

## Riemannian Geometry IV, Solutions 8 (Week 18)

- 8.1.** Recall that a Riemannian manifold is called *homogeneous* if the isometry group of  $M$  acts on  $M$  transitively, i.e. for every  $p, q \in M$  there exists an isometry of  $M$  taking  $p$  to  $q$ . Show that a homogeneous manifold is complete.

*Solution:* According to the theorem of Hopf – Rinow, it suffices to show that  $M$  is geodesically complete. Suppose that some geodesic  $\gamma(t) = \exp_p(tv)$ ,  $\|v\| = 1$  is not defined on  $\mathbb{R}$ , let  $a$  be the supremum of all  $\tau$  such that  $\gamma(\tau)$  is defined. We need to show that it is possible to extend  $\gamma(t)$  to an interval  $(a - \varepsilon, a + \varepsilon)$  for some  $\varepsilon > 0$ .

Take arbitrary point  $q \in M$ . There exists  $\delta > 0$  such that the exponential map on  $B_\delta(0_q)$  is a diffeomorphism. Let  $f$  be an isometry of  $M$  taking  $q$  to  $\gamma(a - \delta/2)$ . Denote  $w = Df^{-1}\gamma'(a - \delta/2)$ . Then the geodesic  $f(\exp_q(wt))$  coincides with  $\gamma(a - \delta/2 + t)$  for  $0 \leq t < \delta/2$ . However, due to the choice of  $\delta$ , the geodesic  $\exp_q(wt)$  is defined for all  $|t| < \delta$ . Therefore, we can define  $\gamma(a - \delta/2 + t) = f(\exp_q(wt))$  for  $\delta/2 \leq t < \delta$ , and thus we extend the geodesic  $\gamma$  past  $t = a$ .

- 8.2.** Let  $(M, g)$  be a Riemannian manifold and  $v_1, \dots, v_n \in T_pM$  be an orthonormal basis. We know from Exercise 10.4 for the geodesic normal coordinates  $\varphi : B_\epsilon(p) \rightarrow B_\epsilon(0) \subset \mathbb{R}^n$ ,

$$\varphi^{-1}(x_1, \dots, x_n) = \exp_p\left(\sum x_i v_i\right)$$

that  $\frac{\partial}{\partial x_i}|_p = v_i$  and  $\nabla_{\frac{\partial}{\partial x_i}} \frac{\partial}{\partial x_j} = 0$ . Define an *orthonormal frame*  $E_1, \dots, E_n : B_\epsilon(p) \rightarrow TM$  by Gram – Schmidt orthonormalization, i.e.,

$$\begin{aligned} F_1(q) &:= \frac{\partial}{\partial x_1}\Big|_q, & E_1(q) &:= \frac{1}{\|F_1(q)\|} F_1(q), \\ &\vdots & & \\ F_k(q) &:= \frac{\partial}{\partial x_k}\Big|_q - \sum_{j=1}^{k-1} \left\langle \frac{\partial}{\partial x_k}\Big|_q, E_j(q) \right\rangle E_j(q), & E_k(q) &:= \frac{1}{\|F_k(q)\|} F_k(q), \\ &\vdots & & \end{aligned}$$

By construction, we have  $E_i(p) = v_i$  and  $E_1(q), \dots, E_n(q)$  are orthonormal in  $T_qM$  for all  $q \in B_\epsilon(p)$ .

- (a) Prove by induction on  $k$  that

$$\begin{aligned} \left(\nabla_{\frac{\partial}{\partial x_i}} F_k\right)(p) &= 0, \\ \nabla_{\frac{\partial}{\partial x_i}} \langle F_k, F_k \rangle^{-1/2}(p) &= 0, \\ \left(\nabla_{\frac{\partial}{\partial x_i}} E_k\right)(p) &= 0, \end{aligned}$$

for all  $i \in \{1, \dots, n\}$ .

(b) Show that

$$(\nabla_{E_i} E_j)(p) = 0$$

for all  $i, j \in \{1, \dots, n\}$ .

