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Riemannian Geometry IV, Solutions 6 (Week 16)

6.1. (*) Choose any r > 0 and consider a cylinder $C \subset \mathbb{R}^3$ with induced metric,

$$C = \{(x, y, z) \in \mathbb{R}^3 \,|\, x^2 + y^2 = r^2\}$$

C can be parametrized by

$$(r\cos\varphi, r\sin\varphi, z), \quad \varphi \in [0, 2\pi), z \in \mathbb{R}$$

- (a) Show that a curve $c(t) = (r \cos(t/r), r \sin(t/r), 0)$ is a geodesic. Write c(t) in the form $(\varphi(t), z(t))$.
- (b) Let $\alpha \in \mathbb{R}$. Show that $c_{\alpha}(t) = (\varphi(t), z(t)) = ((t \cos \alpha)/r, t \sin \alpha)$ is a geodesic.
- (c) Construct two distinct geodesic variations $F_1(s,t)$ and $F_2(s,t)$ of c(t), such that $F_1(s,0) \equiv c(0)$, and $F_2(s,0) \neq c(0)$ for any $s \neq 0$. Compute the variational vector fields of F_1 and F_2 .
- (d) Construct the basis of the space J_c of Jacobi fields along c(t).
- (e) Show that for any $t_0 \in \mathbb{R}$ the points c(0) and $c(t_0)$ are not conjugate along c(t).

Solution:

(a) One way to do this is to use symmetry of C. More precisely, the reflection in the plane z = 0 is obviously an isometry of C, and it preserves c(t). By the uniqueness theorem of a geodesic in a given direction, the trace of c(t) should be a trace of a geodesic. Now observe that ||c'(t)|| = 1, so c(t) is a geodesic.

Another way is to observe that C is locally isometric to \mathbb{R}^2 , and the isometry takes c(t) to a straight line on \mathbb{R}^2 (parametrized proportionally to arc length).

Finally, one can compute the induced metric and Christoffel symbols (they are all zeros!), and then verify that c(t) satisfies the ODE for geodesics. These ODE's are then equivalent to the second derivatives of the components of c(t) vanishing identically, which is clearly satisfied as the geodesic c(t) is written as c(t) = (t/r, 0) in coordinates (φ, z).

- (b) The second and the third methods from (a) work perfectly fine in this case as well.
- (c) We can take

$$F_1(s,t) = \left(r\cos\left(\frac{t\cos s}{r}\right), r\sin\left(\frac{t\cos s}{r}\right), t\sin s\right) = c_s(t)$$

Clearly, $F_1(0,t) = c(t)$, $F_1(s,0) \equiv (r,0,0) = c(0)$, and every $t \mapsto F_1(s_0,t)$ is a geodesic by (b). The variational vector field is $X_1(t) = (0,0,t)$.

Shifting c(t) in vertical direction, we can take

$$F_2(s,t) = (r\cos(t/r), r\sin(t/r), s)$$

The corresponding variational vector field is $X_2(t) = (0, 0, 1)$.

- (d) We need 2n = 4 linearly independent vector fields. We have already found two, and observe that X_1 and X_2 are both orthogonal and clearly linear independent, so they form a basis of the space of orthogonal Jacobi fields. We can also take $X_3(t) = c'(t)$ and $X_4 = tc'(t)$, all of them together form a basis.
- (e) Assume that $J(0) = J(t_0) = 0$ for some $J \in J_c$. Since J(0) = 0, J should be a linear combination of X_1 and X_4 . However, such a non-zero linear combination never vanishes except for t = 0.
- **6.2.** (*) Let $c : [0,1] \to M$ be a geodesic, and let J be a Jacobi field along c. Denote c(0) = p, c'(0) = v. Define a curve $\gamma(s)$,

$$\gamma: (-\varepsilon, \varepsilon) \to M, \qquad \gamma(0) = p, \gamma'(0) = J(0)$$

Define also a vector field $V(s) \in \mathfrak{X}_{\gamma}(M)$ such that

$$V(0) = v, \qquad \frac{D}{ds}V(0) = \frac{D}{dt}J(0),$$

and a variation $F(s,t) = \exp_{\gamma(s)} tV(s)$.

- (a) Show that F(s,t) is a geodesic variation of c(t).
- (b) Show that $\frac{\partial F}{\partial s}(0,0) = \gamma'(0) = J(0)$, and $\frac{D}{dt}\frac{\partial F}{\partial s}(0,0) = \frac{D}{ds}V(0) = \frac{D}{dt}J(0)$.
- (c) Deduce from (a) and (b) that every Jacobi field along a geodesic c(t) is a variational vector field of some geodesic variation of c.

Solution:

- (a) By the definition of the exponential map, for given s the curve $t \mapsto \exp_{\gamma(s)} tV(s)$ is a geodesic.
- (b) We have

$$\frac{\partial F}{\partial s}(0,0) = \frac{\partial}{\partial s}\Big|_{s=0} \exp_{\gamma(s)} tV(s)\Big|_{t=0} = \frac{\partial}{\partial s}\Big|_{s=0} \exp_{\gamma(s)}(0) = \frac{\partial}{\partial s}\Big|_{s=0} \gamma(s) = \gamma'(0) = J(0)$$

and

$$\frac{D}{dt}\frac{\partial F}{\partial s}(0,0) = \frac{D}{ds}\Big|_{s=0}\frac{\partial F}{\partial t}\Big|_{t=0}(s,t) = \frac{D}{ds}\Big|_{s=0}V(s) = \frac{D}{ds}V(0) = \frac{D}{dt}J(0)$$

(c) According to (a), the variation F is geodesic, thus its variational vector field $\frac{\partial F}{\partial s}(0,t)$ is Jacobi. By (b), $\frac{\partial F}{\partial s}(0,0) = J(0)$, and $\frac{D}{dt}\frac{\partial F}{\partial s}(0,0) = \frac{D}{dt}J(0)$, which means that $\frac{\partial F}{\partial s}(0,t) = J(t)$ due to the uniqueness theorem.

