Lecture 26

We have seen that we can easily diagonalize a matrix having n distinct eigenvalues. Even if the eigenvalues are not distinct, a matrix may still be diagonalizable:

Example 26.1. Let $A = \begin{pmatrix} 1 & 0 & 0 \\ 1 & -1 & -1 \\ 1 & -2 & 0 \end{pmatrix}$. Its eigenvalues are given by the roots of the polynomial

$$(1 - \lambda)((-1 - \lambda)(-\lambda) - 2) = (1 - \lambda)(\lambda^2 + \lambda - 2) = (1 - \lambda)^2(\lambda + 2),$$

that is, eigenvalues: 1, -2.

We now find the eigenspaces. For $\lambda = 1$:

$$\begin{pmatrix} 0 & 0 & 0 \\ 1 & -2 & -1 \\ 1 & -2 & -1 \end{pmatrix} \underline{x} = 0 \iff x - 2y - z = 0.$$

Thus, the eigenspace has two free parameters:

$$E_1 = \left\{ \begin{pmatrix} 2y+z \\ y \\ z \end{pmatrix} \mid y, z \in \mathbb{C} \right\}.$$

Thus E_1 is a two-dimensional space, so we can find two linearly independent vectors in it, for example

$$\begin{pmatrix} 2\\1\\0 \end{pmatrix} \text{ and } \begin{pmatrix} 1\\0\\1 \end{pmatrix}$$

Then

$$E_{1} = \left\{ y \begin{pmatrix} 2\\1\\0 \end{pmatrix} + z \begin{pmatrix} 1\\0\\1 \end{pmatrix} \mid y, z \in \mathbb{C} \right\} = \operatorname{span} \left\{ \begin{pmatrix} 2\\1\\0 \end{pmatrix}, \begin{pmatrix} 1\\0\\1 \end{pmatrix} \right\}.$$

Moreover, for $\lambda = -2$, we get

$$\begin{pmatrix} 3 & 0 & 0\\ 1 & 1 & -1\\ 1 & -2 & 2 \end{pmatrix} \underline{x} = 0 \iff \begin{pmatrix} 0 & 6 & -6\\ 0 & 3 & -3\\ 1 & -2 & 2 \end{pmatrix} \underline{x} = 0$$
$$\iff \begin{pmatrix} 1 & 0 & 0\\ 0 & 1 & -1\\ 0 & 0 & 0 \end{pmatrix} \underline{x} = 0 \iff \begin{cases} x & = 0\\ y - z & = 0. \end{cases} \iff \underline{x} = \begin{pmatrix} 0\\ y\\ y \end{pmatrix}, \ y \in \mathbb{C}.$$
Thus $E_{-2} = \left\{ \begin{pmatrix} 0\\ y\\ y \end{pmatrix} \mid y \in \mathbb{C} \right\} = \operatorname{span} \left\{ \begin{pmatrix} 0\\ 1\\ 1 \end{pmatrix} \right\}.$ Since $\begin{pmatrix} 0\\ 1\\ 1 \end{pmatrix}$ is an eigenvector for an eigenvalue which is distinct from that for the eigenvectors $\begin{pmatrix} 0\\ 1\\ 1 \end{pmatrix}$

Since $\begin{pmatrix} 0\\1\\1 \end{pmatrix}$ is an eigenvector for an eigenvalue which is distinct from that for the eigenvectors $\begin{pmatrix} 2\\1\\0 \end{pmatrix}$

and $\begin{pmatrix} 1\\0\\1 \end{pmatrix}$, we see that

$$\begin{pmatrix} 2\\1\\0 \end{pmatrix}, \begin{pmatrix} 1\\0\\1 \end{pmatrix}, \begin{pmatrix} 0\\1\\1 \end{pmatrix}$$

are linearly independent. Thus, they form a basis for \mathbb{C}^3 and hence A is diagonalizable. In fact, if we form the matrix

$$P = \begin{pmatrix} 2 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{pmatrix},$$

then Proposition 25.3 tells us that

$$P^{-1}AP = \begin{pmatrix} 1 & 0 & 0\\ 0 & 1 & 0\\ 0 & 0 & -2 \end{pmatrix}.$$

Summarizing, we just need to choose a basis in each eigenspace, and then collect all of these together to compose a basis of the whole space \mathbb{C}^n . This can be done in the only case when we have "enough" linearly independent eigenvectors in every eigenspace, i.e. if the sum of all of the dimensions dim E_{λ_i} is equal to n. In fact, the following (non-trivial) statement always holds.

Fact. Let det $(A - \lambda I) = \prod_{i=1}^{k} (\lambda_i - \lambda)^{l_i}$, where the sum of all l_i is equal to n (recall that numbers l_i are called *multiplicities* of roots λ_i). Then for every $i = 1, \ldots, k$ one has dim $E_{\lambda_i} \leq l_i$.

Therefore, the example above can be generalized in the following way:

Theorem 26.2. Let $A \in Mat_n(\mathbb{C})$, let $\lambda_1, \ldots, \lambda_k$ be the eigenvalues of A, and let the characteristic polynomial of A be $det(A - \lambda I) = \prod_{i=1}^k (\lambda_i - \lambda)^{l_i}$, where the sum of all l_i is equal to n. Then A is diagonalizable if and only if for every $i = 1, \ldots, k$ the dimension of the eigenspace E_{λ_i} is equal to l_i .

Note that, by definition, $E_{\lambda_i} = \ker(A - \lambda_i I)$, and thus dim $E_{\lambda_i} = n - \operatorname{rk}(A - \lambda_i I)$. Thus, Theorem 26.2 can be reformulated in the following easy-to-use way:

Corollary 26.3. A matrix $A \in Mat_n(\mathbb{C})$ with eigenvalues $\lambda_1, \ldots, \lambda_k$ and characteristic polynomial $det(A - \lambda I) = \prod_{i=1}^k (\lambda_i - \lambda)^{l_i}$ is diagonalizable if and only if for every $i = 1, \ldots, k$ we have $n - rk(A - \lambda_i I) = l_i$.

Corollary 26.3 leads to the following algorithm.

Criterion of diagonalizability of a matrix. Let $A \in Mat_n(\mathbb{C})$. To decide whether A is diagonalizable, we need to do the following.

- **Step 1**. Compute the characteristic polynomial $\det(A \lambda I) = (\lambda_1 \lambda)^{l_1} (\lambda_2 \lambda)^{l_2} \dots (\lambda_k \lambda)^{l_k}$.
- **Step 2**. For every i = 1, ..., k compute the number $n rk(A \lambda_i I)$.
- **Step 3.** If for every i = 1, ..., k we have $n rk(A \lambda_i I) = l_i$, then A is diagonalizable. Otherwise, it is not.

Remark. In Steps 2 and 3, we need to consider only eigenvalues λ_i with $l_i > 1$. Indeed, since we know that $1 \leq n - \operatorname{rk}(A - \lambda_i I) \leq l_i$, the equality $l_i = 1$ guarantees that $n - \operatorname{rk}(A - \lambda_i I) = 1 = l_i$ (in particular, we immediately get Corollary 25.4).