*Solution:*

(a) Induction proof for

$$\left( \nabla_{\frac{\partial}{\partial x_i}} F_k \right)(p) = 0, \quad (1)$$

$$\nabla_{\frac{\partial}{\partial x_i}} \langle F_k, F_k \rangle^{-1/2}(p) = 0, \quad (2)$$

$$\left( \nabla_{\frac{\partial}{\partial x_i}} E_k \right)(p) = 0, \quad (3)$$

for all  $i \in \{1, \dots, n\}$ .

One easily checks (1), (2), (3) for  $k = 1$ . Assume all three equations hold for  $k$ . Then we obtain

$$\left( \nabla_{\frac{\partial}{\partial x_i}} F_{k+1} \right)(p) = \left( \nabla_{\frac{\partial}{\partial x_i}} \frac{\partial}{\partial x_{k+1}} \right)(p) - \frac{\partial}{\partial x_i} \Big|_p \sum_{j=1}^k \left\langle \frac{\partial}{\partial x_{k+1}}, E_j \right\rangle E_j.$$

Using at the right hand side the product rule, the Riemannian property of the Levi-Civita connection, and the induction hypothesis  $\nabla_{\frac{\partial}{\partial x_i}} E_j(p) = 0$  for  $1 \leq j \leq k$ , we conclude that the whole expression vanishes. Next, we obtain

$$\nabla_{\frac{\partial}{\partial x_i}} \langle F_{k+1}, F_{k+1} \rangle^{-1/2}(p) = -\frac{1}{\|F_{k+1}(p)\|^3} \langle \nabla_{\frac{\partial}{\partial x_i}} F_{k+1}, F_{k+1} \rangle(p),$$

which implies that also this expression vanishes because of (1). Finally,

$$\left( \nabla_{\frac{\partial}{\partial x_i}} E_{k+1} \right)(p) = \nabla_{\frac{\partial}{\partial x_i}} \langle F_{k+1}, F_{k+1} \rangle^{-1/2}(p) F_{k+1}(p) + \frac{1}{\|F_{k+1}(p)\|} \left( \nabla_{\frac{\partial}{\partial x_i}} F_{k+1} \right)(p),$$

which vanishes again because of (1) and (2). This finishes the induction procedure.

(b) We conclude

$$(\nabla_{E_i} E_j)(p) = \nabla_{E_i(p)} E_j = 0$$

from (3), since  $E_i(p)$  is just a linear combination of the basis vectors  $\frac{\partial}{\partial x_k}$ .

### 8.3. Second Bianchi Identity

Let  $(M, g)$  be a Riemannian manifold and  $R$  be the curvature tensor, defined by

$$R(X, Y, Z, W) = \langle R(X, Y)Z, W \rangle.$$

(a) Let  $E_1, \dots, E_n : B_\epsilon(p) \rightarrow TM$  be the orthonormal frame introduced in Exercise 8.2. For simplicity, let  $e_i = E_i(p)$  and  $E_{ij} = [E_i, E_j]$ . Show that

$$\nabla R(e_i, e_j, e_k, e_l, e_m) = \langle \nabla_{e_m} \nabla_{E_k} \nabla_{E_l} E_i - \nabla_{e_m} \nabla_{E_l} \nabla_{E_k} E_i - \nabla_{e_m} \nabla_{E_{kl}} E_i, e_j \rangle.$$

(b) Using (a) and the Riemannian curvature tensor, derive

$$\begin{aligned} \nabla R(e_i, e_j, e_k, e_l, e_m) + \nabla R(e_i, e_j, e_l, e_m, e_k) + \nabla R(e_i, e_j, e_m, e_k, e_l) \\ = \langle \nabla_{[E_{mk}, E_l] + [E_{kl}, E_m] + [E_{lm}, E_k]} E_i, e_j \rangle \end{aligned}$$

(c) Use Jacobi identity and linearity to prove the *Second Bianchi Identity*:

$$\nabla R(X, Y, Z, W, T) + \nabla R(X, Y, W, T, Z) + \nabla R(X, Y, T, Z, W) = 0,$$

for  $X, Y, Z, W, T$  vector fields on  $M$ .

