{R}^4$  at the point  $(1, 0) \in \mathbb{C}^2$  with the span of  $\partial/\partial a, \partial/\partial b, \partial/\partial c$  and  $\partial/\partial d$ .  
 In terms of this basis, what is the subspace tangent to  $S^3$  at  $(1, 0)$ ?
- (b) The map  $\pi : S^3 \rightarrow \mathbb{C}$  given by  $\pi(w, z) = z/w$  is defined away from  $w = 0$ . Identify the kernel of

$$D\pi : T_{(1,0)}S^3 \rightarrow T_0\mathbb{C}.$$

*Solution:*

- (a) If we write  $|w|^2 + |z|^2 = F(w, z) = F(a, b, c, d) = a^2 + b^2 + c^2 + d^2$  then  $S^3 = F^{-1}(1)$ , the preimage of a regular value of  $F$ . Since  $F$  is constant along  $S^3$ , we have  $DF(p)v = 0$  for any  $p \in S^3$  and  $v \in T_p S^3$ .

Now,  $DF(1, 0) = (2a, 2b, 2c, 2d)|_{a=1, b=c=d=0} = (2, 0, 0, 0)$ , and this is zero on a 3-dimensional subspace which must coincide with the 3-dimensional space  $T_{(1,0)} S^3$ :

$$T_{(1,0)} S^3 = \left\langle \frac{\partial}{\partial b}, \frac{\partial}{\partial c}, \frac{\partial}{\partial d} \right\rangle.$$

- (b) Let us write the coordinates on  $\mathbb{C}$  as  $\alpha + i\beta$

For the basis vectors  $\frac{\partial}{\partial b}, \frac{\partial}{\partial c}, \frac{\partial}{\partial d}$  of  $T_{(1,0)} S^3$  we consider some curves  $\gamma_b, \gamma_c$  and  $\gamma_d$  such that the directional derivatives along these curves coincide with  $\frac{\partial}{\partial b}, \frac{\partial}{\partial c}, \frac{\partial}{\partial d}$ . Then we consider the images of these curves under the map  $\pi$  and write the directional derivatives along  $\pi(\gamma_b), \pi(\gamma_c)$  and  $\pi(\gamma_d)$  in the basis  $\langle \frac{\partial}{\partial \alpha}, \frac{\partial}{\partial \beta} \rangle$ .

Consider  $\gamma_d(t) = (1, it)$  be a path through  $(1, 0) \in \mathbb{C}^2$ . Then  $\gamma'_d(0) = \partial/\partial d$ . Now  $D\pi_{(1,0)}(\gamma'_d(0)) = (\pi \circ \gamma_d)'(0)$  and  $(\pi \circ \gamma_d)(t) = \frac{it}{1} = it$  so we see that

$$D\pi_{(1,0)} \left( \frac{\partial}{\partial d} \right) = \frac{\partial}{\partial \beta} \in T_0 \mathbb{C}$$

Similarly we choose  $\gamma_c(t) = (1, t)$  and see that  $(\pi \circ \gamma_c)(t) = \frac{t}{1} = t$ , so

$$D\pi_{(1,0)} \left( \frac{\partial}{\partial c} \right) = \frac{\partial}{\partial \alpha} \in T_0 \mathbb{C}.$$

Finally, take  $\gamma_b(t) = (1 + it, 0)$ , so that  $(\pi \circ \gamma_b)(t) = \frac{0}{1+it} = 0$  and

$$D\pi_{(1,0)} \left( \frac{\partial}{\partial b} \right) = 0 \in T_0 \mathbb{C}$$

Hence we see that the kernel of  $D\pi_{(1,0)}$  is just the 1-dimensional vector space spanned by  $\frac{\partial}{\partial b}$ .

- 3.4.** (★) Show that the tangent space of the Lie group  $SO_n(\mathbb{R}) \subset M_n(\mathbb{R}) \cong \mathbb{R}^{n^2}$  (see Exercise 2.3) at the identity  $I \in SO_n(\mathbb{R})$  is given by

$$T_I SO_n(\mathbb{R}) = \{A \in M_n(\mathbb{R}) \mid A^t = -A\},$$

i.e., the space of all skew-symmetric  $n \times n$ -matrices.

**Hint:** You may use that we have, componentwise,  $(AB)'(s) = A'(s)B(s) + A(s)B'(s)$  for the product of any two matrix-valued curves, and  $(A^t)'(s) = (A'(s))^t$ .

*Solution:*

Let  $A : (-\varepsilon, \varepsilon) \rightarrow SO_n(\mathbb{R})$  be a smooth curve on the smooth manifold  $SO_n(\mathbb{R})$  with  $A(0) = I$ . Then we know that

$$A(s)(A(s))^t = I,$$

for all  $s \in (-\varepsilon, \varepsilon)$ . Differentiation gives

$$A'(0)(A(0))^t + A(0)(A'(0))^t = A'(0)I^t + I(A'(0))^t = A'(0) + (A'(0))^t = 0.$$

So we conclude that

$$T_I SO(n) \subset \{B \in M_n(\mathbb{R}) \mid B + B^t = 0\}.$$

The right hand side is the space of all skew-symmetric  $n \times n$ -matrices, which is a vector space of dimension  $\frac{n(n-1)}{2}$ . Since  $SO_n(\mathbb{R})$  is a differentiable manifold of dimension  $\frac{n(n-1)}{2}$ , its tangent space  $T_I SO_n(\mathbb{R})$  is a vector space of the same dimension. Since both vector spaces have the same dimension, the above inclusion is actually an equality, i.e.,

$$T_I SO_n(\mathbb{R}) = \{B \in M_n(\mathbb{R}) \mid B + B^t = 0\}.$$