

## Riemannian Geometry IV, Solutions 7 (Week 17)

- 7.1.** (a) Let  $c(t)$  be a geodesic, and let  $c(t_0)$  be conjugate to  $c(t_1)$ . Let  $J$  be any Jacobi field along  $c$  vanishing at  $t_0$  and  $t_1$ . Show that  $J$  is orthogonal, i.e.  $\langle J(t), c'(t) \rangle \equiv 0$ .
- (b) Show that the dimension of the space  $J_c^\perp$  of orthogonal vector fields along  $c$  is  $2n - 2$ .

*Solution:*

- (a) We have proved in class that the function  $t \mapsto \langle J(t), c'(t) \rangle$  is linear. Since it is equal to zero at two points  $t_0$  and  $t_1$ , it vanishes everywhere, so  $J(t)$  is orthogonal.
- (b) Recall that  $J(t)$  is orthogonal if and only if both  $\langle J(0), c'(0) \rangle$  and  $\langle \frac{D}{dt} J(0), c'(0) \rangle$  vanish. Each of these equations defines a codimension one subspace in  $T_p M$ , so the dimension of  $J_c^\perp = (n - 1) + (n - 1) = 2n - 2$ .

- 7.2.** (★) Let  $M$  be a Riemannian manifold of non-positive sectional curvature, i.e.  $K(\Pi) \leq 0$  for any 2-plane  $\Pi \subset TM$ .

- (a) Let  $c : [a, b] \rightarrow M$  be a geodesic and let  $J$  be a Jacobi field along  $c$ . Let  $f(t) = \|J(t)\|^2$ . Show that  $f''(t) \geq 0$ , i.e.,  $f$  is a convex function.
- (b) Derive from (a) that  $M$  does not admit conjugate points.

*Solution:*

- (a) We have

$$f'(t) = \frac{d}{dt} \Big|_{t=0} \langle J(t), J(t) \rangle = 2 \left\langle \frac{D}{dt} J(t), J(t) \right\rangle$$

and

$$f''(t) = 2 \left( \left\langle \frac{D^2}{dt^2} J(t), J(t) \right\rangle + \left\| \frac{D}{dt} J(t) \right\|^2 \right).$$

Using Jacobi equation, we conclude

$$f''(t) = 2 \left( -\langle R(J(t), c'(t))c'(t), J(t) \rangle + \left\| \frac{D}{dt} J(t) \right\|^2 \right).$$

We have  $\langle R(J(t), c'(t))c'(t), J(t) \rangle = 0$  if  $J(t), c'(t)$  are linear dependent and, otherwise, for  $\Pi = \text{span}(J(t), c'(t)) \subset T_{c(t)}M$ ,

$$\langle R(J(t), c'(t))c'(t), J(t) \rangle = K(\Pi) (\|J(t)\|^2 \|c'(t)\|^2 - (\langle J(t), c'(t) \rangle)^2) \leq 0,$$

since sectional curvature is non-positive (we also used Cauchy – Schwarz inequality here). This shows that  $f''(t)$ , as a sum of two non-negative terms, is greater than or equal to zero.

- (b) If there were a conjugate point  $q = c(t_2)$  to a point  $p = c(t_1)$  along the geodesic  $c$ , then we would have a non-vanishing Jacobi field  $J$  along  $c$  with  $J(t_1) = 0$  and  $J(t_2) = 0$ . This would imply that the convex, non-negative function  $f(t) = \|J(t)\|^2$  would have zeros at  $t = t_1$  and  $t = t_2$ . This would force  $f$  to vanish identically on the interval  $[t_1, t_2]$ , which would imply that  $J$  vanishes as well, which leads to a contradiction.

**7.3.** (★) Let  $M = \{(x, y, z) \in \mathbb{R}^3 \mid x^2 + y^2 = z\}$  be a paraboloid of revolution with metric induced by  $\mathbb{R}^3$ . Let  $p = (0, 0, 0)$ . Show that  $p$  has no conjugate points in  $M$ .

