

# Lecture 24

## Eigenvalues of special matrices

We now look at eigenvalues of matrices of special types.

**Hermitian matrices.** Let  $A \in \text{Mat}_n$  be Hermitian, so that  $A^\dagger = A$ . Let  $\underline{v}$  be an eigenvector of  $A$ ,  $A\underline{v} = \lambda\underline{v}$ . Let us compute  $\underline{v}^\dagger A\underline{v}$  in two ways. First,

$$\underline{v}^\dagger A\underline{v} = (\underline{v}^\dagger A)\underline{v} = (\underline{v}^\dagger A^\dagger)\underline{v} = (A\underline{v})^\dagger \underline{v} = (\lambda\underline{v})^\dagger \underline{v} = \underline{v}^\dagger \lambda^* \underline{v} = \lambda^* (\underline{v}^\dagger \underline{v}).$$

On the other hand,

$$\underline{v}^\dagger A\underline{v} = \underline{v}^\dagger (A\underline{v}) = \underline{v}^\dagger \lambda \underline{v} = \lambda (\underline{v}^\dagger \underline{v}).$$

Comparing the two expressions and using the fact  $\underline{v}^\dagger \underline{v} \neq 0$ , we see that  $\lambda^* = \lambda$ . Therefore, eigenvalues of Hermitian matrices are always real.

**Example 24.1.** Let  $A = \begin{pmatrix} 1 & i \\ -i & 2 \end{pmatrix}$ . Then the characteristic polynomial is  $\det(A - \lambda I) = (1 - \lambda)(2 - \lambda) - 1 = \lambda^2 - 3\lambda + 1$  which has two real roots  $\lambda = \frac{3 \pm \sqrt{5}}{2}$ .

As real symmetric matrices are Hermitian, we see that they also have real eigenvalues. Further, the computation above applied to an anti-Hermitian matrix would give  $\lambda^* = -\lambda$ , which implies that the eigenvalues are purely imaginary (i.e., their real part is zero). Summarizing, we have

**Corollary 24.2.** • *Eigenvalues of Hermitian matrices are real.*

- *Eigenvalues of real symmetric matrices are real.*
- *Eigenvalues of anti-Hermitian matrices are purely imaginary. In particular, eigenvalues of real anti-symmetric matrices are purely imaginary.*

**Unitary matrices.** Now let  $A \in \text{Mat}_n$  be unitary, so that  $A^\dagger A = I$ . Let  $\underline{v}$  be an eigenvector of  $A$ ,  $A\underline{v} = \lambda\underline{v}$ . Let us compute  $\underline{v}^\dagger \underline{v}$ . We have

$$\underline{v}^\dagger \underline{v} = \underline{v}^\dagger I \underline{v} = \underline{v}^\dagger A^\dagger A \underline{v} = (A\underline{v})^\dagger (A\underline{v}) = (\lambda\underline{v})^\dagger (\lambda\underline{v}) = \underline{v}^\dagger \lambda^* \lambda \underline{v} = (\lambda \lambda^*) (\underline{v}^\dagger \underline{v}) = |\lambda|^2 (\underline{v}^\dagger \underline{v}).$$

Therefore,  $|\lambda|^2 = 1$ , so  $|\lambda| = 1$ .

**Corollary 24.3.** *Eigenvalues of unitary and real orthogonal matrices have modulus 1.*

**Example 24.4.** Let  $A = \begin{pmatrix} \cos \varphi & -\sin \varphi \\ \sin \varphi & \cos \varphi \end{pmatrix}$ . Then  $\lambda = \pm e^{i\varphi}$ , so  $|\lambda| = 1$ .

## Diagonalization

A matrix  $A \in \text{Mat}_n(\mathbb{C})$  is said to be *diagonalizable* if we can choose a basis for  $\mathbb{C}^n$  consisting of eigenvectors of  $L_A$ .

The term *diagonalization* means the following. Given a basis  $\{\underline{v}_1, \dots, \underline{v}_n\}$  for  $\mathbb{C}^n$ , we can create a *matrix*  $B = (b_{ij})$  of  $L_A$  *with respect to this basis*: we can write for every  $j = 1, \dots, n$

$$L_A(\underline{v}_j) = b_{1j}\underline{v}_1 + b_{2j}\underline{v}_2 + \dots + b_{nj}\underline{v}_n = \sum_{i=1}^n b_{ij}\underline{v}_i.$$

If the basis consists of eigenvectors of  $L_A$ , then  $L_A \underline{v}_j = \lambda_j \underline{v}_j$ , so the matrix  $B$  is *diagonal*.

**Example 24.5.** We have already seen in (22.4) that  $A = \begin{pmatrix} 3 & 1 \\ -2 & 0 \end{pmatrix}$  has eigenvectors

$$\underline{v}_1 = \begin{pmatrix} 1 \\ -2 \end{pmatrix}, \quad \underline{v}_2 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

with eigenvalues  $\lambda_1 = 1$  and  $\lambda_2 = 2$  respectively. Therefore,

$$L_A \underline{v}_1 = 1 \cdot \underline{v}_1 + 0 \cdot \underline{v}_2, \quad L_A \underline{v}_2 = 0 \cdot \underline{v}_1 + 2 \cdot \underline{v}_2,$$

and thus  $L_A$  is given by the diagonal matrix  $\begin{pmatrix} 1 & 0 \\ 0 & 2 \end{pmatrix}$  in the basis  $\{\underline{v}_1, \underline{v}_2\}$ .