*Solution:*

(a) Note that  $E_{rs}(p) = \nabla_{e_r} E_s - \nabla_{e_s} E_r = 0$ . Therefore,

$$\begin{aligned} \nabla R(e_i, e_j, e_k, e_l, e_m) &= e_m(\langle R(E_i, E_j)E_k, E_l \rangle) = e_m(\langle R(E_k, E_l)E_i, E_j \rangle) \\ &= \langle \nabla_{e_m} \nabla_{E_k} \nabla_{E_l} E_i - \nabla_{e_m} \nabla_{E_l} \nabla_{E_k} E_i - \nabla_{e_m} \nabla_{E_{kl}} E_i, e_j \rangle. \end{aligned}$$

(b) (a) implies that

$$\begin{aligned} &\nabla R(e_i, e_j, e_k, e_l, e_m) + \nabla R(e_i, e_j, e_l, e_m, e_k) + \nabla R(e_i, e_j, e_m, e_k, e_l) \\ &= \langle \nabla_{e_m} \nabla_{E_k} \nabla_{E_l} E_i + \nabla_{e_k} \nabla_{E_l} \nabla_{E_m} E_i + \nabla_{e_l} \nabla_{E_m} \nabla_{E_k} E_i \\ &\quad - \nabla_{e_m} \nabla_{E_l} \nabla_{E_k} E_i - \nabla_{e_l} \nabla_{E_k} \nabla_{E_m} E_i - \nabla_{e_k} \nabla_{E_m} \nabla_{E_l} E_i \\ &\quad - \nabla_{e_m} \nabla_{E_{kl}} E_i - \nabla_{e_k} \nabla_{E_{lm}} E_i - \nabla_{e_l} \nabla_{E_{mk}} E_i, e_j \rangle \\ &= \langle R(e_m, e_k, \nabla_{e_l} E_i) + \nabla_{E_{mk}(p)} \nabla_{E_l} E_i - \nabla_{e_l} \nabla_{E_{mk}} E_i \\ &\quad + R(e_k, e_l, \nabla_{e_m} E_i) + \nabla_{E_{kl}(p)} \nabla_{E_m} E_i - \nabla_{e_m} \nabla_{E_{kl}} E_i \\ &\quad + R(e_l, e_m, \nabla_{e_k} E_i) + \nabla_{E_{lm}(p)} \nabla_{E_k} E_i - \nabla_{e_k} \nabla_{E_{lm}} E_i, e_j \rangle. \end{aligned}$$

Using  $\nabla_{e_r} E_s = 0$ , all above curvature terms vanish and this result simplifies to

$$\begin{aligned} &\nabla R(e_i, e_j, e_k, e_l, e_m) + \nabla R(e_i, e_j, e_l, e_m, e_k) + \nabla R(e_i, e_j, e_m, e_k, e_l) \\ &= \langle R(E_{mk}(p), e_l, e_i) + \nabla_{[E_{mk}, E_l]} E_i + R(E_{kl}(p), e_m, e_i) + \nabla_{[E_{kl}, E_m]} E_i \\ &\quad + R(E_{lm}(p), e_k, e_i) + \nabla_{[E_{lm}, E_k]} E_i, e_j \rangle. \end{aligned}$$

Using  $E_{rs}(p) = 0$ , this simplifies further to

$$\begin{aligned} &\nabla R(e_i, e_j, e_k, e_l, e_m) + \nabla R(e_i, e_j, e_l, e_m, e_k) + \nabla R(e_i, e_j, e_m, e_k, e_l) \\ &= \langle \nabla_{[E_{mk}, E_l] + [E_{kl}, E_m] + [E_{lm}, E_k]} E_i, e_j \rangle. \end{aligned}$$

(c) Jacobi identity tell us that  $[E_{mk}, E_l] + [E_{kl}, E_m] + [E_{lm}, E_k] = 0$ , and therefore we obtain

$$\nabla R(e_i, e_j, e_k, e_l, e_m) + \nabla R(e_i, e_j, e_l, e_m, e_k) + \nabla R(e_i, e_j, e_m, e_k, e_l) = 0.$$

Since this holds for any choice of basis vectors in every slot, we obtain the same result for any choice of arbitrary tangent vectors in  $T_p M$  in each slot, by linearity.