*Solution:*

Let  $q = (q_1, q_2, q_3) \neq p$  be any point in  $M$ . Denote by  $\Pi \subset \mathbb{R}^3$  the 2-dimensional plane spanned by  $q$  and the  $z$ -axis. It is easy to check that there is a geodesic  $c(t) \subset M \cap \Pi$  with  $c(0) = p$ ,  $c(t_1) = q$ .

Take a parallel of  $M$  passing through  $q$ . Applying the same argument to all other points on the parallel, we see that every “vertical” plane through  $p$  in  $\mathbb{R}^3$  contains a geodesic of  $M$ , and only one of them (namely,  $c$ ) passes through  $q$ . As these geodesics exhaust all the directions from  $p$ , we conclude that  $c$  is the only geodesic between  $p$  and  $q$ , and thus it is minimal. By Theorem 9.24 this implies that for any  $t_0 \in (0, t_1)$  the point  $c(t_0)$  is not conjugate to  $p$ .

Rotating the whole picture around the  $z$ -axis (this is clearly an isometry of  $M$ ) we see that  $p$  has no conjugate points in a ball  $z < q_3$  (where  $q = (q_1, q_2, q_3)$ ), so taking  $q$  far enough from  $p$  we can prove that  $p$  has no conjugate points in a ball of any size centered at  $p$ .

**7.4.** Let  $(M, g)$  be a Riemannian manifold. For a tensor  $T$  let  $\nabla T$  denote its covariant derivative, see Exercise 9.3.  $T$  is called a *parallel tensor* if  $\nabla T = 0$ .

(a) Assume that  $T_1, T_2 : \mathfrak{X} \times \mathfrak{X} \rightarrow C^\infty(M)$  are parallel tensors. Show that the tensor  $T : \mathfrak{X} \times \mathfrak{X} \times \mathfrak{X} \times \mathfrak{X} \rightarrow C^\infty(M)$ , defined as

$$T(X_1, X_2, X_3, X_4) = T_1(X_1, X_2)T_2(X_3, X_4),$$

is also parallel.

(b) Use (a) to show that  $\nabla R' = 0$  for the tensor

$$R'(X, Y, Z, W) = \langle X, W \rangle \langle Y, Z \rangle - \langle X, Z \rangle \langle Y, W \rangle.$$

(c) Use Exercise 4.3 and (b) to show that all manifolds with constant sectional curvature have parallel Riemann curvature tensor

$$R(X, Y, Z, W) := \langle R(X, Y)Z, W \rangle.$$

*Solution:*

(a) We have

$$\begin{aligned} \nabla T(X_1, X_2, X_3, X_4, Y) &= \\ &= Y(T_1(X_1, X_2)T_2(X_3, X_4)) - \sum_{i=1}^4 T(X_1, \dots, \nabla_Y X_i, \dots, X_4) = \\ &= T_1(X_1, X_2) \underbrace{(Y(T_2(X_3, X_4)) - T_2(\nabla_Y X_3) - T_2(\nabla_Y X_4))}_{=\nabla T_2(X_3, X_4, Y)=0} + \\ &\quad + T_2(X_3, X_4) \underbrace{(Y(T_1(X_1, X_2)) - T_1(\nabla_Y X_1) - T_1(\nabla_Y X_2))}_{=\nabla T_1(X_1, X_2, Y)=0} = 0. \end{aligned}$$

(b) Let  $T(X, Y) = \langle X, Y \rangle$ . Since  $\nabla$  is Riemannian, we have

$$\nabla T(X, Y, Z) = Z(\langle X, Y \rangle) - \langle \nabla_Z X, Y \rangle - \langle X, \nabla_Z Y \rangle = 0.$$

Note that  $R'(X, Y, Z, W) = T(X, W)T(Y, Z) - T(X, Z)T(Y, W)$ . Part (a) implies then that we have  $\nabla R' = 0$ .

(c) If  $(M, g)$  is a manifold with constant sectional curvature  $K_0 \in \mathbb{R}$ , we have by Exercise 4.3

$$R(X, Y, Z, W) = \langle R(X, Y)Z, W \rangle = K_0(\langle X, W \rangle \langle Y, Z \rangle - \langle X, Z \rangle \langle Y, W \rangle) = K_0 R'(X, Y, Z, W).$$

Then  $\nabla R = K_0 \nabla R' = 0$  follows from (b).