

## Geometry III/IV, Term 2 (Section 8)

### 8 Isometries of $\mathbb{H}^2$

#### 8.1 Reflections

**Definition.** A *reflection*  $r_l$  with respect to a hyperbolic line  $l$  is an isometry preserving the line  $l$  pointwise and swapping the half-planes.

**Example.** • In the Poincaré disc and upper half-plane models: reflections are represented by Euclidean reflections and inversions.

• In the Klein disc model: given  $A$  and  $l$ , one can construct  $r_l(A)$ .

**Theorem 8.1.** In hyperboloid model: given  $\mathbf{a} \in \mathbb{R}^{2,1}$  s.t.  $(\mathbf{a}, \mathbf{a}) > 0$  (i.e.  $(\mathbf{x}, \mathbf{a}) = 0$  defines a line  $l_{\mathbf{a}}$ ), the map  $r_{\mathbf{a}} : \mathbf{x} \mapsto \mathbf{x} - 2\frac{(\mathbf{x}, \mathbf{a})}{(\mathbf{a}, \mathbf{a})}\mathbf{a}$  is the reflection with respect to the line  $l_{\mathbf{a}}$ .

#### 8.2 Classification

**Theorem 8.2.** Any isometry of  $\mathbb{H}^2$  is a composition of at most 3 reflections.

**Corollary 8.3.** A non-trivial orientation-preserving isometry of  $\mathbb{H}^2$  has either 1 fixed point in  $\mathbb{H}^2$ , or 1 fixed point on the absolute, or two fixed points on the absolute.

**Definition 8.4.** A non-trivial orientation-preserving isometry of  $\mathbb{H}^2$  is called *elliptic* if it has one fixed point in  $\mathbb{H}^2$ , *parabolic* if it has one fixed point in  $\partial\mathbb{H}^2$ , and *hyperbolic* if it has two fixed points in  $\partial\mathbb{H}^2$ .

**Exercise.** Any orientation-reversing isometry is a glide reflection, i.e. a composition of a hyperbolic isometry (preserving some line  $l$ ) and a reflection in  $l$ .

**Example 8.5.** In the upper half-plane model, an isometry  $z \mapsto \frac{az+b}{cz+d}$  with  $a, b, c, d \in \mathbb{R}$ ,  $ad - bc = 1$  is elliptic if  $|d + a| < 2$ , parabolic if  $|d + a| = 2$  and hyperbolic if  $|d + a| > 2$ .

**Remark 8.6** (Invariant sets of isometries). Sets preserved by a given isometry for elliptic, parabolic and hyperbolic isometries are *circles*, *horocycles* and *equidistant curves* respectively.

#### 8.3 Horocycles and Equidistant curves.

Recall the definition of a circle: a *circle* is a set of points that are on the same distance from a given point (centre).

**Properties.** 1. All lines through the centre are orthogonal to the circle.

2. The distance between two concentric circles  $\gamma$  and  $\gamma'$  is constant (i.e. given a point  $A \in \gamma$  and a closest to  $A$  point  $A' \in \gamma'$ , the distance  $d(A, A')$  does not depend on the choice of  $A$ ).

**Definition 8.7.** A *horocycle*  $h$  is a limit of circles: let  $P \in \mathbb{H}^2$  be a point, and  $l$  be a ray from  $P$ ; for  $t > 0$  let  $O_t \in l$  be a point s.t.  $d(P, O_t) = t$ ;

let  $C(t)$  be a circle centred at  $O_t$  of radius  $t$ ; then a horocycle  $h = \lim_{t \rightarrow \infty} C(t)$ .

The point  $X = \lim_{t \rightarrow \infty} O(t) \in \partial\mathbb{H}^2$  is called the *centre* of the horocycle  $h$ .

**Remark.** In the Poincaré disc, every circle tangent to the absolute represents some horocycle.

**Properties.** 1. All lines through the centre of the horocycle are orthogonal to the horocycle.

2. The distance between two concentric horocycles  $h$  and  $h'$  is constant (i.e. given a point  $A \in h$  and a closest to  $A$  point  $A' \in h'$ , the distance  $d(A, A')$  does not depend on the choice of  $A$ ).

**Remark.** In projective models, an equation of a circle with centre  $\mathbf{u}$  (where  $(\mathbf{u}, \mathbf{u}) < 0$ ) can be written as  $(\mathbf{x}, \mathbf{u})^2 = c(\mathbf{x}, \mathbf{x})$  for some constant  $c$ . Similarly, an equation of a horocycle with centre  $\mathbf{u}_0$  (where  $(\mathbf{u}_0, \mathbf{u}_0) = 0$ ) can be written as  $(\mathbf{x}, \mathbf{u}_0)^2 = c(\mathbf{x}, \mathbf{x})$  for some constant  $c$ .

**Definition 8.8.** An *equidistant curve*  $e$  to a line  $l$  is a locus of points that are on a given distance from  $l$ .

**Examples.** In UHP, if  $l$  is a vertical ray  $0\infty$ , then  $e$  is a union of two (Euclidean) rays from  $0$  making the same angle with  $l$ . If  $l$  is a half of a Euclidean circle, then  $e$  is a union of two arcs of circles making the same angle with  $l$  (same in the Poincaré disc).

**Properties.** 1. All lines orthogonal to  $l$  are orthogonal to any equidistant curve of  $l$ .

2. The distance between two equidistant curves to the same line is constant.

**Remark.** 1. For elliptic, parabolic and hyperbolic isometry  $f$  of  $\mathbb{H}^2$ , through each point of  $\mathbb{H}^2$  there is a unique invariant curve of  $f$  (circle, horocycle or equidistant curve respectively) and a unique line orthogonal to all invariant curves.

2. Representation of elliptic, parabolic and hyperbolic isometries as  $r_2 \circ r_1$  is not unique:  $r_1$  can be a reflection with respect to any line from the orthogonal family, by if  $r_1$  is fixed then  $r_2$  is unique.