6.3. Jacobi fields and conjugate points on locally symmetric spaces

A Riemannian manifold (M, g) is called a *locally symmetric space* if $\nabla R = 0$ (see Exercise 9.3). Let (M, g) be an *n*-dimensional locally symmetric space and $c : [0, \infty) \to M$ be a geodesic with p = c(0) and $v = c'(0) \in T_p M$. Prove the following facts:

- (a) Let X, Y, Z be parallel vector fields along c. Show that R(X, Y)Z is also parallel.
- (b) Let $K_v \in \text{Hom}(T_pM, T_pM)$ be the curvature operator defined by

$$K_v(w) = R(w, v)v.$$

Show that K_v is self-adjoint, i.e.,

$$\langle K_v(w_1), w_2 \rangle = \langle w_1, K_v(w_2) \rangle$$

for every pair of vectors $w_1, w_2 \in T_p M$.

(c) Choose an orthonormal basis $w_1, \ldots, w_n \in T_p M$ that diagonalizes K_v , i.e.,

$$K_v(w_i) = \lambda_i w_i$$

(such a basis exists since K_v is self-adjoint). Let W_1, \ldots, W_n be the parallel vector fields along c with $W_i(0) = w_i$ (i.e., $\{W_i\}$ form a parallel orthonormal basis along c). Show that for all $t \in [0, \infty)$

$$K_{c'(t)}(W_i(t)) = \lambda_i W_i(t).$$

(d) Let $J(t) = \sum_i J_i(t) W_i(t)$ be a Jacobi field along c. Show that Jacobi equation translates into

$$J_i''(t) + \lambda_i J_i(t) = 0$$
, for $i = 1, ..., n$.

(e) Show that the conjugate points of p along c are given by $c(\pi k/\sqrt{\lambda_i})$, where k is any positive integer and λ_i is a positive eigenvalue of K_v .

Solution:

(a) We know that $\nabla R = 0$. Let $\frac{D}{dt}$ denote covariant derivative along c. Then we have, for parallel vector fields X, Y, Z along c that

$$0 = \nabla R(X, Y, Z, c')(t) = \frac{D}{dt} R(X(t), Y(t))Z(t) - R(X(t), \underbrace{\frac{D}{dt}Y(t)}_{=0})Z(t) - R(X(t), Y(t)) \underbrace{\frac{D}{dt}Z(t)}_{=0} = \underbrace{\frac{D}{dt}R(X(t), Y(t))Z(t)}_{=0}.$$

This shows that R(X, Y)Z is parallel.

(b) The symmetries of R yield

$$\langle K_v(w_1), w_2 \rangle = \langle R(w_1, v)v, w_2 \rangle = \langle R(w_2, v)v, w_1 \rangle = \langle K_v(w_2), w_1 \rangle = \langle w_1, K_v(w_2) \rangle.$$

(c) Since K_v is self-adjoint, we can find an orthonormal basis $w_1, \ldots, w_n \in T_p M$ with $K_v(w_i) = \lambda_i w_i$. We know, by (a), that $K_{c'(t)}(W_i(t)) = R(c'(t), W_i(t))W_i(t)$ is parallel and, since $K_{c'(0)}(W_i(0)) = K_v(w_i) = \lambda_i w_i$, we must have

$$K_{c'(t)}(W_i(t)) = \lambda_i W_i(t),$$

since parallel vector fields V along c are uniquely determined by their initial values $V(0) \in T_p M$. (d) Let J be a Jacobi field along c. Then J satisfies the Jacobi equation

$$\frac{D^2}{dt^2}J + R(J,c')c' = 0.$$

Since W_1, \ldots, W_n form a parallel basis along c, we obtain, by taking inner product with W_i :

$$0 = \langle \frac{D^2}{dt^2} J, W_i \rangle + \langle R(J, c')c', W_i \rangle =$$

$$= \frac{d^2}{dt^2} \sum_j J_j \langle W_j, W_i \rangle + \sum_j J_j \langle R(W_j, c')c', W_i \rangle =$$

$$= J_i'' + \sum_j J_j \lambda_j \langle W_j, W_i \rangle = J_i'' + \lambda_i J_i.$$

(e) The unique solution of $J''_i(t) + \lambda_i J_i(t) = 0$, $J_i(0) = 0$ (up to scalar multiples) is given by

$$J_i(t) = \begin{cases} \sin(t\sqrt{\lambda_i}) & \text{if } \lambda_i > 0, \\ t & \text{if } \lambda_i = 0, \\ \sinh(t\sqrt{-\lambda_i}) & \text{if } \lambda_i < 0. \end{cases}$$

So J_i has zeros for positive t only if $\lambda_i > 0$, and these are precisely at $t = \pi k / \sqrt{\lambda_i}$. The corresponding Jacobi fields with J(0) = 0 and $\frac{D}{dt}J(0) = w_i$ produce the conjugate points $c(\pi k / \sqrt{\lambda_i})$.