## Riemannian Geometry IV, Homework 4 (Week 14)

Due date for starred problems: Friday, February 14.

## 4.1. Scalar curvature

The scalar curvature s(p) at point  $p \in M$  is defined by

$$s(p) = \sum_{j=1}^{n} Ric_p(u_j),$$

where  $\{u_j\}$  is an orthonormal basis of  $T_p(M)$ .

- (a) Let V be a vector space,  $\langle \cdot, \cdot \rangle$  is an inner product on V, and Q is a quadratic form on V. Show that there exists a linear map  $T \in \text{End}(V)$  such that  $Q(x) = \langle Tx, x \rangle$  for every  $x \in V$ .
- (b) Show that the scalar curvature is well-defined, i.e. it does not depend on the choice of an orthonormal basis of  $T_p(M)$ .

## **4.2.** $(\star)$ Einstein manifolds

A Riemannian manifold (M, g) is called an *Einstein manifold* if there exists  $c \in \mathbb{R}$  such that

$$Ric_p(v,w) = c\langle v,w \rangle$$

for every  $p \in M$ ,  $v, w \in T_p M$ .

(a) Show that (M, g) is an Einstein manifold if and only if there exists  $c \in \mathbb{R}$  such that

$$Ric_p(v) = c$$

for every  $p \in M$  and unit tangent vector  $v \in T_p M$ .

- (b) Show that if (M, g) is of constant sectional curvature then (M, g) is an Einstein manifold.
- **4.3.** Let (M, g) be a Riemannian manifold. The goal of this exercise is to show that M is of constant sectional curvature  $K_0$  if and only if

$$\langle R(v_1, v_2)v_3, v_4 \rangle = -K_0(\langle v_1, v_3 \rangle \langle v_2, v_4 \rangle - \langle v_1, v_4 \rangle \langle v_2, v_3 \rangle)$$

for any  $p \in M$  and  $v_1, v_2, v_3, v_4 \in T_p M$ . Denote the expression  $-K_0(\langle v_1, v_3 \rangle \langle v_2, v_4 \rangle - \langle v_2, v_3 \rangle \langle v_1, v_4 \rangle)$  by  $(v_1, v_2, v_3, v_4)$ .

(a) Show that if

$$\langle R(v_1, v_2)v_3, v_4 \rangle = (v_1, v_2, v_3, v_4)$$

for any four tangent vectors  $v_1, v_2, v_3, v_4 \in T_p M$ , then M is of constant sectional curvature  $K_0$ .

Now assume that M is of constant sectional curvature  $K_0$ . Our aim is to show that

$$\langle R(v_1, v_2)v_3, v_4 \rangle = (v_1, v_2, v_3, v_4)$$

for any four tangent vectors  $v_1, v_2, v_3, v_4 \in T_p M$ .

(b) Show that the expression  $(v_1, v_2, v_3, v_4)$  is a tensor, i.e. it is multilinear.

- (c) Show that  $(v_1, v_2, v_3, v_4)$  has the same symmetries as Riemann curvature tensor has. Namely,
  - $\cdot (v_1, v_2, v_3, v_4) = -(v_2, v_1, v_3, v_4)$
  - $\cdot (v_1, v_2, v_3, v_4) = -(v_1, v_2, v_4, v_3)$
  - $\cdot (v_1, v_2, v_3, v_4) = (v_3, v_4, v_1, v_2)$
  - $\cdot (v_1, v_2, v_3, v_4) + (v_2, v_3, v_1, v_4) + (v_3, v_1, v_2, v_4) = 0$
- (d) Show that if  $\{v_1, v_2, v_3, v_4\} \subset \{v, w\}$ , i.e. no more than two distinct vectors are involved, then

$$\langle R(v_1, v_2)v_3, v_4 \rangle = (v_1, v_2, v_3, v_4)$$

(e) Show that if no more than three distinct vectors are involved, then

$$\langle R(v_1, v_2)v_3, v_4 \rangle = (v_1, v_2, v_3, v_4).$$

(f) Show that for any four vectors  $\{v_1, v_2, v_3, v_4\}$ 

$$\langle R(v_1, v_2)v_3, v_4 \rangle - (v_1, v_2, v_3, v_4) = \langle R(v_3, v_1)v_2, v_4 \rangle - (v_3, v_1, v_2, v_4),$$

i.e. the difference above is invariant with respect to cyclic permutation of first three arguments.

(g) Use Bianchi identity to prove the initial statement.

## 4.4. Constant sectional curvature of hyperbolic 3-space

Let  $\mathbb{H}^3 = \{(x_1, x_2, x_3) \in \mathbb{R}^3 \mid x_3 > 0\}$  be the upper half-space model of the 3-dimensional hyperbolic space, i.e. its metric is defined by  $g_{ij} = 0$  for  $i \neq j$ ,  $g_{ii} = 1/x_3^2$ .

- (a) Show that sectional curvatures  $K(\frac{\partial}{\partial x_1}, \frac{\partial}{\partial x_2})$ ,  $K(\frac{\partial}{\partial x_1}, \frac{\partial}{\partial x_3})$  and  $K(\frac{\partial}{\partial x_2}, \frac{\partial}{\partial x_3})$  in  $\mathbb{H}^3$  are equal to -1.
- (b) Use (a) and the linearity of the Riemann curvature tensor to show that for any  $p \in \mathbb{H}^3$  and  $v_1, v_2, v_3, v_4 \in T_p \mathbb{H}^3$

$$\langle R(v_1, v_2)v_3, v_4 \rangle = -(\langle v_1, v_3 \rangle \langle v_2, v_4 \rangle - \langle v_1, v_4 \rangle \langle v_2, v_3 \rangle)$$

holds.

- (c) Use (b) to show that 3-dimensional hyperbolic space  $\mathbb{H}^3$  has constant sectional curvature -1.
- (d) Show that *n*-dimensional hyperbolic space  $\mathbb{H}^n = \{x \in \mathbb{R}^n \mid x_n > 0\}$  with metric  $g_{ij} = 0$  for  $i \neq j$ ,  $g_{ii} = 1/x_n^2$  has constant sectional curvature -1.