#### 8.4. Schur Theorem

Let  $(M, g)$  be a connected Riemannian manifold of dimension  $n \geq 3$  with the following property: there is a function  $f : M \rightarrow \mathbb{R}$  such that, for every  $p \in M$ , the sectional curvature of **all** 2-planes  $\Pi \subset T_p M$  satisfies

$$K(\Sigma) = f(p).$$

(a) Define  $R(X, Y, Z, W) = \langle R(X, Y)Z, W \rangle$  and

$$R'(X, Y, Z, W) = \langle X, W \rangle \langle Y, Z \rangle - \langle X, Z \rangle \langle Y, W \rangle.$$

Use Exercises 3.4 and 7.3 to show that  $\nabla R(X, Y, Z, W, U) = (Uf)R'(X, Y, Z, W)$  (for the definition of the covariant derivative of a tensor, see Exercise 9.3).

(b) Use the Second Bianchi Identity (see Exercise 8.3) to show that

$$\begin{aligned} & (Tf)(\langle X, W \rangle \langle Y, Z \rangle - \langle X, Z \rangle \langle Y, W \rangle) \\ & \quad + (Zf)(\langle X, T \rangle \langle Y, W \rangle - \langle X, W \rangle \langle Y, T \rangle) \\ & \quad + (Wf)(\langle X, Z \rangle \langle Y, T \rangle - \langle X, T \rangle \langle Y, Z \rangle) = 0. \end{aligned}$$

(c) Fix a point  $p \in M$  and choose  $X(p), Z(p) \in T_p M$  arbitrary. Because  $n \geq 3$ , we can choose  $W, Y$  such that

$$\langle Z(p), W(p) \rangle_p = \langle Z(p), Y(p) \rangle_p = \langle Y(p), W(p) \rangle_p = 0,$$

and  $\|Y(p)\| = 1$ . Choose  $T = Y$ . Show that this choice yields

$$\langle (Wf)(p)Z(p) - (Zf)(p)W(p), X(p) \rangle(p) = 0,$$

and conclude that we have  $(Zf)(p) = 0$ .

(d) Prove *Schur Theorem*: show that  $f$  is a constant function, i.e., there is a  $C \in \mathbb{R}$  such that  $f(p) = C$  for all  $p \in M$ .

*Solution:*

(a) We know from Exercise 7.3(b) that the tensor  $R'$  is parallel, i.e.,  $\nabla R' = 0$ . We conclude from (the proof of) Exercise 3.4 that  $R = fR'$ , and therefore

$$\nabla R(X, Y, Z, W, U) = (Uf)R'(X, Y, Z, W).$$

(b) The Second Bianchi Identity tells us that

$$\nabla R(X, Y, Z, W, T) + \nabla R(X, Y, W, T, Z) + \nabla R(X, Y, T, Z, W) = 0,$$

which yields, using the definition of  $R'$ :

$$\begin{aligned} 0 &= (Tf)(\langle X, W \rangle \langle Y, Z \rangle - \langle X, Z \rangle \langle Y, W \rangle) \\ & \quad + (Zf)(\langle X, T \rangle \langle Y, W \rangle - \langle X, W \rangle \langle Y, T \rangle) \\ & \quad + (Wf)(\langle X, Z \rangle \langle Y, T \rangle - \langle X, T \rangle \langle Y, Z \rangle). \end{aligned}$$

(c) Using the relations  $\langle Z(p), W(p) \rangle = \langle Z(p), Y(p) \rangle = \langle Y(p), W(p) \rangle = 0$ ,  $\|Y(p)\| = 1$  and  $T = Y$ , we conclude that, at  $p$

$$\begin{aligned} 0 &= (Tf)(p)(\langle X(p), W(p) \rangle \cdot 0 - \langle X(p), Z(p) \rangle \cdot 0) \\ & \quad + (Zf)(p)(\langle X(p), T(p) \rangle \cdot 0 - \langle X(p), W(p) \rangle \cdot 1) \\ & \quad + (Wf)(p)(\langle X(p), Z(p) \rangle \cdot 1 - \langle X(p), T(p) \rangle \cdot 0) \\ & = \langle (Wf)(p)Z(p) - (Zf)(p)W(p), X(p) \rangle. \end{aligned}$$

(d) Since  $Z(p)$  and  $W(p)$  are linearly independent and  $X(p) \in T_p M$  was arbitrary, we conclude that both  $(Wf)(p) = 0$  and  $(Zf)(p) = 0$ . Since  $Z(p)$  was arbitrary,  $f$  must be locally constant. Since  $M$  is connected,  $f$  is globally constant.