# Lecture 13

Example 13.1. Here is another situation with three variables and three equations.

$$\begin{cases} x+y = 3\\ y+z = 1\\ x-z = 2 \end{cases} \longrightarrow \begin{pmatrix} 1 & 1 & 0 & | & 3\\ 0 & 1 & 1 & | & 1\\ 1 & 0 & -1 & | & 2 \end{pmatrix} \xrightarrow{R_3-R_1} \begin{pmatrix} 1 & 1 & 0 & | & 3\\ 0 & 1 & 1 & | & 1\\ 0 & -1 & -1 & | & -1 \end{pmatrix}$$
$$\xrightarrow{R_3+R_2} \begin{pmatrix} 1 & 1 & 0 & | & 3\\ 0 & 1 & 1 & | & 1\\ 0 & 0 & 0 & | & 0 \end{pmatrix} \xrightarrow{R_3+R_2} \begin{pmatrix} 1 & 1 & 0 & | & 3\\ 0 & 1 & 1 & | & 1\\ 0 & 0 & 0 & | & 0 \end{pmatrix}$$
$$\xrightarrow{R_1-R_2} \begin{pmatrix} 1 & 0 & -1 & | & 2\\ 0 & 1 & 1 & | & 1\\ 0 & 0 & 0 & | & 0 \end{pmatrix}.$$

This is equivalent to the system

$$\left\{ \begin{array}{rrrr} x-z&=&2\\ y+z&=&1 \end{array} \right. \Longleftrightarrow \left\{ \begin{array}{rrrr} x&=&2+z\\ y&=&1-z \end{array} \right. .$$

For any  $z \in \mathbb{R}$  (without restriction) we thus have a solution

$$(x, y, z) = (2 + z, 1 - z, z).$$

Hence, there are *infinitely many* solutions to this system.

#### Example 13.2.

$$\begin{cases} 2x + 2y + 3z = 7 \\ x + 2y - z = 0 \end{cases} \longrightarrow \begin{pmatrix} 2 & 2 & 3 & | & 7 \\ 1 & 2 & -1 & | & 0 \end{pmatrix} \xrightarrow{R_1 - 2R_2} \begin{pmatrix} 0 & -2 & 5 & | & 7 \\ 1 & 2 & -1 & | & 0 \end{pmatrix} \\ \xrightarrow{R_1 \leftrightarrow R_2} \begin{pmatrix} 1 & 2 & -1 & | & 0 \\ 0 & -2 & 5 & | & 7 \end{pmatrix} \xrightarrow{R_1 + R_2} \begin{pmatrix} 1 & 0 & 4 & | & 7 \\ 0 & -2 & 5 & | & 7 \end{pmatrix} \\ \xrightarrow{-\frac{1}{2}R_2} \begin{pmatrix} 1 & 0 & 4 & | & 7 \\ 0 & 1 & -5/2 & | & -7/2 \end{pmatrix} \longrightarrow \begin{cases} x + 4z = 7 \\ y - 5z/2 = -7/2 \end{cases} \\ \xleftarrow{K} = 7 - 4z \\ y = -7/2 + 5z/2 \end{cases}$$

So for each  $z \in \mathbb{R}$  we have a solution for x and y. Thus the system has infinitely many solutions.

### **Gauss** elimination

This is the general algorithm to solve a linear system of equations. We have already seen the method in several examples, but we will describe exactly what its goal is, and give more examples.

In order to solve a system  $(A \mid \underline{b})$ , we use ERO to transform this matrix into one where A is as close as possible to an identity matrix. Looking back at some of the previous examples, we got:

• Example (12.5):

$$\left(\begin{array}{rrrr|rrr} 1 & 0 & 0 & 3 \\ 0 & 1 & 0 & -4 \\ 0 & 0 & 1 & 1 \end{array}\right).$$

(unique solution)

• Example (13.1):

(infinitely many solutions)

It is not always possible to achieve an identity matrix, but something close to it is always possible, namely a matrix such that:

- Every row starts with some 0-entries (possibly no 0-entries for the first row) followed by a 1-entry (unless the whole row is zero).
- The number of 0-entries in a row is *more* than in the preceding row (unless both the row and the preceding one consist of 0-entries only).
- The first non-zero entry in each row lies below 0-entries of all previous rows.

**Definition 13.3.** Augmented matrices satisfying the above three conditions are said to be in *Re*duced Row Echelon Form (RREF).

In (13.4), the matrix

$$\left(\begin{array}{rrrrr} 1 & 2 & 0 & 2 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 \end{array}\right)$$

is in RREF. We have no zeros in the beginning of the 1st row, two zeros in the 2nd, and three in the 3rd. Note that the first non-zero entry in the 2nd row lies below a 0-entry of the 1st row.

Here is an example to illustrate RREF:

#### Example 13.4.

$$\begin{pmatrix} 1 & 2 & 1 & | & 1 \\ 2 & 4 & 1 & | & 3 \\ 1 & 2 & 3 & | & -1 \end{pmatrix} \xrightarrow{R_2 - 2R_1} \begin{pmatrix} 1 & 2 & 1 & | & 1 \\ 0 & 0 & -1 & | & 1 \\ 1 & 2 & 3 & | & -1 \end{pmatrix} \xrightarrow{R_3 - R_1} \begin{pmatrix} 1 & 2 & 1 & | & 1 \\ 0 & 0 & -1 & | & 1 \\ 0 & 0 & 2 & | & -2 \end{pmatrix}$$
$$\xrightarrow{-R_2} \begin{pmatrix} 1 & 2 & 1 & | & 1 \\ 0 & 0 & 1 & | & -1 \\ 0 & 0 & 2 & | & -2 \end{pmatrix} \xrightarrow{R_3 - 2R_2} \begin{pmatrix} 1 & 2 & 1 & | & 1 \\ 0 & 0 & 1 & | & -1 \\ 0 & 0 & 0 & | & 0 \end{pmatrix} \xrightarrow{R_1 - R_2} \begin{pmatrix} 1 & 2 & 0 & | & 2 \\ 0 & 0 & 1 & | & -1 \\ 0 & 0 & 0 & | & 0 \end{pmatrix}$$
$$\iff \begin{cases} x = 2 - 2y \\ z = -1. \end{cases}$$

Thus, we have have infinitely many solutions (one for each  $y \in \mathbb{R}$ ).

Here is another example, which shows how to apply the ERO systematically in Gaussian elimination to achieve RREF.

## Example 13.5.

$$\xrightarrow{R_4-2R_3} \begin{pmatrix} 1 & 2 & 1 & 3 \\ 0 & 1 & 1 & 3 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{pmatrix} \xrightarrow{R_1-R_3} \begin{pmatrix} 1 & 2 & 0 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{pmatrix} \xrightarrow{R_1-2R_2} \begin{pmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{pmatrix}.$$

This last matrix is in RREF, and the matrix to the left of the vertical line is an identity matrix with an extra zero-row added. This means that the system has a *unique* solution:

$$x = -1, \quad y = 1, \quad z = 2.$$